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#### FINAL REPORT

NASA CONTRACT NO. NAS8-34529

PINHOLE/CORONOGRAPH POINTING CONTROL SYSTEM INTEGRATION AND NOISE REDUCTION ANALYSIS

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Prepared for

National Aeronautics and Space Administration Marshall Space Flight Center Huntsville, Alabama 35812

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Submitted to

National Aeronautics and Space Administration

Marshall Space Flight Center

Huntsville, Alabama 35812

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# TABLE OF CONTENTS

	TITLE .	PAGE NO.
I.	Introduction	1 .
II.	Gimbal (AGS) System	5
	1. AGS Layout	5
	2. AGS Interfacing	9
	3. AGS Noise, Errors and Accuracy	11
	4. AGS Disturbances	14
	5. AGS Limitations	19
III.	Aspect Sensing System	22
	1. LOS Fine Sun Sensor	22
	2. Laser Interferometer	26
	3. Star Tracker	30
IV.	Control System	32
	1. The Plant Model	32
	2. Modal Controller	38
	3. Rigid Body Controller	41
٧.	System Simulations	44
	<ol> <li>Plant (Boom-Mask) Simulation</li></ol>	44
	2. AGS Simulation	45
	3. Control Simulation	45
	4. Disturbance, Noise Simulation	45
VI.	Results	47
	1. Deployment	47 🛴
	2. Thruster Firings	55
	3. Noise	55
זזע	Conclusions	62

# TABLE OF CONTENTS (Cont'd)

		TITLE	PAGE NO.
VIII.	Bib	liography	63
IX.	Арр	endices	
	Α.	Plant Data	65
	В.	Root Locus Plots	71
	c.	Bode Plots	78
	D.	Simulation Programs/Flowcharts	81
	Ε.	Shuttle Drift/Deadband	157
	F.	Simulation Results	167
	G.	LOS Sun Sensor Calculations	325

# LIST OF FIGURES

	TITLE	PAGE NO.
1.	P/OF SYSTEM LAYOUT	3
2.	AGS LAYOUT	6
3.	AGS SOFTWARE/INTERFACING	10
4.	AGS POINTING ERRORS	12
5.	SHUTTLE ACCELERATION PERPENDICULAR TO AGS LOS, ELEVATION GIMBAL/PITCH VRCS DISTURBANCE MODEL	16
6.	SHUTTLE ACCELERATION PERPENDICULAR TO AGS LOS, LATTERAL GIMBAL/ROLL VRCS DISTURBANCE MODEL	17
7.	SHUTTLE ACCELERATION PERPENDICULAR TO AGS LOS	18
8.	AGS ACCELEROMETER MODEL	20
9.	AGS DISTURBANCES	21
0.	LOS SUN SENSOR LAYOUT	24
1.	LOS SUN SENSOR FIELD STOP	25
2.	LASER INTERFEROMETER LAYOUT	29
3.	STAR TRACKER FUNCTIONAL ELEMENTS	-31
4.	P/OF CONTROL SYSTEM	33
5-2	O. BOOM DEPLOYMENT SEQUENCE	49
21.	ROLL DISTURBANCE RESPONSE	56
22.	PITCH DISTURBANCE RESPONSE	57
23.	YAW DISTURBANCE RESPONSE	58
24.	NOISE CHARACTERISTICS	6Ö
25	NOISE CHARACTERISTICS	61

## LIST OF TABLES

	TITLE	PAGE NO.
1.	SYSTEM STATE DEFINITION	4
2.	AGS POINTING ERRORS	13
3.	SHUTTLE VRCS LIMIT CYCLE DISTURBANCES	15
4.	ASPECT SENSING SYSTEM	27
5.	P/OF SCIENTIFIC INSTRUMENTS	36
6.	MOMENTS OF INERTIA	37
7.	RESULTS SUMMARY	48

#### I. Introduction

The Pinhole Occulter Facility (P/OF) is a Space Shuttle based experiment for the production of solar coronographics and hard x-ray images. The system is basically a pinhole camera utilizing a deployable 50-m flexible boom for separating the pinholes and coronograph shields from the recording devices located in the Shuttle bay. At the distal end of the boom from the Shuttle is a 25 kg mask containing pinholes and coronograph shields. At the proximal end the detectors are located and mounted, along with the deployable boom, to the ASPS gimbal pointing system (AGS).

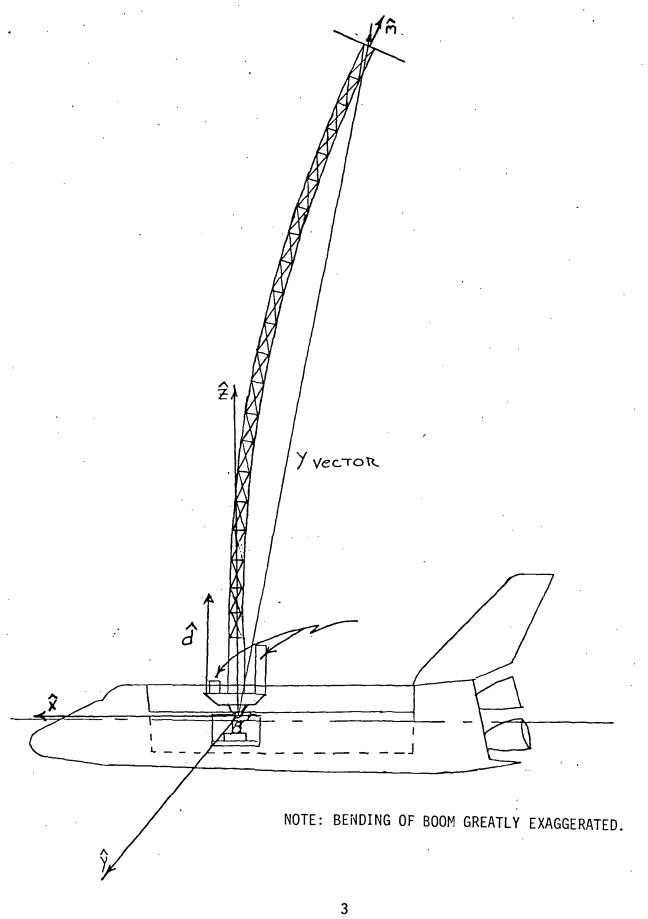
The mask must be pointed at the sun with a high degree of pointing stability and accuracy to align the axes of the detectors with the pinholes and shields. Failure to do so will result in a blurring of the images on the detectors and a loss of resolution. Being a Shuttle based experiment, the system will be subjected to the disturbances of the Shuttle. The worst of these is thruster firing for orbit correction; the Shuttle uses a bang-bang thruster control system to maintain orbit to within preset limits. Other disturbances include man motion, motion induced by other systems, and gravity gradient torques.

The control system of the pointing mount can sense both position of the mask tip relative to the base and pointing error and uses these to accurately estimate the flexible body modes of the system and point the boom. An optimal control/suppression scheme is then used to control the flexible modes. Acceleration feedback is used to point the system. Disturbances are detected by accelerometers in the AGS and are used as negating commands to drive the system and reduce disturbance effects.

An overall layout of the P/OF system is shown in Figure 1. Motions of the boom are measured in the  $\hat{x}$ ,  $\hat{y}$ ,  $\hat{z}$  coordinate system which is centered on the gimbal axes. The AGS is mounted 2.2 m forward and .75 m above the Shuttle cm. The vector y is the total pointing vector of the system; the difference between vector y and the vector command is the total pointing error of the system. The vector  $\hat{d}$  is the pointing of the base of the boom (AGS mounting plate). The vector  $\hat{m}$  is (assuming rigid boom-mask mounting)  $y - \hat{d}$ .

The simulation of this system will be by state space analysis. The boom maintains vibrational states called flexible modes as well as rigid rotational modes. The Shuttle is modeled by rigid rotational and rigid translational modes. The AGS is modeled by use of phase variables and random noise. The sensors are modeled as constant gains with random noise. The states used in this study are defined in Table 1.

FIGURE 1 P/OF SYSTEM LAYOUT



#### TABLE 1

#### SYSTEM STATE DEFINITION

- X<sub>C</sub> CONTROLLED STATES (8 total)
  - These are the states which define the flexible body positions and velocities (modes) of the experiment. They are acted on (or controlled) by the inner loop controller -KX<sub>C</sub>.
- X<sub>R</sub> RIGID BODY STATES (6 total)
  - These are the states which define the rigid body positions and velocities (modes) of the experiment. Physically they represent the angular displacements and velocities of the experiment. They are acted on by the PID controller.
- X<sub>S</sub> SUPPRESSED STATES (8 total)

These states represent additional flexible body positions and velocities (modes) of the experiment. These states are not physically suppressed by the inner loop controller; the design of the inner loop controller is such that its effect on these states is minimized.

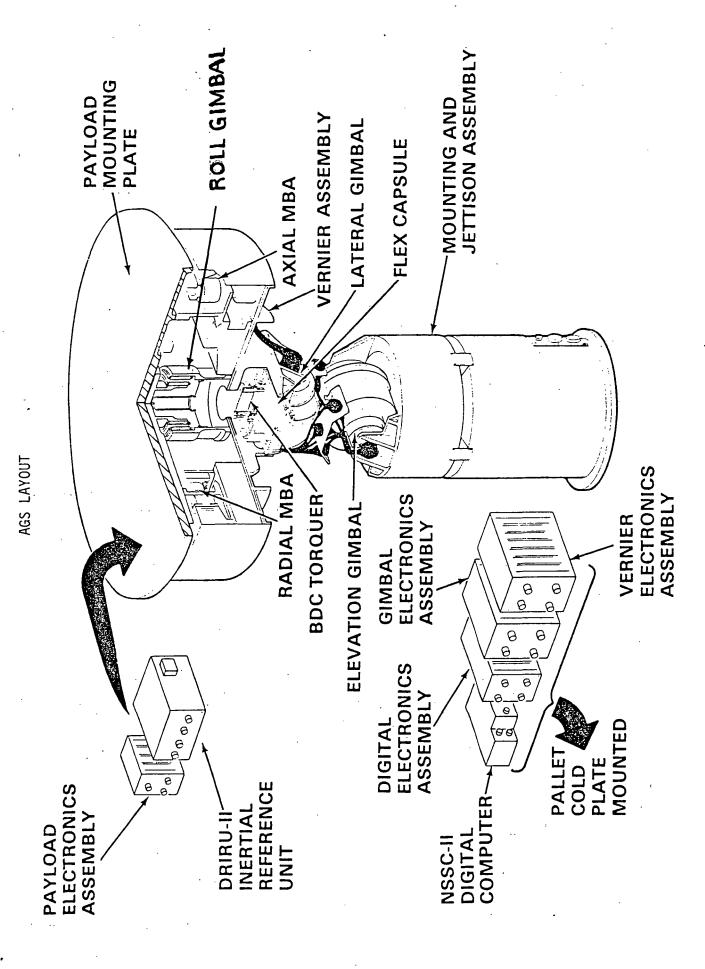
- X<sub>sh</sub> SHUTTLE STATES (12 total)
  - These are the states that define the shuttle orbiter. Physically they are the linear and angular positions and velocities of the Shuttle.
- X<sub>G</sub> AGS STATES (13 total)
  - These states define the modal filters of AGS plus the proportional-integral-derivative (PID) controller.

### II. Gimbal (AGS) System

In the P/OF system, all instruments, boom and mask must be pointed at the sun. All motions of the Shuttle (linear and angular) are angular changes as seen by the instruments. This enables a three dimensional angular pointing mount system to be used. For reduced pointing errors the angular suspension pointing system (ASPS) can be used. The ASPS gimbal pointing system (AGS) was used in this study.

## II.1 AGS Layout

Figure 2 illustrates the layout of the major elements comprising AGS<sup>[1]</sup>Two identical gimbal assemblies are stacked to form an elevation and a lateral gimbal pair. The lower (elevation) gimbal provides an angular range of  $\pm$  100 degrees (from vertical), and the upper (lateral) gimbal provides cross-axis positioning of  $\pm$  60 degrees. The gimbals are mechanically limited by an adjustable stop arrangement to prevent contact with the Shuttle. A Mounting and Jettison Assembly (MJA) is used to connect the gimbal pair with the underlying mounting structure. launch and landing, a separation device within the MJA physically disconnects the mounting base from the AGS gimbals which are independently caged with the experiment to the mounting structure. This approach prevents indeterminant load paths from occurring across the gimbal bearings due to static deflection of the mounting structure and launch or landing environmental loads. The MJA also contains a pyrotechnically actuated jettison system, which provides for total separation (and jettisoning) of the experiment/AGS gimbals in the event of a multiple failure in orbit. An accelerometer unit mounted on the MJA senses orbiter motion for use in a feedforward decoupling control law. [2]



The gimbals are connected to the experiment through a Payload Mounting Structure (PMS) and an Experiment Mounting Structure. The PMS consists of a nominal 1 meter diameter mounting plate and an adapter section which connects with the lateral gimbal. An optional third gimbal to permit rotation about the payload line of sight (roll axis) can be inserted at this location. Since the payload mounting plate is removable, experiment integration can be accomplished independently of the pointing system. Also, the flat end-mount configuration of the mounting plate permits overhanging to accommodate the large POF boom, coronographs and x-ray detectors. [2]

Each of the Coarse Gimbal Assemblies contains a permanent magnet, brushless two-phase dc torquer, a multispeed wound rotor resolver for commutation of the torquer drive signal and a <u>single-speed wound rotor resolver for position readout and control of the gimbal angle</u>. Since both elevation and lateral gimbals have a limited rotational freedom, electrical connections are carried across the rotating gimbals through flex capsules. The flex capsules contain flat flex tapes which are looped between concentric cylinders in the center of each gimbal. Duplex gimbal bearing pairs are used in each gimbal assembly in a fixed/floating cartridge arrangement. The cartridges permit the bearing preload to be set by tolerances within the cartridge itself; dimensional changes which result from temperature variations cause the sliding cartridge to move axially without inducing mechanical stresses or upsetting the bearing preloads. [2]

The AGS inertial sensors will be mounted on the experiment mounting structure for coalignment with the experiment. These <u>sensors include</u> the DRIRU-II (on all missions) and one or more angular error sensors as

discussed in the Sensor Study Section (III). Control and data interfaces with the sensors are provided by a Payload Electronics Assembly (PEA) which is connected to the remainder of the AGS electronics through a multiplexed serial data system. The PEA is a general purpose microprocessor-controlled interface unit which provides a Remote Interface Unit (RIU) compatible serial interface with the position sensors, and a special purpose interface with the DRIRU-II. Experiment control and data is handled by a standard Remote Acquisition Unit (RAU) which connects to the Spacelab Command and Data Measurement System (CDMS). Additional lines are also provided to the experiment for high speed data, control and power. Both the PEA and RAU are located on the payload side of the AGS gimbals. [2]

Primary AGS electronics consist of a Gimbal Electronics Assembly (GEA), Digital Electronics Assembly (DEA) and NASA Standard Spacecraft Computer (NSSC-II), all of which are mounted to a Spacelab cold plate on the same Spacelab pallet as the AGS mechanical hardware. The GEA contains analog electronics for modulation and demodulation of the gimbal angle resolvers and for power drive of the two-phase, brushless dc torquers used to position the gimbals. The interfaces with these electronics are analog, and they are connected directly to A/D and D/A converters within the DEA. A discrete system for driving an independent set of backup coils in the torquers and for determining gimbal position using separate discrete type optical sensors is also provided by the GEA. When connected through hard wiring to a contingency panel in the Orbiter or alternatively to the subsystem CDMS, this system provides a fully redundant backup caging capability for the AGS. The GEA also contains electronics which operate the experiment launch locks and power switching for all of the AGS electronics (sensors, PEA, DEA and NSSC-II). [2]

The DEA is a microprocessor-controlled general purpose interface unit which provides data input and output to the NSSC-II. Interface modules permit serial data transfer to and from the PEA, analog input and output signals to the GEA and Accelerometer Unit, discrete I/O with the GEA, serial I/O with the Spacelab CDMS via a coldplate-mounted RAU and serial output to the Spacelab High Rate Multiplexer (HRM). [2]

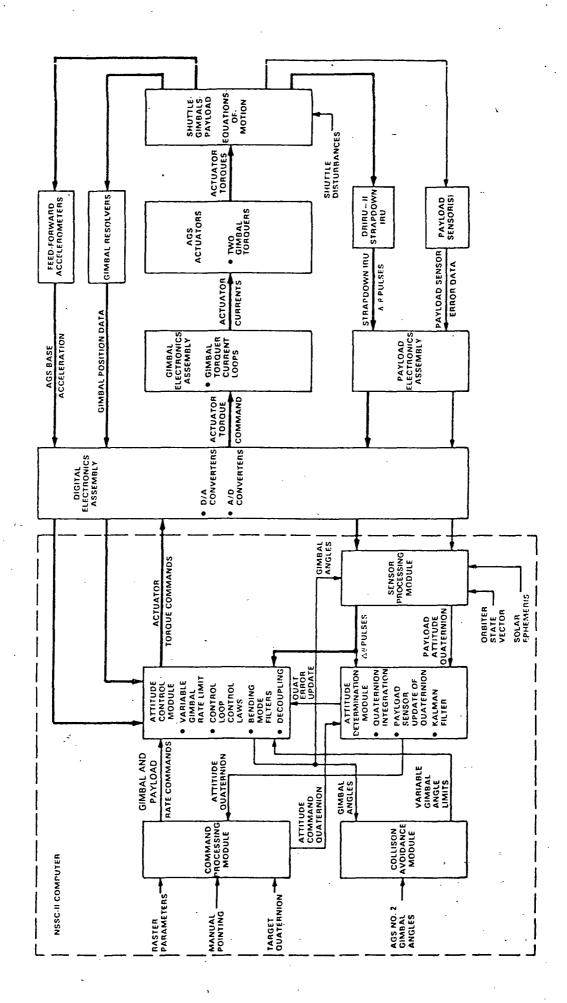
Flight software is organized into functional modules which are relatively independent, as indicated in Figure 3. The Attitude Control Module provides the servo error compensation and torque distribution for the two gimbal control systems and is described first. Two ACS modes are provided on the AGS depending on whether the gimbal resolver or the IRU is used for feedback control of the attitude. These are defined as the Gimbal Pointing ACS Mode and the Payload Pointing ACS Mode, respectively. [2]

Gimbal (resolver) pointing will normally be used only during the initial erection, holding or stowage maneuvers which involve a sequence of individual gimbal axis rotations. All other operations will use the Payload (IRU) Pointing Mode.

#### II.2 AGS Interfacing

The AGS is accessible through the output sensors and Payload Electronic Assembly (PEA) and the NSSC-II computer. These access the regular torquer coils and can be used for rigid body control. Command inputs to the gimbal originate in the NSCC-II which as seen in Figure 4 outputs to the DEA which in turn activates the GEA and the gimbal. [1]

In addition, a separate access is available. This path is through the GEA directly to the two sets of coils in the torquers. This path could be used if multiloop control is necessary such as modal control of AGS SOFTWARE/INTERFACING



-

flexible bodies. For POF, this access appears to be promising.

### II. 3 AGS Noise, Errors and Accuracy

For the purposes of this study all quiescent stability errors and pointing inaccuracies shall be considered as noise. Pointing error defines the total angular error that is allowed by the AGS. Pointing error is the sum of pointing accuracy and pointing stability.

Pointing accuracy defines how close the AGS initially points the experiment line of sight to the desired target. Pointing accuracy applies at the beginning of an experiment observation period following an in-orbit calibration of the alignment errors, maneuverability to the desired target and convergence of the altitude determination system over the specific settling time. Examples of errors that contribute to pointing accuracy are sensor readout errors and thermal distortion occurring after the in-orbit calibration. The numeric values of pointing accuracy are considered to be  $3\sigma$  values (3 standard deviations) to insure probability of target acquisition.

Pointing stability defines how close the AGS stays pointed to the initial point during an experiment. Pointing stability is usually thought of as two conditions: quiescent stability and disturbance response. Quiescent stability is the case where no external disturbances are acting on the AGS or experiment and steady state condition have been reached by the Altitude Control System (ACS). Quiescent stability values are considered as  $l\sigma$ . A pictorial view of these errors is shown in Figure 4. Table 2 contains a summary of the AGS pointing errors. [2]

DISTURBANCE RESPONSE ERROR (PEAK) POINTING ACCURACY POINTING STABILITY POINTING ERROR ENVELOPE TIME --- WITH DISTURBANCES AGS POINTING ERRORS ARGET LINE DESIRED NO DISTURBANCES +--QUIESCENT STABILITY ERROR 125 STEADY STATE OPERATION SLEW AND SETTLING TRANSIENTS TARGET ... T. LOS ANGLE EXPENIMENT FOINTING

FIGURE 4

12

TABLE 2

AGS F	ORBITER		
Quiescent stability (1 <sub>0</sub> )	AGS .2 arc sec	ASPS .01 arc sec	360 arc sec
Pointing accuracy (3 <sub>0</sub> ) payload	.l arc sec	.l arc sec	1080 arc sec

#### II. 4 AGS Disturbances

The Shuttle VRCS limit cycle disturbance is the most significant disturbance input to the AGS ACS. Six thrusters are utilized in the VRCS each having 111.2 N. thrust. These disturbances are modeled as ideal pulses of force of finite duration.

The Shuttle VRCS limit cycle disturbances are summarized in Table 3 for roll, pitch and yaw limit cycles. Also indicated are the axes of the POF boom for each Shuttle limit cycle. The table indicates the thrusters operating, pulse width, Y and Z axis forces and torques applied to the Shuttle for each axis cycle. The Shuttle's angular and translational acceleration due to the limit cycle are also listed. From this table, it can be seen that roll is the most significant limit cycle disturbance.

The effects of a limit cycle disturbance on the POF boom are not those listed in Table 3 but must first be reflected through the gimbal and accelerometer feed forward. A planar model was used for lateral gimbal/roll and elevation gimbal/pitch VRCS disturbances.  $^{[2]}$  Each was developed assuming the other axis was  $^{O}$  away from vertical.

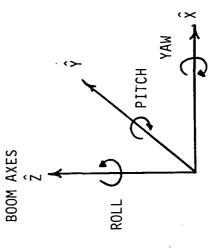
Figure 5 shows the development of the expression for acceleration perpendicular to the AGS line of sight (LOS) for roll. The first of the two equations at the bottom of the figure gives the acceleration as a function of angular and translational accelerations. The second uses the values of Table 3. Figure 6 shows the same development for the elevation gimbal/pitch VRCS limit. The two equations at the bottom of Figure 6 are as above.

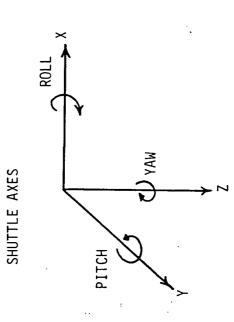
Figure 7 shows the net acceleration perpendicular (A  $_{\perp LOS}$ ) to the LOS in m/sec<sup>2</sup> for both elevation gimbal/pitch and lateral gimbal/roll VRCS

TABLE 3

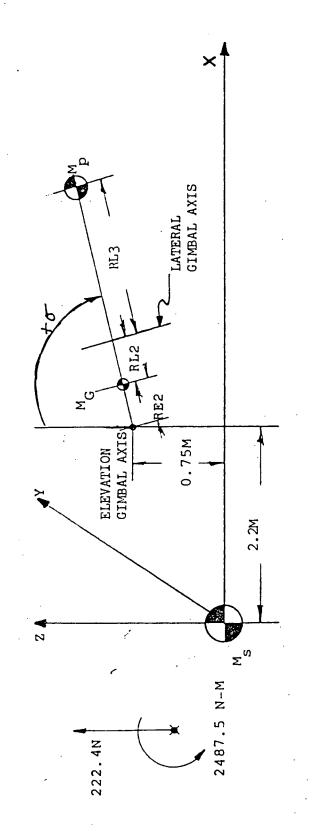
SHUTTLE VRCS LIMIT CYCLE DISTURBANCES [2]

<u> </u>			
.ATIONAL (M/SEC <sup>2</sup> ) ïs	0.002318	0.00263	0.001004
VRCS TRANSLATIONAL ACCELERATION (M/SEC <sup>2</sup> ) Ÿs Żs	-0.002176	0	0.0004518 0.001004
S AR . ATION SEC/SEC <sup>2</sup>	128	09-	09+
VRCS ANGULAR ACCELERATION (DEG/SEC <sup>2</sup> ) SEC/SEC <sup>2</sup>	0.03561	-0.01672	0.01673
VRCS TORQUE (N-M)	682.4	-2487.5	2592.6
F <sub>Z</sub> (N)	196	222.4	84.9
F <sub>Y</sub> (N)	-184	0	38.2
BURN TIME (SEC.)	Ó.20	0.52	0.48
THRUSTERS OPERATING	2, 4, 6	9 ' 9	2, 3
SHUTTLE AXIS	ROLL	РІТСН	YAW
BOOM	YAW	РІТСН	ROLL





SHUTTLE ACCELERATION PERPENDICULAR TO AGS LOS, ELEVATION GIMBAL/PITCH VRCS DISTURBANCE MODEL



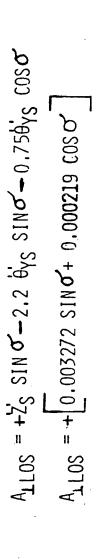
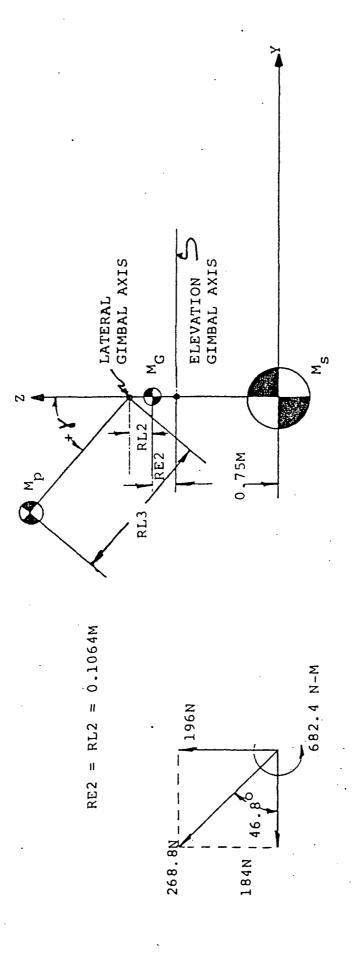


FIGURE 6

SHUTTLE ACCELERATION PERPENDICULAR TO AGS LOS, LATTERAL GIMBAL/ROLL VRCS DISTURBANCE MODEL



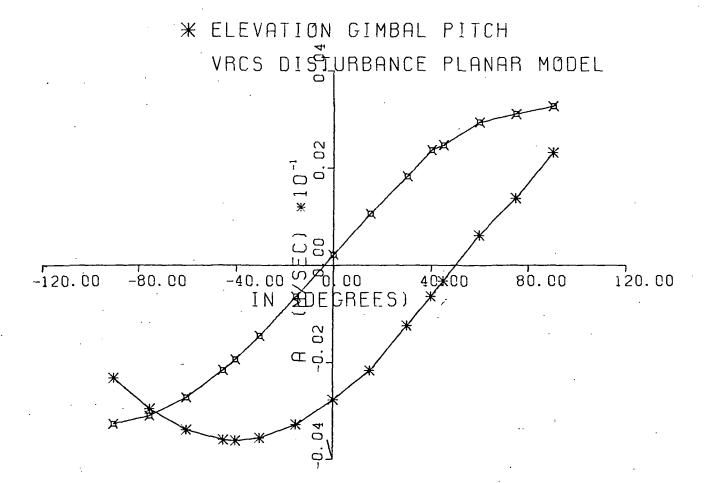
 $A_{LLOS} = +\dot{Y}_{S} \cos 3/4 + \dot{Z}_{S} \sin 3/4 - (0.75 + 0.1064 + 0.1064) \dot{\theta}_{XS} \cos 3/4$ 

 $A_{LLOS} = +0.00231.8 \text{ SIN } 8 -0.002774 \text{ COS } 8$ 

FIGURE 7
SHUTTLE ACCELERATION PERPENDICULAR TO AGS LOS

★ LATERAL GIMBAL & ROLL

 VRCS DISTURBANCE PLANAR MODEL



ELEVATION GIMBAL ANGLE LATERAL GIMBAL ANGLE disturbances resulting from the planar model. For POF boom the  $A_{\perp LOS}$  are those nearest  $0^{\circ}$ . The worst of these disturbances can clearly be seen as a roll VRCS firing resulting in an  $A_{\mid LOS}$  = .0028 m/sec<sup>2</sup>.

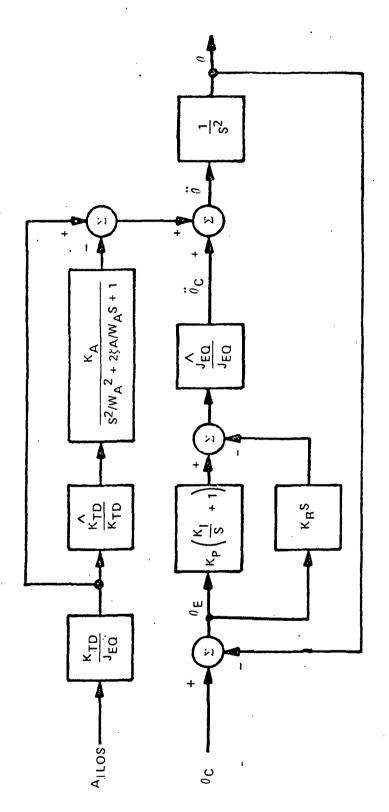
This  $A_{\perp LOS}$  is then reflected to the load as shown in Figure 8. Not only is this disturbance passed forward through the gain conversion from m/sec $^2$  to RAD/sec $^2$  but it is picked up by the accelerometer which tries to negate this signal. Figure 9 shows the resulting angular acceleration disturbances at the base of the POF boom for an accelerometer of 20 Hz bandpass  $K_A$  = 1 and  $\frac{K_{TD}}{J_{EQ}}$  = .05167 RAD/m(roll) and  $\frac{K_{TD}}{J_{EQ}}$  = .05239 RAD/m (pitch). The bandpass of the accelerometer was set at 20 Hz. in this study so that gravity gradients would be decoupled and the effects of thruster firing on the large inertia of the POF system would be minimized. The response of the accelerometer can be modeled as impulses as shown in Figure 9.

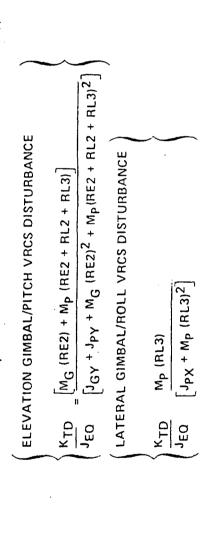
## II. 5 AGS Limitations

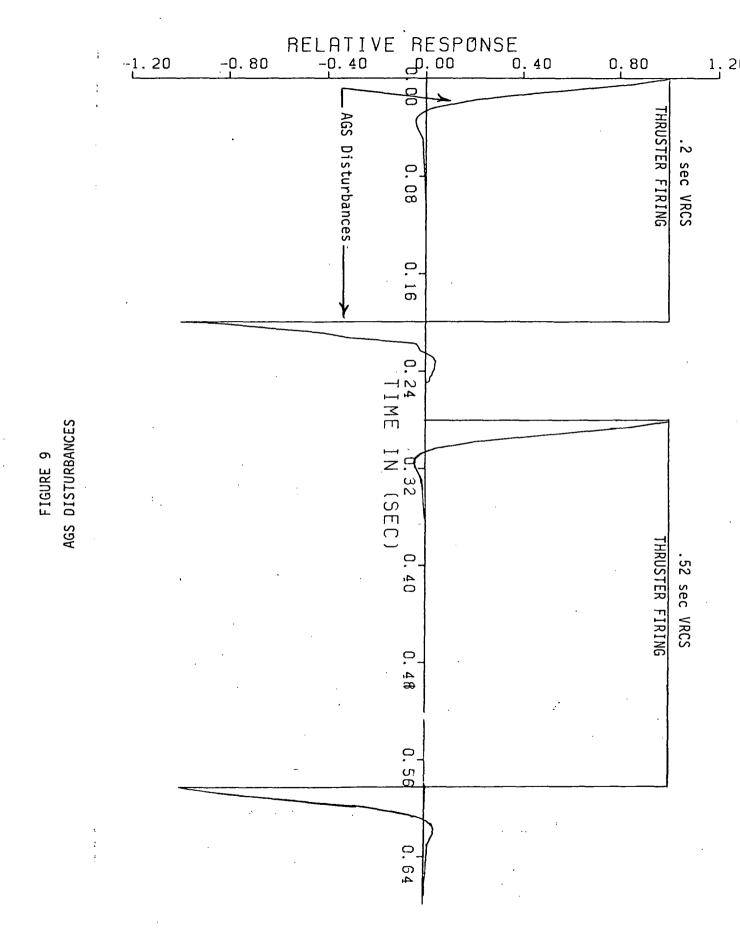
The chief limitation to the AGS is the total available torque per gimbal axis of 33.9 NT-MT<sup>[2]</sup>. If this torque limit is not adequate for both rigid body pointing and active mode damping the future development of larger AGS torquers<sup>[1]</sup> may be required. In addition the AGS pointing accuracy of 1/arc sec  $(3\sigma)$  may not be adequate.

FIGURE 8

AGS ACCELEROMETER MODEL







### III. Aspect Sensing System

The Aspect Sensing System (ASS) for P/OF must yield fine measurements of: 1. modal vibrations about each of the three boom coordinate axis, and 2. rigid body rotations about each boom axis. In addition, coarse measurements must be available for deployment and target acquisition. This report will deal only with fine measurements.

The following system is proposed: A fine LOS sun sensor, a laser interferometer and a star tracker. The fine LOS sun sensors would yield a combination of the error in rigid body rotations plus modal vibrations about boom pitch and yaw. This sensor could not detect boom roll.

The laser interferometers would detect the relative angles between the boom base and tip. These angles are the result of modal vibrations. The flexible body modes can be estimated from these measurements. The output of the interferometer system subtracted from the fine LOS sun sensor would yield the error in rigid body rotations.

The star tracker would be used to measure rigid body boom roll. From the star tracker, error in rigid body roll can be obtained.

### III. 1 LOS Fine Sun Sensor

A configuration which allows the sun sensor to view the sun through a small window in the mask is shown in Figure 11<sup>[4]</sup>. The required four sectors of the solar limb are viewed through the window by four pentaprisms, each of which relays the view to a corresponding pentaprism located over the sun sensor objective lens. (Only two pairs of the four pairs of pentaprisms are shown in this figure). Pentaprisms are used here for their constant deviation characteristic, which simplifies the alignment and mechanical stability requirements. The angular deviation of a ray by a pentaprism in a plane mutually perpendicular to entrance and exit faces

is a constant, regardless of minor tilts and misalignments of the prism itself. Pentaprisms are commonly made with deviation angles equal to  $90^{\circ}$ ,  $\pm 1$  arc second. The purpose of the bandpass filter over the window in the occulter is to prevent radiation passing through the window in the occulter from raising the stray light levels in the White Light Coronagraph. The nominal bandpass of this filter is 8250 Å to 8750 Å. A similar filter is placed over the objective lens of the sun sensor to decrease the effects of stray light on the aspect signals from this sensor.

The spacing between the outer pentaprisms will be approximately equal to the boom length times the angular diameter of the sun. Thus, it would be 46.5 cm for a 50 meter boom. Nominal apertures for the window, the pentaprisms, and the objective lens are 5 cm, 2.5 cm, and 8.0 cm, respectively.

The four sectors of the limb are imaged onto the field stop by the objective lens, as shown in Figures 10 and 11. The field stop contains four cross-shaped cutouts, behind each of which is a separate detector. Nominally, the image of the solar limb will lie along the centerline of those arms of each cross which are tangent to the limb when the sensor is pointed at the center of the sun, as shown.

Initially, the signal rises slowly from zero as the image of the solar disk fills more and more of the inner radial arm of the cross of Figure 11. Then, the slope of the curve suddenly increases as the image begins to fill the tangential arms of the cross, with the signal equal to  $S_{\mathbb{C}}$  when the image of the limb lies at an angular position  $\theta_{\mathbb{C}}$  along the centerline of the cross. Finally, the slope decreases again as the image begins to fill the outer radial arm of the cross. The purpose of the radial arms, of course, is to increase the angular dynamic

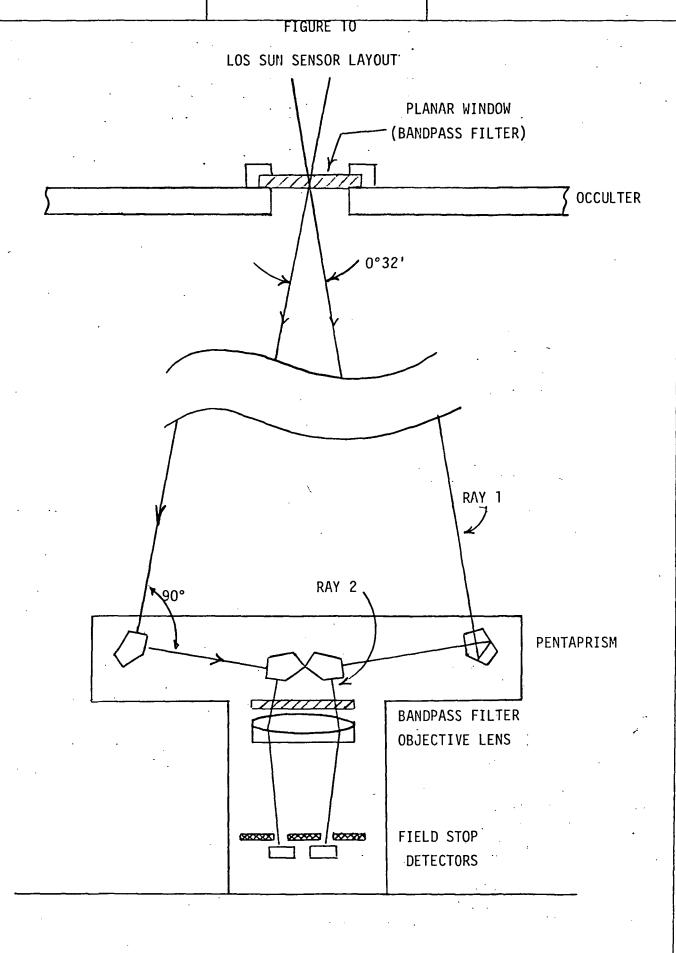
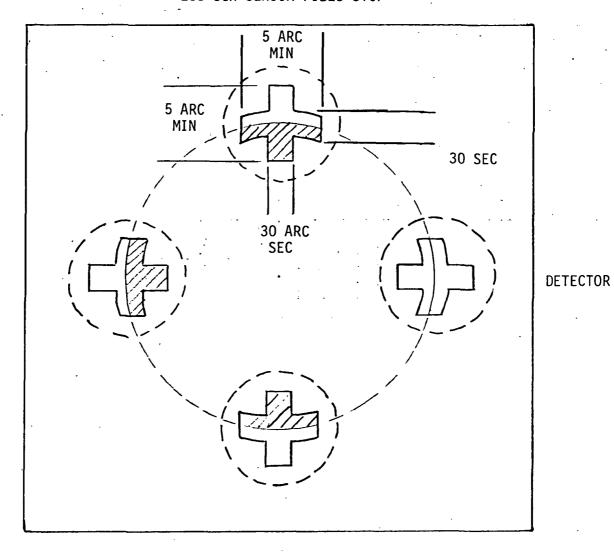
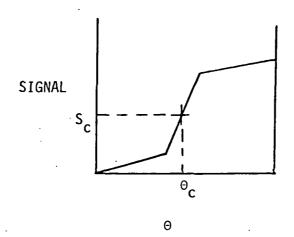


FIGURE 11

# LOS SUN SENSOR FIELD STOP





range of the sensor. The purpose of the tangential arms is to increase the slope of the error signals when the sensor approaches the orientation at which it is centered on the sun.

Typical dimensions for the cross-shaped cutouts are shown in Figure 11. The arms are 30 arc seconds wide and a total of 5 arc minutes long, giving a total angular area of 4.75 square arc minutes for each cross. When nominally centered on the sun, one half the area or 3.38 sq. min. of a cross will be filled with radiation from the solar disk. Then, a change in the angular orientation 0 of 5 arc seconds corresponds to change in illuminated area in the cross of .42 sq. arc min., or to an 18% change in signal level. Similarly, a change in 0 of 0.3 arc seconds results in a signal change of 1.1%. Signal changes of these amounts should be readily detectable, and should also be large compared to the shifts in sensitivity of most stable types of detectors which might be used here. Even a change in 0 of 0.05 arc seconds corresponds to a readily detectable signal change of 0.18%. Table 4 summarizes the characteristics of the proposed LOS fine sun sensor as well as the other components of the ASS.

## III.2. <u>Laser Interferometer</u>

The laser interferometer measures the six coordinates necessary to know the position of the mask (boom tip) relative to its base. A preliminary configuration for this system is shown in Figure  $12^{\left[5\right]}$ . One laser with beam splitters provides the source of all six measurements. In Figure 13, beam splitter would be located at A, D, P and Q, and detectors at B, R, S, D and A. Interferometers are located along with each detector. The six differences in distance are measured then  $(q_1-q_6)$ . With these measurements, the relative positions and orientations of the mask are

TABLE 4

ASPECT SENSING SYSTEM					
INSTRUMENT	LOS SUN SENSOR	LASER INTERFEROMETER	STAR * TRACKER		
MEASURES RIGID BODY PITCH, YAW		MODAL VIBRATIONS	RIGID BODY ROLL		
RESOLUTION	.05 ARC SEC	.01 ARC SEC	.6 ARC SEC		
S/N	1000	2 x 10 <sup>6</sup>	3000		
ACCURACY	±.0025 ARC SEC	±.005 ARC SEC	±.3 ARC SEC		
WEIGHT	1.4 kg	22 kg	35.4 kg		
ERROR IN ΔΧ,ΔΥ		.005 mm			

<sup>\*</sup> For a 10 inch tracker

given by

$$D_{x} = 1 q_{1}/d$$

$$D_{y} = 1 q_{2}/d$$

$$D_{z} = D(q^{2} + d^{2})^{\frac{1}{2}}$$

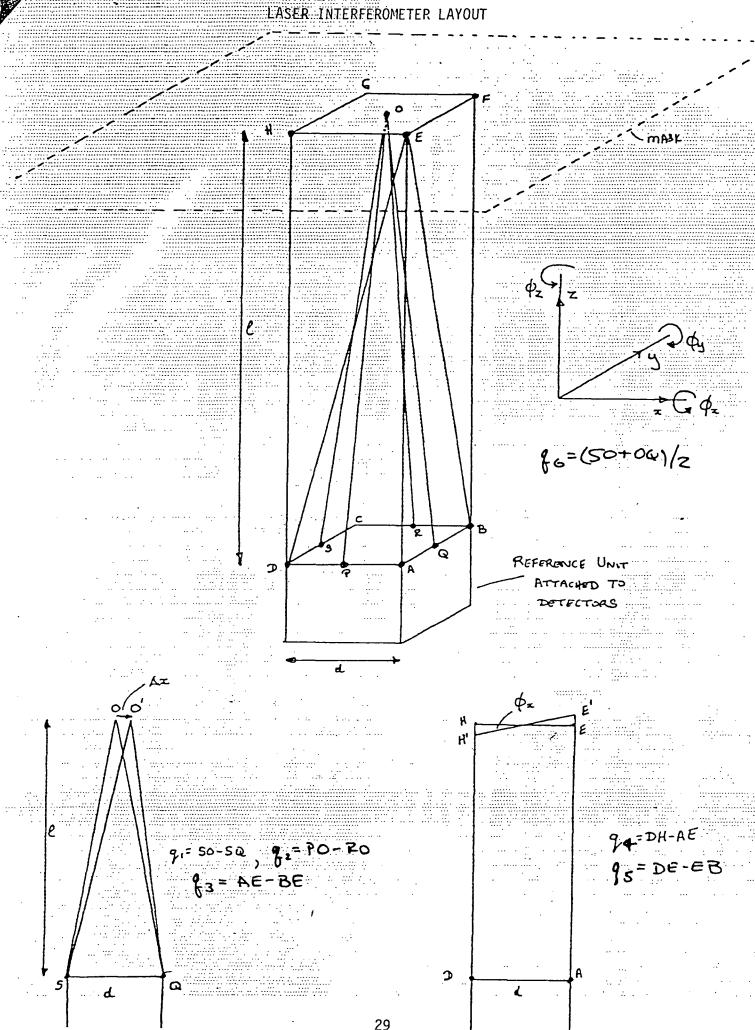
$$\Phi_{x} = q_{3}d$$

$$\Phi_{y} = q_{4}/d$$

$$\Phi_{z} = 1 q_{6}/d^{2}$$

These motions (q's) can be measured with a .lµm typical accuracy  $^{[6]}$ . Resolution can be extended electronically down to .0016 µm with conventional interferometers  $^{[7]}$ . This corresponds to .0003 arc sec for a 50 m boom.

In addition, AC Laser Interferometers (ACLI) have high repeatability and high accuracy [6,7]. Accuracies of .5 parts per million are routine. Long range optical paths are also typically in use (60 m). The Hewlitt-Packard HP 5526 A has a range of 60 m and accuracies as stated above. In addition, ACLI's can have bandwidths as high as 10Hz allowing for the measurement of modal vibrations. Table 4 summarizes the characteristics of proposed ACLI's as well as the other components of the ASS.



#### III.3. Star Tracker

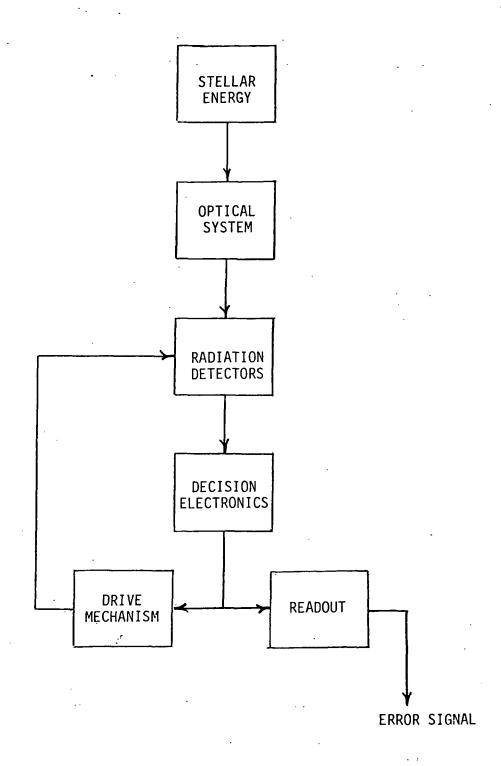
The star tracker is used to measure rigid body rotations about the longitudinal axis (roll) of the boom. An additional measurement of the rigid rotations, as measured by the LOS fine sun sensor, is possible. If targets other than the sun are studied, the star tracker would be the only source of the measurement of rigid body rotations.

The basic functional elements of a star tracker and scanner are shown in Figure 13. The optical system collects and focuses collimated energy from a star and transmits it to the detector. The major optical design consideration are aperture size, angular field of view, optical resolution, aberration, distortion and spectral transmissive efficiency. [8] The three types of optical systems generally employed are reflecting, refracting and hybrid.

The radiation detectors are usually photomultipliers, vicicons or photodiode arrays and the decision electronics are generally integrators over a fixed period which increases the signal to noise (S/N) ratio. The noise effect, which appears primarily as random shot noise at the detector output, is minimized by extending the integrative time for star error signals. [9] This, in practice, means a reduction of the tracker bandwidth to below 1 HZ.

The drive mechanisms in the cases of the photodiode array or vidicon are electronic signals used to scan the detector and there are no moving parts in the tracker itself. The electronic outputs are error signals in tracking about the axes under study. These signals can be used to drive the rigid body system error to zero. A summary of the star trackers characteristics [10] as well as other components of the ASS are shown in Table 4.

FIGURE 13
STAR TRACKER FUNCTIONAL ELEMENTS



### IV. Control System

The Control System of the P/OF uses the gimbals of Section I as actuators and the sensors of Section II. The plant to be controlled is described in Section IV.1. The control laws are described in detail in Section IV.2 and IV.3.

The Control System consists of two control loops as shown in Figure 14. The inner loop is a modal controller whose function is to actively add damping to the flexible boom. This is accomplished by measuring the modes of the system at the boom tip (mask), adding phase to them and actuating the base with this signal. The resulting vibrations tend to cancel those vibrations present in the boom and it appears that the damping of the boom is much greater than in actuality. The main benefit of this method is the insensitivity of the controller to the actual damping factor [11] of the plant model.

The outer loop controller of Figure 14 is the rigid body controller that actually points the boom as if it were rigid. This controller affects the modal controller only minimally and sets the bandpass of the system. This system tracks the target using the Proportional-Integral-Derivative (PID) controller of the AGS as well as other components of the AGS controller. Noise reduction is accomplished by severely limiting the overall bandpass of the system.

# IV.1 The Plant Model

The model of the plant has been detailed extensively [12,13,14]. These models will be reviewed and extended as required. The boom is, modeled as a flexible + rigid body. These are the first three sets of states of Table 1. The equations of motion are then,

MODEL Noise SENSOR Š Xe = ARXe+ Bei X= Axx+ 850 xc= Ac x+ RU CONTROL 84 3/3 MODAL 50. 52+ 145 +49 MODAL ACCELEROMETER (5/21/2+ 1/2/2) AGS NOISE MODEL PID CONTR 14, (5+05+8)

P/OF CONTROL SYSTEM

where  $\ddot{U}$  is the 3 x 1 rotational acceleration matrix at the base of the boom and

$$\begin{bmatrix} Y_{C} \\ Y_{S} \\ Y_{R} \end{bmatrix} = \begin{bmatrix} C_{C} & 0 & 0 \\ 0 & C_{S} & 0 \\ 0 & 0 & C_{B} \end{bmatrix} \begin{bmatrix} X_{C} \\ X_{S} \\ X_{R} \end{bmatrix}$$
(2)

$$Y = Y_C + Y_S + Y_R \tag{3}$$

where  $Y_C$  is the tip deflection due to the controlled modes,  $Y_S$  the tip deflection due to the suppressed modes and  $Y_R$  the tip deflection due to the rigid modes. Note that  $Y_R$  is also the deflection of the base of the boom and Y is the total tip deflection.

The flexible body modes (natural frequencies) are functions of boom length, width, mass and tip mass  $^{[12,15]}$ . The first eight (8) modes were used in this study and resulted from a 50 meter x l meter boom with a 25 kg tip mass. These boom frequencies and shapes are summarized in Table A-1 of Appendix A. The damping factor for the boom appears to be in the 1-2% region  $^{[15]}$  as measured by the SEPS boom test.

Using these data, the resultant  $A_C$  and  $A_S$  matrices can be derived and are listed in Appendix A. The rigid body motions are simply double integrations of base accelerations and result in the  $A_R$  matrix of Appendix A. The input  $(B_C, B_S)$  and output  $(C_C, C_S)$  matrices for the flexible modes were derived from NASTRAN analysis [12,14] and are also

listed in Appendix A. The input  $(B_r)$  and output  $(C_R)$  matrices for the rigid modes are ones and zeros which simply reflect the double integration [14]. These matrices are also shown in Appendix A.

Equations (1), (2) and (3) completely describe the motion of the tip and base of boom due to accelerations at the base. These equations do not however describe the effects that the actuator has on the system. These equations are discussed in Section IV.3.

The scientific instruments to be used [16,17,18] are summarized in Table 5 along with their respective masses, sizes and mounting locations. The instruments consist of two (2) coronographs – one ultraviolet and one white light, and two x-ray detectors on x-y tables. In addition to these instruments, the LOS fine sun sensor, laser interferometers and star tracker of Table 4 must also be mounted on the AGS mounting plate along with the boom deployment canister.

Since the torque capabilities of the AGS actuator are limited to 33.9 NT-m (see Section II) a knowledge of the moments of inertia about each of the gimbal axes is necessary. The moments of inertia are a result not only of the boom-mask but also of the scientific instruments loaded onto the AGS platform as well as the other gimbal drives and mechanisms mounted above the axis under consideration. The moments of inertia about each boom axis are listed in Table 6 for the boom perpendicular to the mounting platform. The torque required if the system was totally rigid would be the total angular acceleration about each gimbal axis times the moment of inertia about that axis. Since the system is not rigid but flexible, the total required torque has an upper bound of the torque calculated assuming a rigid body.

TABLE .5

·S(	CIENTIFIC	INSTRUMENTS			
Instrument	Weight (kg)	Size (m)	Cen X	ter of M Y	lass Z
U.V. Coronograph	180	1.5x1.5x6	1.75	1.75	2
White Light Coronograph	80	.6Dx2	1.3	1.3	1
X-ray Detector 1	100	lxlx.5	1.5	1.5	.25
X-ray Detector 2	100	1x1x.5	1.5	1.5	.25

<sup>\* (0,0,0)</sup> is located in the center of the mounting plate, top surface.

<sup>&</sup>lt;sup>†</sup> Movable X-Y table allows the cm to be changed in X & Y. These figures are for the detector abutting the boom deployment canister.

TABLE 6

	MOMENTS OF INERTIA														
AX	IS	J <sub>P</sub> (1)	M <sub>p</sub> (2)	(3) r <sub>p</sub>	(4)										
воом	SHUTTLE	J <sub>P</sub> (KG-m <sup>2</sup> )	(KG)	(m)	JEQ										
Х	Х	57230 <sup>*</sup>	685	6.5	86,171										
Υ	-Y	57230 <sup>*</sup>	1013**	6.7	88,429										
Z	-Z	4250	685	2.6	8,880										

<sup>\*</sup> From Nastran Analysis [14].

- (1)  $J_p \triangleq Moment of inertia of the payload about its own center of mass (C.M.)$
- (2)  $M_p$   $\underline{\Delta}$  Mass of the payload
- (3)  $r_p \triangleq Location of the payload C.M. relative to the gimbal axis$
- (4)  $J_{EQ} \triangleq Total inertia about each gimbal axis = <math>J_p + J_G + M_p r_p^2$

<sup>\*\*</sup>Includes 328 kg for the X and Z gimbal assemblies.

# IV.2 Modal Controller

The partioning of the state vectors in Equation 1 reflects the objectives of the modal control system design. The controlled states,  $\mathbf{x}_{c}$ , must be controlled to achieve satisfactory system damping off line while the suppressed states,  $\mathbf{x}_{s}$ , are known but not critical to the control design<sup>[19,20]</sup>.

What we would like to do is effect changes in  $x_c$  and no changes in either  $x_s$  or  $x_R$ . The effect of the controller on the rigid modes or suppressed modes is called control spillover. We wish on one hand to optimize the system for the controlled states and limit the control spillover: the controlled states are actively damped while the suppressed states are not excited by the controller and the rigid states are unaffected by it.

We have an optimum controller

$$\ddot{u}^0 = - Kx_c \tag{4}$$

determined by using an index of performance

$$PI = \int_{0}^{\infty} (x_{c}^{T} Q_{c} x_{c} + \ddot{u}^{T} R_{c} \ddot{u}) dt .$$
 (5)

which results in the modified plant equations:

$$\begin{bmatrix} x_{c} \\ x_{s} \\ x_{R} \end{bmatrix} = \begin{bmatrix} A_{c} - B_{c}K, & 0, & 0 \\ - B_{s}K, & A_{s}, & 0 \\ - B_{R}K, & 0, & A_{R} \end{bmatrix} \cdot \begin{bmatrix} x_{c} \\ x_{s} \\ x_{R} \end{bmatrix}$$
(6)

Clearly, we would like to have for no control spillover:

$$B_{1}K = \begin{bmatrix} B_{s} \\ B_{R} \end{bmatrix} \qquad K = 0 , \qquad (7)$$

which merely implies the orthogonality of  $B_1$  and K.

By modifying the performance index to include spillover terms  $(B_1\ddot{u})$  we can simultaneously minimize the PI and the product  $B_1K$ . Including these spillover terms in the PI, we have:

$$PI = \int_{0}^{\infty} [x_{c}^{T} Q_{c} x_{c} + \ddot{u}^{T} R_{c} \ddot{u} + (B_{1}u)^{T} R_{s} (B_{1} \ddot{u})] dt$$
 (8)

$$= o^{\int_{0}^{\infty} [x_{c}^{T} Q_{c} x_{c} + \ddot{u}^{T} (R_{c} + B_{1}^{T} R_{s} B_{1}) \ddot{u}] dt.$$
 (9)

Now by heavily penalizing the PI to suppressed state spillover ( $R_S^{>>>}R_c$ ), we can force the maximization of the orthogonality of  $B_1$  and K. The feedback coefficient matrix can now be solved from the familiar matrix riccati<sup>[14]</sup>.

The control spillover into the rigid body states cannot be avoided, but represents only steady state following errors. These errors can be removed by the proper selection of controller gains for command inputs and rigid body feedback. The design of a rigid body controller is detailed in Section IV.3.

The output of the modal controller (Equation 4) can be added to the output of the AGS feedforward accelerometor (see Figure 14) and the AGS driven by the resultant signal via the DEA-GEA. The modes themselves must first be measured. This represents a more difficult task.

Due to the nature of the system (the forms of the matrices  $C_c$  and  $C_s$ ) an observer for the first eight modes which does not have signal present from the suppressed modes could not be designed. This observation spill-over could cause serious stability problems [19,20]. Two promising techniques are available, however. The first technique is to bandlimit the sensors detecting the modal vibrations and construct an optimal controller

which is unaffected by the filter but yet does not undo the filter's effects. [21] Another technique is to use a comb filter which is phase-locked to the modal frequencies and "combs" out the individual components. [22] The relative components are then readily determined. The value of the second approach is that the comb filters can be realized in hardware which may now be less expensive than software. [23]

The modal controller is strictly an active damping system. The original eigenvalves for the controller states were for 2% damping:

$$\lambda_{1,2} = \lambda_{3,4} = .0217 \pm j \ 1.086$$
 RAD/SEC  
 $\lambda_{5,6} = \lambda_{7,8} = .150 \pm j \ 7.50$  RAD/SEC.

While the eigenvalves for the controlled states under the effects of the modal controller are:

$$\lambda_{1,2} = \lambda_{3,4} = 1.3785 + j 1.0894$$
 RAD/SEC  $\lambda_{5,6} = \lambda_{7,8} = 1.2508 + j 7.4484$  RAD/SEC .

The effective damping ratio for the first four eigenvalves was increased from 2% to 126.5% and the effective damping ratio for the second four controlled eigenvalves increased from 2% to 16%. This yields time constants (the inverse of real part of the eigenvalves) for all modes on the boom of under 1 sec.

# IV.3. Rigid Body Controller

The rigid body controller consists of the outer loop of Figure 14.

This loop is comprised of the PID controller and modal filters of the AGS, the plant, sensors with noise and unity feedback. Only the rigid body modes (with modal spillover) are detected (as discussed in Section III) and fedback with this controller.

The philosophy of design of this controller was to bandpass limit the system to reduce noise but not to significantly affect the pole placement resulting from the modal controller. The AGS has two areas for design: the PID controller and the modal filter. The gains for the PID controller were chosen for optimal tracking [24] and were:

$$G_{PIDX} = \frac{K_{\chi}(s^2 + 2.02s + 2.08)}{s}$$

$$G_{PIDY} = \frac{K_{\gamma}(s^2 + 4.116s + 3.62)}{s}$$

$$G_{PIDZ} = \frac{K_{\zeta}(0.s^2 + 0.s + 1)}{s}$$
(10)

The PID controller gains determine the placement of zeros of the system. The gains selected resulted in zeros being placed close to but not canceling the poles of the first two modes. With the rigid loop closed, the modal roots cannot migrate significantly for the first two modes.

The remainder of the rigid body controller was designed using root locus techniques. For this technique the transfer functions must be known. The plant equations are [14]:

$$Y_{c}(s) = C_{c} \Phi_{o} B_{c} (s^{2} \theta_{G}(s))$$

$$= s \begin{bmatrix} \frac{2.668}{s^{2} + 2.69s + 2.99} + \frac{.267}{s^{2} + 2.05s + 56.3}, & 0 \\ 0 & , \frac{-1.092}{s^{2} + 2.69s + 2.99} + \frac{.108}{s^{2} + 2.05s + 56.3}, & 0 \\ 0 & , & 0 \end{bmatrix} (s^{2}\theta_{G}(s)), (11)$$

$$\gamma_{s}(s) = C_{s} \Phi_{s} B_{s} [I_{3} - K\Phi_{o} B_{c}] (s^{2} \theta_{G}(s))$$

$$= s \begin{bmatrix} .05s^{4} + .052s^{3} + 2.521s^{2} - .1074s + 2.83 & , & 0 & , & 0 \\ 0 & , .03s^{4} + .028s^{3} + 1.505s^{2} - .232s + 1.695 & , & 0 \\ 0 & , & 0 & & , & 0 \end{bmatrix} (s^{2}\theta_{G}(s)), (12)$$

$$= (s^{2} + 2.69s + 2.99) (s^{2} + 2.05s + 56.3)(s^{2} + 2.2s + 475.9)$$

and.

$$Y_{R}(s) = C_{R} \Phi_{R} B_{R} [I - K\Phi_{O} B_{c}] (s^{2} \theta_{G}(s))$$

$$= \frac{1}{s^{2}} \begin{bmatrix} s^{4}+1.04s^{3}+50.39s^{2}-1.94s+56.39 & 0 & , & 0 \\ 0 & , & s^{4}+.94s^{3}+50.18s^{2}-7.5s+56.39 & , & 0 \\ 0 & , & 0 & , & 0 \end{bmatrix} (s^{2}\theta_{G}(s)), (13)$$

$$= \frac{1}{(s^{2}+2.69s+2.99)} (s^{2}+2.05s+56.3)$$

The overall gimbal transfer function is

$$G_{G} = \frac{s^{2}\theta_{G}}{\theta_{F}} = G_{PID} \cdot G_{M}$$
 (14)

where  $\boldsymbol{G}_{\boldsymbol{M}}$  is the modal filter transfer function.

The modal filters were chosen for X and Y to be:

$$G_{M} = \frac{s^{2}(s^{2}+2s+401)}{(s^{2}+8s+16)(s^{2}+40s+400)}$$

$$= (\frac{s}{s+4})^{2} \frac{s^{2}+2s+401}{(s^{2}+20)^{2}}$$
(15)

The first term represents a bandpass limited differentiator so that the rigid body system is type 1. The second term prevents the migration of the suppressed modes to the right half s-plane and prevents instability.

The root locus plots for the rigid body controller are shown in Appendix B. Plots are shown for the controlled and suppressed modes for X and Y and the rigid modes for  $\hat{X}$ ,  $\hat{Y}$  and  $\hat{Z}$ . The Bode plots for the rigid body modes are shown in Appendix C for  $\hat{X}$ ,  $\hat{Y}$  and  $\hat{Z}$ .

# V. System Simulations

The system was simulated using a Univac <code>]100/digital</code> computer. All equations of motion were first order state variable notation equations and were integrated using the fourth order Runge-Kutta numerical integrator of Appendix D. Integration stepsize was varied between <code>.01 sec/step and .1 sec/step</code>.

The computer programs which simulate the system along with their respective flow charts are listed in Appendix D. All the plant/control equations are computed in subroutine FUNC. The subroutine RKSUB is the Runge-Kutta integrator. The main program handles the input-output and timing. All data related to the simulation is in Appendix A.

# V.1. Plant (Boom-Mask) Simulation

The plant was simulated using the model of section IV.1. Equations (1)-(3) of section IV.1 are repeated below. The first order state variable equations are:

$$\begin{bmatrix} \dot{x}_{c} \\ \dot{x}_{s} \\ \dot{x}_{R} \end{bmatrix} = \begin{bmatrix} A_{c} & 0 & 0 \\ 0 & A_{s} & 0 \\ 0 & 0 & A_{R} \end{bmatrix} \begin{bmatrix} x_{c} \\ x_{s} \\ x_{R} \end{bmatrix} + \begin{bmatrix} B_{c} \\ B_{s} \\ B_{R} \end{bmatrix} \begin{bmatrix} \ddot{u} \\ \ddot{u} \end{bmatrix}$$
(1)

$$\begin{bmatrix} Y_{C} \\ Y_{S} \\ Y_{R} \end{bmatrix} = \begin{bmatrix} C_{S} & 0 & 0 \\ 0 & C_{S} & 0 \\ 0 & 0 & C_{R} \end{bmatrix} X_{C} \\ X_{S} \\ X_{R} \end{bmatrix}, \qquad (2)$$

and

$$Y = Y_C + Y_S + Y_R \tag{3}$$

where  $Y_R$  is the rigid body deflection (both base and tip),  $Y_c$  the tip

deflection due to the controlled modes ( $X_c$ ) and  $Y_s$  the tip deflection due to the suppressed modes ( $X_s$ ).

## V.2. AGS Simulation

The AGS was simulated using the frequency response equations of Section IV.3. These equations were transformed into the time domain using phase variables and resulted in the following state equations.

$$\dot{X}_{G} = A_{MAT} X_{G} + B_{G}^{\theta} F \tag{16}$$

where the  $X_{\bar{G}}$ 's are the AGS states and

$$\ddot{\theta}_{E} = \ddot{R}_{com} - \ddot{Y}_{R} . \tag{17}$$

The matrices  $\mathbf{A}_{\mathrm{MAT}}$  and  $\mathbf{B}_{\mathrm{G}}$  are listed in Appendix A.

#### V.3. Control Simulation

The P/OF control system is a two loop controller (as seen in Figure 14). The driving functions for the plant (Boom-Mask) is the 3xl Ü vector. This vector is the sum of modal control + noise, the output of the AGS + the disturbances + noise (see Section IV.4). The control law is, neglecting the additive noises and disturbances

$$\ddot{U} = -KX_{c} + C_{G}X_{G}$$
 (18)

where the  $X_{C}$ 's are driven by the  $\theta_{E}$  of Equation (17).

# V.4 Disturbance, Noise Simulation

The disturbance model used was the AGS VRCS disturbance model of Section II.4. Both man-motion and thruster firing result in doublet impulses being impressed on the boom base (see Section II.4). The disturbances,  $\ddot{\theta}_D$ , are additive to the control equation (18) resulting in the

following modified  $\ddot{U}$ :

$$\ddot{U} = -KX_C + C_GX_G + \ddot{\theta}_D. \qquad (19)$$

The noise was modeled as a random stationary process of mean zero. The standard deviation of each noise ( $N_1$  -  $N_4$  of Figure 14) was determined as follows.  $N_3$  and  $N_4$ , the sensor noise, has the standard deviation of Table 4 ( $\pm$  ½ resolution) while  $N_1$  is the pointing accuracy of the AGS and  $N_2$  is the quiescent pointing stability of the AGS.  $N_1$ ,  $N_2$ ,  $N_3$  and  $N_4$  are all 3x1 vectors.

These noise vectors further modify the control law of Equations (18) and (19) yielding

$$\ddot{U} = -K(X_C + N_3) + C_G X_G + \theta_D + N_1 + N_2$$
 (20)

while the forcing function for the AGS controller of Equation (17) becomes

$$\ddot{\theta}_{E} = \ddot{R}_{com} - \ddot{Y}_{R} + N_{4} \tag{21}$$

#### VI. Results

The flight of the P/OF can be considered to be in three phases: deployment, noise/drifting, and response to VRCS thruster firings. The feedforward accelerometer decouples the shuttle gravity gradient (G.G.) accelerations from the boom and no estimate of the boom G.G. rates are attempted. The boom G.G. rates should be an order of magnitude less than the shuttle rates and the results of earlier studies demonstrated the ability of the P/OF to follow even the shuttle G.G. rates [14,24].

The shuttle drifting simulation results are shown in Appendix E for three deadbands: 1°, 2° and 5°. For a 1° deadband the mean period between thruster firings is 40 sec but the thruster will fire in bursts of 15 times to alter the shuttle's course. All data for the shuttle G.G. rates was obtained from STS-1 data  $\begin{bmatrix} 25 \end{bmatrix}$ . The period of the plots (3000 sec) is one-half an orbit. For a 5° deadband the thrusters fired in bursts every 160 sec.

The results of the total system simulation which incorporated the shuttle, AGS, P/OF, controllers, noise and disburbances are shown in Appendix F. The shuttle drifting of Appendix E is verified in Appendix F. These plots show tip response, base response (both in arc sec) and control effort (arc sec/sec<sup>2</sup>). A summary of results is shown in Table 7.

# VI.1 Deployment

Deployment of the boom involves extending the boom from its canister, initial pointing, and calibration. To the simulation this means initial boom displacements and velocities must be damped out and the boom pointed at the sun. All of the deployment activities must be carried out in the presence of noise. A typical deployment sequence can be seen in Figures 15 to 20. Figure 15 shows the initial damping out of modal displacements and velocities. The initial conditions of these figures were

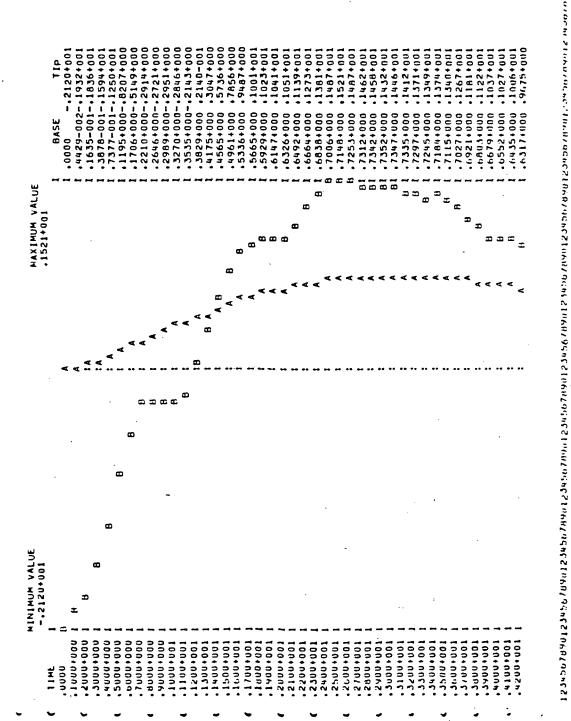
TABLE 7

	RESULTS SUMMARY									
	MAXIMUM	RMS								
NOISE	.06 ARC SEC	.015 ARC SEC								
VRCS DISTURBANCE	* -									
ROLL x	.5 · ARC SEC	.36 ARC SEC								
ŷ	.065 ARC SEC	.015 ARC SEC								
Z ^	.065 ARC SEC	.015 ARC SEC								
PITCH x	.065 ARC SEC	.015 ARC SEC								
ŷ	.09 ARC SEC	.035 ARC SEC								
Ž	.065 ARC SEC	.015 ARC SEC								
YAW x	.065 ARC SEC	.015 ARC SEC								
ý	.065 ARC SEC	.015 ARC SEC								
Z	.19 ARC SEC	.12 ARC SEC								
DISTURBANCE SETTLING TIME	1 SEC									
DEPLOYMENT SETTLING TIME	10 SEC									
TORQUE	·									
x	14.9 N-m									
ŷ	5.7 N-m									
ź .	.8 N-m									
SHUTTLE DEADBAND	J.º	1°								

<sup>\*</sup> INCLUDES NOISE

FIGURE 15

BOOM DEPLOYMENT SEQUENCE (DISPLACEMENTS IN ARC SEC)



DATA FOR THE X-AXIS

VERSUS TIME

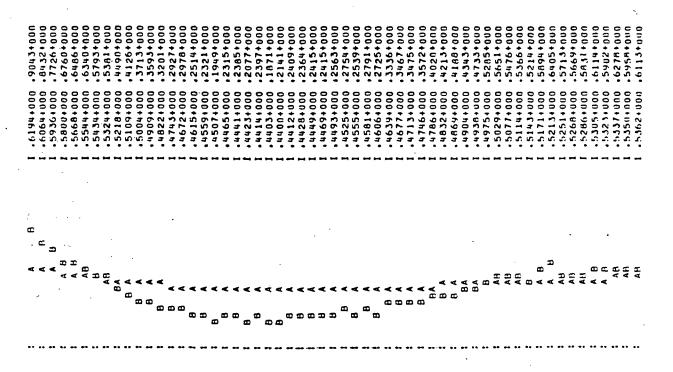
BASE 11P

VERSUS

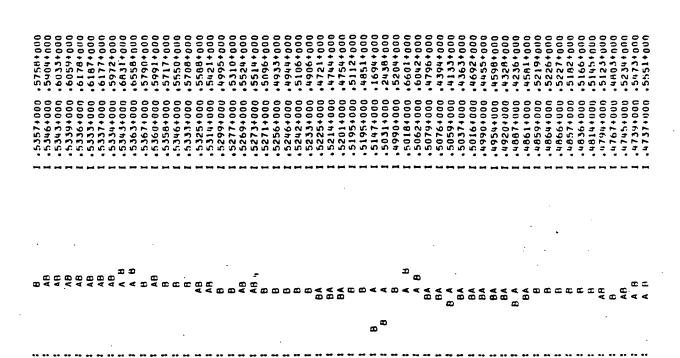
CURVE 'A' IS A PLOT OF

49

# . BOOM DEPLOYMENT SEQUENCE (DISPLACEMENTS IN ARC SEC)

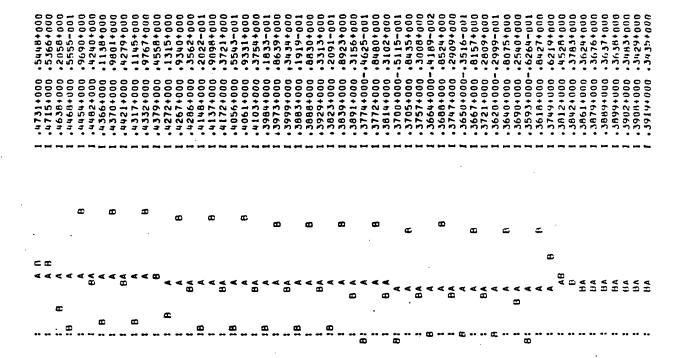


# BOOM DEPLOYMENT SEQUENCE (DISPLACEMENTS IN ARC SEC)



10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.002 | 10200.

# BOOM DEPLOYMENT SEQUENCE (DISPLACEMENTS IN ARC SEC)

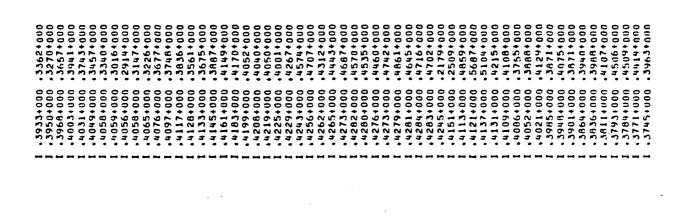


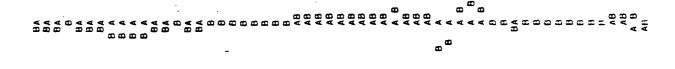
Thrusters firing

11570 + 002 11610 + 002 11610 + 002 11610 + 002 11610 + 002 11610 + 002 11610 + 002 1170 + 002

52

BOOM DEPLOYMENT SEQUENCE (DISPLACEMENTS IN ARC SEC)





BOOM DEPLOYMENT SEQUENCE (DISPLACEMENTS IN ARC SEC)

37064000 37134000 36564000 38744000 36344000 39464000 35764000 4054000 35764000 4054000 35764000 30404000 35764000 30404000 35764000 3124000 34784000 32564000 34784000 32564000 34784000 32564000 34784000 32564000 33144000 34364000 32574000 34364000 32574000 34364000 32574000 34364000 32574000 34364000 32634000 331344000 31644000 31944000 31644000 31984000 31644000 31844000 31644000 31844000 31644000 31844000 31644000 31844000 31644000 31844000 31644000 31844000 31644000 31844000 31644000 31844000 31644000 31844000 31644000 31844000 31644000 31844000 31644000 31844000

27/24-002  chosen at random. Figures 16-20 show the calibration and initial pointing of the boom. The torque required to initially damp the boom, point and calibrate it did not exceed the 33.9 N-m capability of the AGS torques and was limited to 14.9 N-m in  $\hat{x}$  and 5.7 N-m in  $\hat{y}$ .  $\hat{z}$  did not possess modal dynamics due to the low tip mass [14]. Extended plots and data of deployment are shown in Appendix F, Figures F1 to F43 including torque plots. All tip and base plots are in ARC SEC and all torque plots are in N-m.

# VI.2 Thruster Firings

The typical responses of the boom tip and base to thruster firings are shown in Figures 21 to 23. Figure 21 shows a typical response to a roll axis VRCS thruster firing. The maximum tip error was .6 arc sec while the maximum base error was .048 arc sec. The maximum control effort was 28.9 arc sec/sec<sup>2</sup> resulting in a torque demand of 8.1 N-m. A complete thruster sequence is shown in Appendix F, Figures F44 to F61.

Figure 22 shows a typical response to a pitch axis VRCS thruster firing. The maximum tip error was .03 arc sec while the maximum base error was .02 arc sec. The maximum control effort was .8 arc sec/sec<sup>2</sup> resulting in a torque demand of .337 N-m. A complete thruster sequence is shown in Appendix F, Figures F62 to F100.

A typical response to a yaw axes VRCS thruster firing is shown in Figure 23. The maximum control effort required was .0008 arc sec/sec<sup>2</sup> or a torque of .01 N-m. The maximum tip and base errors were .19 arc sec and .19 arc sec respectively. A complete thruster sequence can be seen in Appendix F, Figures F101 to F139.

# VI.3 Noise

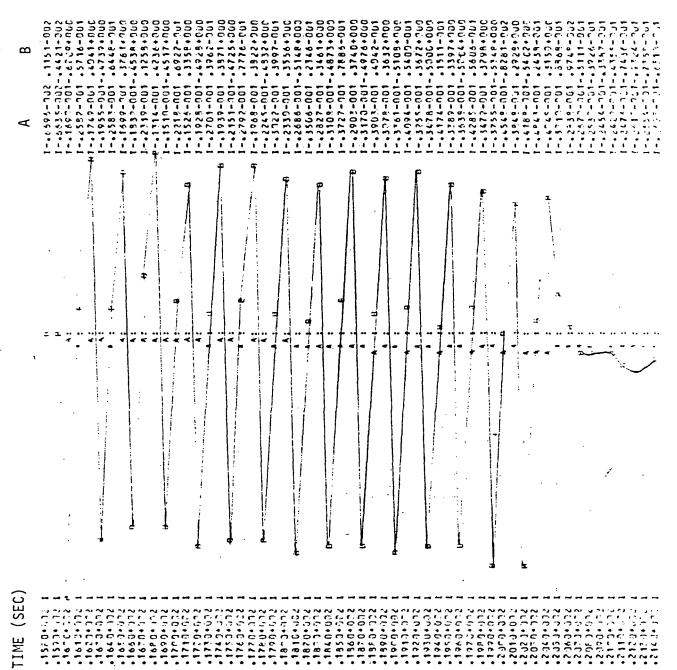
Of considerable interest in the P/OF is the system noise. Noise appears as random excursions of the boom tip (primary effect) and base

FIGURE 21

## ROLL DISTURBANCE RESPONSE

A = BASE

B = BOOM TIP



## PITCH DISTURBANCE RESPONSE

A = BASE

B = BOOM TIP

A B

1-,1939-001-,2346-001

1-,1939-001-,22147-001

1-,1939-001-,22147-001

1-,1939-001-,22147-001

1-,1939-001-,22147-001

1-,1939-001-,2722-001

1-,1939-001-,2722-001

1-,1939-001-,2716-001

1-,1939-001-,2716-001

1-,1939-001-,2716-001

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1-,1639-001-,2738-001

.9214+002 . 4128.002 . 4138.002 . 4138.002 . 4138.002 . 4138.002 . 4138.002 . 4138.002 . 4140.002 . 4140.002 .9148 0002 .4152+002 .9154+002 .9158+002 9210+002 ,9164+002 9166+002 9182+002 4190+002 92044056 ,92061002 300+8026 9212+002 9160+002 9192+002 4146+002 300+0026

# YAW DISTURBANCE RESPONSE

A = B = BASE = BOOM TIP

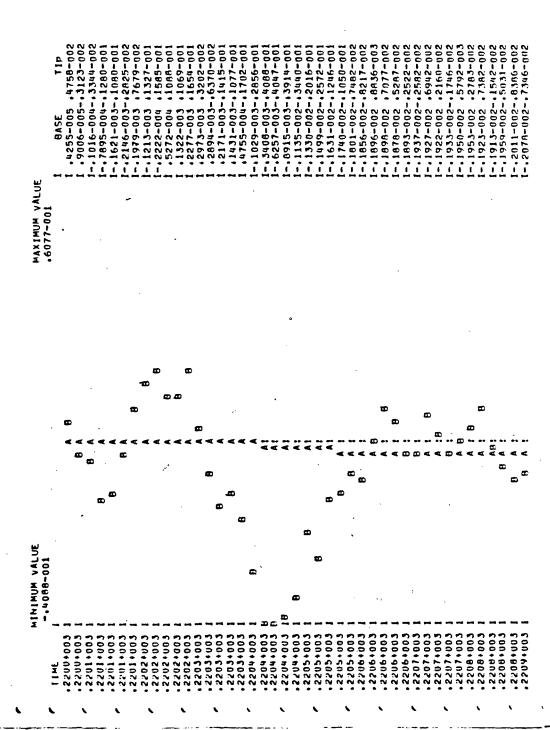
മ	1870+00	1875+00	1880+000	00++881	1888+00	1891+00	00+4681		00++061	00+9061	1908+00	1910+00	00+5161	00+2161	1920+00	1922+00	1925+00	1926+00	1927+00	1928+00	1929+00	1931+00	1934+00	1935+00	1937+00	000+0761	1942+00	1944+00	1946+00	1950+00	1952+00	1953+00	1955+00	1957+00	1959+00	1960+00	1963+00	1965+00	1966+00	1966400	00+5451	1970+00	1971+00	1971+00	1971+00	00+0401	20+02	
¥	870+00	875+00	00+088	884+00	888+00	891+00	895+00	00+668	00+106	00+906	908+00	910+00	913+00	00+616	920+00	922+00	925+00	926+00	927+00	928+00	929+00	932+00	934+00	935+00	937+00	19404000	942+00	00+556	00+956	950+00	952+00	953+00	955+00	957+00	00+656	962+00	963+00	965+00	966+00	900+006	00+595	970+00	971+00	971100	971+00	00+1/6	970+00	
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TIME (SEC)

- 2300 + 000 3 : 2300 +

(secondary effect). Figures 24 and 25 show a typical on target noise time course. The maximum noise was bounded by .1 arc sec for the boom tip and an order of magnitude less for the base. The rms noise was approx imately .015 arc sec for the boom tip in  $\hat{x}$ ,  $\hat{y}$  and  $\hat{z}$  (boom roll). Complete noise characteristics about the  $\hat{x}$  axis are shown in Appendix F Figures F140 - 153 over a 15 sec time period.

# NOISE CHARACTERISTICS



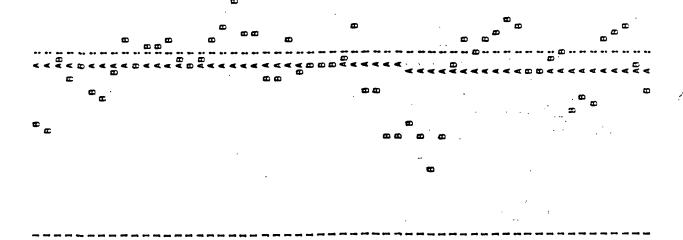
DATA FOR THE X-AXIS

VERSUS VERSUS

CURVE '8' IS A PLOT OF

#### NOISE CHARACTERISTICS





22101003 210+003 2210+003 2210+003 2211+003 11+003 11.003 2111003 212+003 212+003 212+003 22121003 2124003 213+003 2213+003 22134003 3+003

210+003

# VII. Conclusions

As the results show, the P/OF is asymptotically stable (returns to rest at no displacement after an initial displacement). In addition the P/OF has good pointing accuracy ( $1\sigma$  = .03 arc sec.), good pointing stability ( $1\sigma$  = .015 arc sec quiescent) and low disturbance responses (.5 arc sec maximum). The controllers utilized were an inner loop modal controller which actively damped the P/OF boom and an outer loop rigid body controller utilizing the PID controller of the AGS + the AGS modal filters. The state of the art sensors proposed allow the system to work within error tolerances. The AGS torquer appear to be sufficient to move and control the P/OF's large inertia. Disturbances, either VRCS thruster firings or man motion, do not have significant effects on the pointing stability of the system.

The main problem with a system of this type is cost.<sup>[23]</sup> The inner loop controller requires filters plus an eight order estimator which could cost as much as 3-4 million dollars alone. The implementation of the rigid body controller plus modal filter could easily run just as much. Clearly, a less expensive way of achieving the same results would be of great benefit.

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- IX. Appendices
- IX.A. Plant Data

# APPENDIX A PLANT DATA

# A.1. MATRICES

$$A_{c} = \begin{cases} 0 & 1 \\ -1.188 & -.0436 \end{cases} & 0 \\ 0 & 1 \\ -1.188 & -.0436 \end{cases}$$

$$0 & 1 \\ 0 & -55.48 & -.298 \end{cases}$$

$$0 & 1 \\ -55.48 & -.298 \end{cases}$$

$$A_{s} = \begin{cases} 0 & 1 \\ -475.9 & -.872 & 0 \\ 0 & 1 \\ -475.9 & -.872 & 0 \\ 0 & 1 \\ 0 & -1958 & -1.77 \end{cases}$$

$$(A-2)$$

$$0 & 1$$

$$0 & 1$$

$$-1958 & -1.77$$

 $A_{G} = \begin{pmatrix} 0 & 1 & & & & \\ 0 & 0 & 1 & & & 0 \\ & & & 0 & 1 & \\ & & & 0 & 0 & 1 \\ & & & & 0 \end{pmatrix}$  (A-5)

(A-6)

	Γο	0	0
	-69.45	-2.523	0
	0	0	0
B <sub>s</sub> =	-2.523	69.45	0
(8x3)	0	. 0	0
	5.204	34.88	0
	0	0	0
	+34.88	-5.205	0

(A-7)

(A-8)

(A

$$B_{G} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ K_{x} & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & K_{y} & 0 \\ 0 & 0 & K_{z} \end{bmatrix}$$
(A-10)

$$C_{C} = \begin{bmatrix} 0 & 7.82E-4 & 0 & -1.96E-3 & 0 & -9.2E-4 & 0 & 1.07E-3 \\ 0 & 8.03E-4 & 0 & 3.19E-4 & 0 & 4.3E-4 & 0 & 3.7E-4 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$
(A-11)

$$C_{s} = \begin{bmatrix} 0, -7.1E-4, 0, -2.8E-5, 0, 7.5E-5, 0, 4.8E-4 \\ 0, 1.5E-5, 0, -4.3E-4, 0, 3.3E-4, 0, -4.9E-5 \\ 0, 0, 0, 0, 0, 0, 0, 0, 0 \end{bmatrix}$$
 (A-12)

$$C_{R} = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \end{bmatrix}$$
 (A-13)

$$C_{G} = \begin{bmatrix} 1, -2.02, -2.08, 0, 0, 0, 0 \\ 0, 0, 0, 1, -4.116, -3.62, 0 \\ 0, 0, 0, 0, 0, 0, 0, 1 \end{bmatrix}$$
 (A-15)

## A.2. MOMENTS OF INERTIA

for Roll (x-axis) Gimbal

$$\frac{K_{TD}}{J_{EQ}} = \frac{M_p RL3}{J_{px} + M_p RL3^2}$$

$$= \frac{685(6.5)}{75230 + 685(6.5)^2} = \frac{4,452.5 \text{ kgm}}{(57230 + 28,941) \text{kgm}^2} = \frac{4452.5}{86,171.25} = 0.05167 \text{ m}^{-1}$$

for Pitch (y-axis) Gimbal

$$\frac{K_{TD}}{J_{EQ}} = \frac{M_{G}(RE2) + M_{P}(RE2 + RC2 + RC3)}{[J_{GY} + J_{PY} + M_{G}(RE2)^{2} + M_{P}(RE2 + RC2 + RC3)^{2}]}$$

$$= \frac{328(.1064) + 685(2(.1064) + 6.5)}{[(328 + 57, 230) + 328(.1064)^{2} + 685(2(.1064) + 6.5)^{2}]}$$

$$= \frac{4633.2}{88428.9} = .05239 \text{ m}^{-1}$$

for  $Y_{GY}$ , assume entire mass of Gimbal is a 'thin' disk lm in dia.

then 
$$J_{GY} = mr^2 = 328(1)^2 = 328 \text{ kgm}^2$$

$$-M_p = 685 \text{ kg}; \text{ c.m.} = 6.5\text{m}$$

SPERRY REPORT, April 1980 "Design & Performance of AGS" pg. 44

- TOTAL AGS WEIGHT w/ROLL(z-axis) 
$$\rightarrow$$
 328 kg = M<sub>G</sub>

From Sperry  $J_{p\gamma} = J_{p\chi} = 57,230 \text{ kgm}^2$ 

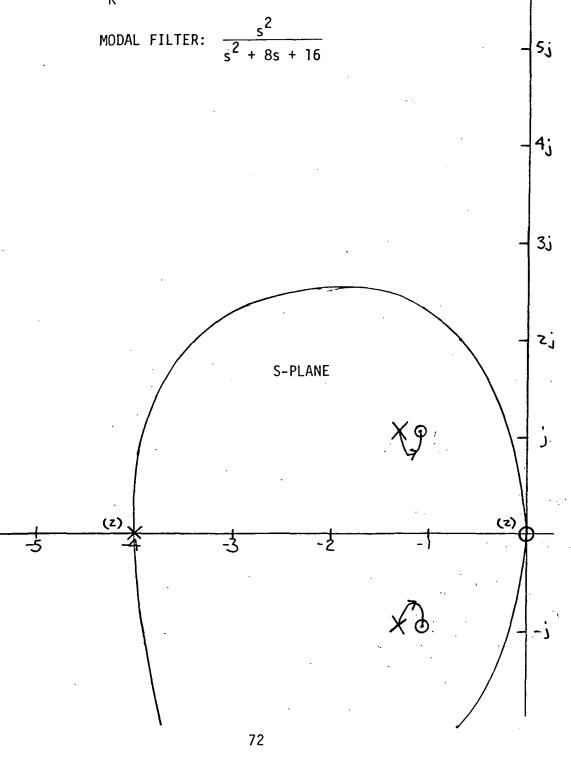
$$RE2 = RC2 = .1064m RL3 = c.m. = 6.5m$$

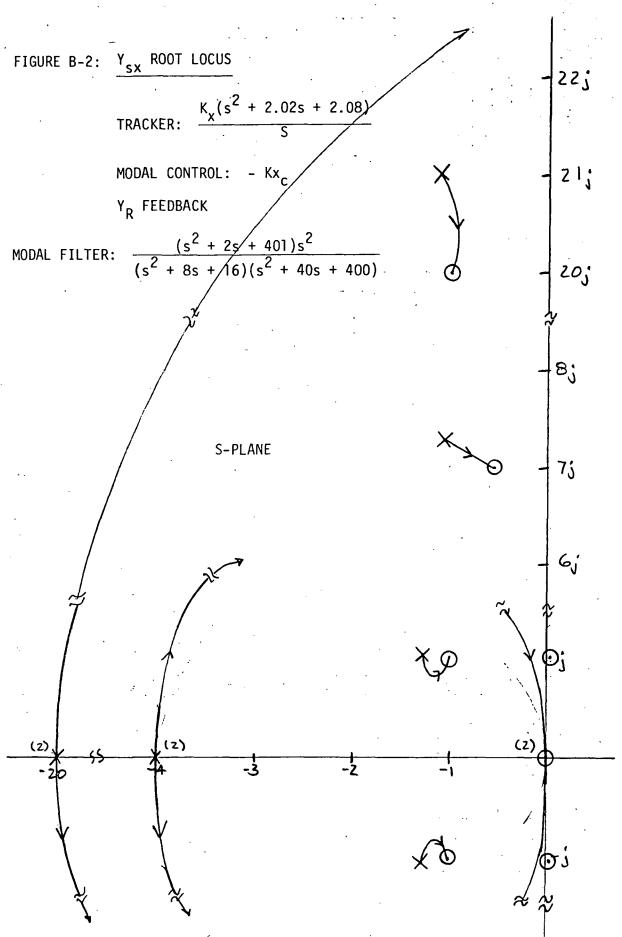
## IX.B. Root Locus Plots

TRACKER:  $\frac{K_x(s^2 + 2.02s + 2.08)}{S}$ 

MODAL CONTROL: - Kxc

Y<sub>R</sub> FEEDBACK

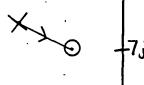




TRACKER: 
$$\frac{K_x(s^2 + 2.02s + 2.08)}{S}$$

MODAL FILTER: 
$$\frac{s^2}{s^2 + 8s + 16}$$

S-PLANE









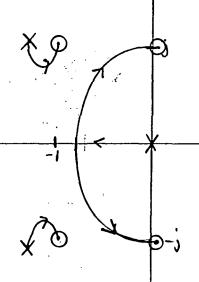


FIGURE	R_4.	Y ROOT	LOCUS
FIGURE	D-4:	'cv Nooi	LUCUS

TRACKER:  $\frac{K_y(s^2 + 4.116s + 3.62)}{s^2}$ 

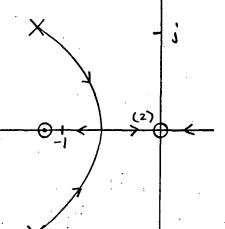
MODAL CONTROL: - Kx<sub>c</sub>

Y<sub>R</sub> FEEDBACK

MODAL FILTER:



5;



Y<sub>sy</sub> ROOT LOCUS FIGURE B-5: 22;  $\frac{K_y(s^2 + 4.116s + 3.62)}{S}$ MODAL CONTROL: - Kxc 21; Y<sub>R</sub> FEEDBACK MODAL FILTER:  $\frac{s^2 (s^2 + 2s + 401)}{(s^2 + 8s + 16)(s^2 + 40s + 400)}$ 20; 85 7 j

FIGURE B-6:

Y<sub>Ry</sub> ROOT LOCUS

TRACKER:  $\frac{K_y(s^2 + 4.116s + 3.62)}{S}$ 

MODAL CONTROL: - Kxc

Y<sub>R</sub> FEEDBACK

MODAL FILTER:  $\frac{s^2}{s^2 + 8s + 16}$ 



6

5.

4

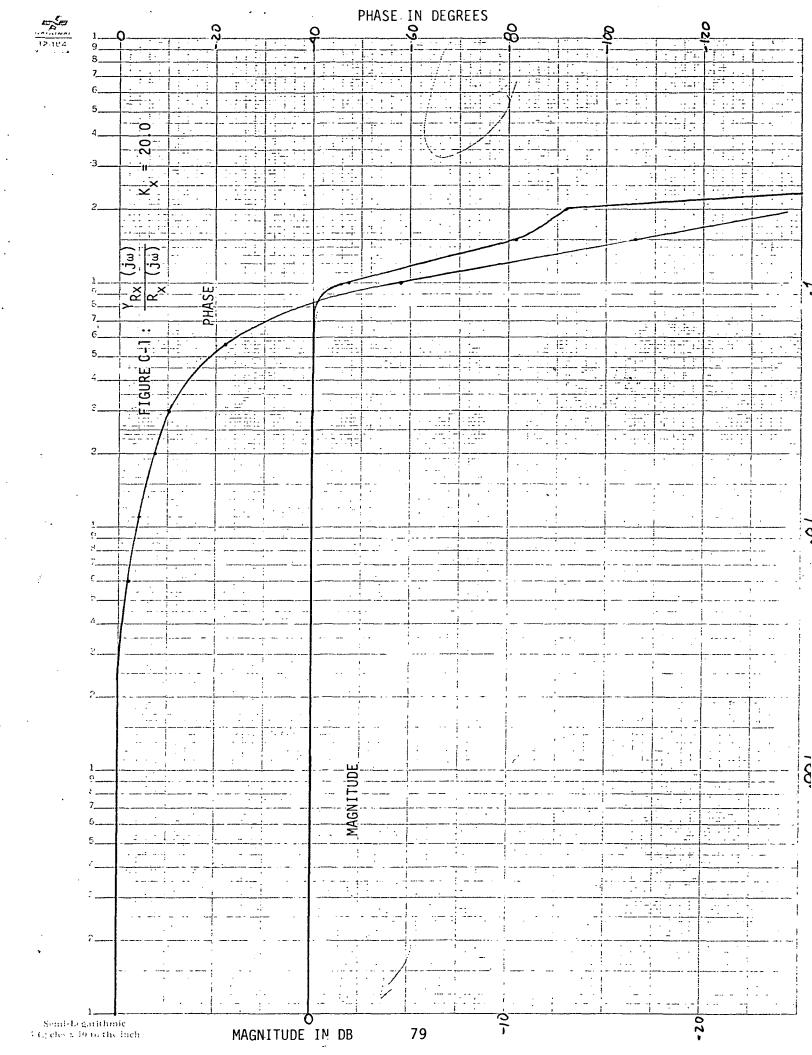
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y go

## IX.C. Bode Plots



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## IX.D. <u>Simulation Programs/Flowcharts</u>

38.9. FORFLO.S EE.AGS/SIM
FLOWCHRATED BY FORFLO /X878/ CM 11 AUG 21 AT TR:07:51
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50880UTINE AGS(XAOISE)
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SIM FLCWCHARTED BY FORFLO (XBJE/ CN 13 AUG 91 AT 08:03:52	SUBFOUTINE LGS (KNGISE)	I [SIGNAL FOR THE NOISE ] I [THE AGS. ] I	COMMON TARNOON	1 FOR THE QUIESENT STABILITY ]	CALL RANDN (XOS, 5) Co. 12 TE-7)	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	CALL RANDMING STORES ST	1 Colore BRAIC SUM IS THE TOTAL 1 I INCISE		TOWNS TO THE SECOND STATE OF THE SECOND STATE	RETURN :
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BA\*Y.FORFLO,S EE.ALOSXY/SIM Flowch\*ated by Forflo /x378/ on 12 Aug 81 AT 38:03:54

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C...COMPUTE ALOS FCR THE LATERAL GIMBAL/ROLL (X-AXIS)
ALOSX*((OZ+,2128).6 2E-4-.002176).cos(sigma)...002318*SIN(sigma)
C...Check for end of X-thřuster firing sequence
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  C... CHECK SAMPLE(10,1) -- IF ZERC, UDIST# 0 AND GO TO Z-AXIS
IF(SAMPLE(10,1). NE. 0.3 50 TO S
UDIST(2,1) = 0.
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               C...COMPUTE ALDS FOR THE ELEVATION GIMPAL/PITCH (Y-AXIS)
                                                  C...ACCELERATION IN THE DIRECTIONS PERPINDICULAR TO C...THE LINE OF SIGHT ARE DETERMINED AND USED TO SCALE C...A DETERMINED PULSE RESPONSE.
      COMPUTE THE INPUT DISTURBANCE AT THE
                                                                                                                          COMMON/CLOCK/T.bT.TRX,TRY,TR2
COMMON/PASS1/EHTET(3,3),F6(8,3),F7(8,3),F8(8,3)
&,F9(12,12),F12(3,3),F11(3,3)
COMMON/PASS3/UDDCT(3,1),RK(3,8),RC(3,1),X(40,1)
COMMON/PASS4/SAMPLE(12,1),UD1ST(3,1),X
                                                                                                                                                                                                                                                                                                                                                                                  C... CHECK X-AXIS FIRST -- IF TRX > C., GO TO X RESFONSE
                                                                                                                                                                                                                                                                                                                                                                                                                                     NON ZERO GO TO X RESPONSE
                         OF THE BOCM DLE TO THE THRUSTER FIRINGS
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           UDIST(1,1)=ALOSX+GAINX
C...ARRIVE HERE FOR Y #XIS. CHECK IF TRY >
4 IF(TRY+GT+A-)GC TO 5
                                                                                                                                                                                                                                                                                                                                                                                                                                                            IF(SAMPLE(3,1).NE_BOB)60 TO 2
C...IF NO X RESPONSE, 60 TO Y-AXIS RESPONSE
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            IF(TRX.GT.01.AND.TRX.LT...2) THEN
UDIST(1.1)=C.
6C TO 4
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            C...ARRIVE HER FOR Y RESPONSE
S TRY=TRY+OT
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              IF(TAX.GE..2)THEN
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   ALOSX=-ALCSX
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        GAPPAEX(11,1)
                                                                                                                                                                                                                                                                               AINX# 3,35167
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            UDIST( 1, 1) = 0
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                SIGMA=X(9,1)
                                                                                                                                                                                                                                                                                                         6A1NY= .05239
                                                                                                                                                                                                                                                                                                                                                    02= 110(2,1)
                                                                                                                                                                                                                                                                                                                             0x=F10(1+3
                                                                                                                                                                                                                                                                                                                                                                                                                                C...CHECK SA"PLE
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               TRX . TRX+DT
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    E 40 11
C...SUBROUT
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ALOSY-ALCS V

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C...ARRIVE HERE FOR THE Z-AXIS

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	178X-L14,2) THEN >	70.4	IF (9.1)  (9.1)  S.D.D.D.D.D.D.D.D.D.D.D.D.D.D.D.D.D.D.	6MA) 6MA) 6MA) 6MA) 6MA) 6MA) 6MA) 6MA)	05.37.45.0	### OSX # GAINX	LIF TRY > G.  1. TRY > G.
a a a a a a a a a a a a a a a a a a a	I I I I I I I I I I I I I I I I I I I	 99		# ALCSX# ((CZA & Z128) #6.2E=4-6.02.476) #CGG(  E. SIGMA) - CCCA & Z128) #6.2E=4-6.02.476) #CGG(  E. SIGMA) - CCCA & Z188 SIN (SIGMA)  E. SIGMA) - CCCA & Z188 SIN (SIGMA)  E. SIGMA - CCCA & SI	I FCIRX 6EE	ALGSX=	[7]

LISE AND GO LISE AND GO LISE AND GO LISE AND AND GO COMPUTE ALC ELEVATION EITE	x
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	IF (TRZ. 61.5C.) GO 10.8	IF (FRZ_61_1C, ) GO TO 8  IF (\$APPLE (12,1) NE, 02, 00 TO 8  IF (\$APPLE (12,1) NE, 02, 00 TO 8  IF (\$APPLE (12,1) NE, 02, 00 TO 8  I FALSE  I FALSE	IF (SAPPLE (12,1) - NE, 02, 00, TO, 8  IF (SAPPLE (12,1) - NE, 02, 00, TO, 8  IF (SAPPLE (12,1) - NE, 02, 00, TO, 8  INTERNATIONAL  CONTRACTOR  CONTRA	1

**S 14** 

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DIMENSION W1(8,12), w2(8,12), w3(8,12), SIGMA(8,12)
R, USH(12,3), w4(9,2), w5(12,3), w6(8,3), w7(12,3), w8(8,1)
B, w7(12,8), w17(12,1), w11(5,8), w12(8,1), w14(2,1), w15(6,1)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         DATA ((CG(I, J), J = 1, 4), I = 1, 3)/2.08, 2.02, 4.0., 3.62, 4.116,
  SEPARATELY. THE ARTIFICIAL STATES XG ARE INTRODUCED REPRESENT THE DYNAMICS OF THE TRACKER AND THE MODAL THE GER OF FILTERS.
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         DIMENSION AMAI(4,4), CG(3,4), XSENS3(3), X4GS(3)
DATA((AMAI(1,1), 1=1,4),1=1,4),10,1,240,1-16,,-18,
                                                                                                                                                                                                                                                                                                                                                                     COMMON/PASS3/ UDDOT(3,1),RK(3,2),RC(3,1),XC(40,1)
COMMON/PASS4/ SAMPLE(12,1),UDIST(3,1),1S
COMMON/PASS6/Gq(12,1),XRDOT(6,1)
                                                                                                                                                                                                                                   COMMON/PASS1/ ETHET(3,3),F6(9,3),F7(9,3),F9(8,3), E4(12,13),F1(3,3),F1(3,3),F1(13,3),F1(12,3)
                         ...SURROUTINE COMPUTES COMPCNENTS (BOOM, R.B., SHLTTLF)
                                                                                                                                                                                  , 1) , xSHbOT (12, 1) , xGbOT (4, 1)
                                                                                                                                                                                                       DI* EHSION XR (6,1), XSH (12, 1), XG (4, 1)
                                                                                                                                                                                                                                                                                   E, ANET (3, 12), MENT (3, 12)
COMMON/PASS 2/ M(E, P), B(8, 3), BC (8,3)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 *ETHET,W4,8,3,3,8,3)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      CALL MXMLT(F9,ETHET,W4,8,3,3,8,3)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                ELSE IF(I.GT.14 AND. I.LT. 27) THEN
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         ELSE 1F(1.GT.25. MD.1.LT.38)THEN
                                                                                                                                                                                                                                                                                                                                                                                                                                                 COMMON/PASS7/A4(3, 1), 88(3,1)
                                                                                                                                                                                                                                                                                                                                          8, UP (6, 3), AR (6, 6), ASH (12, 12)
SUBROUTINE FUNCCY, XDOT, 0, N)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    IF(1.67.8. AND. 1. LT. 15) THEN
                                                                                                                                                         DIMENSION X (C, N) , X DOT (C, N)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      8, JC(9), V(2), SIGMAT(12,º)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              SH (1-14, 1) = X (1, 1)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             8545.416,2479,4-16.,-8./
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  XG(I-26,1)=x(I,1)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               C...COMPUTE THE SIGMS MATRI)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            C...UPDATE THE ETHET MATRIX
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     CALL MXMLT(N4, MET, W2
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          5,W16(6,1),W2C(12,1)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             C... COPY X INTO XCOMPON
                                                                                                                                                                                  DIMENSION XCDOTCE
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     .xc(1,1)=x(1,1)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            CALL MXMLT(F7
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 CALL MYMLTSW4
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        CALL MXMLT(WA
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 CALL MXSUP(W)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          CALL MYMLT(FE
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   CALL ETHETA
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       1=1,37
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            END II
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    1.0.53
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         CALL
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C...COMPUTE THE RIGID EODY CCNTROL (=CG+XG+XGLOT(4,8,9,1)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          C... CALL SUBTOUTINE UDCT TO COMPUTE THE MODAL CONTROL
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 C...CALL SUBGOUTINE ALCS TO COMPUTE DISTURBANCE BUE
C...TO THRUSTER FIRINGS.
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      C...NOTE THAT BB(3,1)=5. NOW DUE TO ZERO ROW IN CG RB(3,1)=9B(3,1)+2.*AA(3,1)
                                                                                                                              CALL MXMLT(W7,F11,BSH,12,3,3,12,3)
C... CALL FOR THE NOISE FOR THE A. B. MEASUREMENTS
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          UDDOT(KK, 1)=UDEOT(KK, 1)+EB(KK, 1)+X4GS(KK)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             C...CALL SUBPOUTINE AGS TO DETERMINE THE NOISE
                                                                                                                                                                                                                   C... COMPUTE THE XGDOT TERMS FOR THE TRACKER AA(1,1)=xc(1,1)-xx(2,1)-xsexsx(1)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       UDDOT(KK, 1) = UDDOT(KK, 1) + UDIST(KK, 1).
                                                                                                                                                                                                                                                                                                                            ALL MXMLTCAMAT, XG, XGDCT, 4, 4, 1, 4, 4
                                                                                  ALL MXNLT(W5, ETHET, W7, 12, 3, 12, 3
                                                                                                                                                                                                                                                                                                                                                                              GDOT (4, 1) = x GDCT (4,1)+10.+AA(2,1)
                                                                                                                                                                                                                                                                                                    AA(3,1)=4C(3,1)-XR(6,1)-XSENS3(3)
                                                                                                                                                                                                                                                                          1A(2,1)=2C(2,1)-XR(4,1)-XSENS3(2)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              CALL MXMLT(AR, XR, W15, 6, 6, 1, 6, 6)
                                                                                                                                                                                                                                                                                                                                                                                                                                         CALL MXMLT(CG, XG, BB, 3,4, 1,3,4)
BB(1,1)=BB(1,1)+XGD(72,1)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 C... COMPUTE THE TOTAL INPUT REGUIRED
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             C... COMPUTE THE BOCH DERIVATIVES
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         BB (2,1)=BB (2,1)+xGBOT (4,1)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      C... COMPUTE THE RIGIO EDDY TERMS
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       CALL MXADD (W1C+W2O+420+1)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             CALL MXMLT(ASH, X SH, W10, 1
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        CALL MXMLT(BSH+UDDCT+W10
                                                                                                                                                                                                                                                                                                                                                        GDOT (2, 1) = X GDCT (2, 1) + 2
C...COMPUTE THE SIGNAT MATRIX
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        CALL NXMLT(F3,51Gnet,b3
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      CDOT(J, 1) = WB(J, 1)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             C...WZJ NCW CONTAINS US
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            CALL AGS (XAGS)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         00 9393 KK=1,3
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  00 9399 KK=1,3
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   CALL ALOS
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         CALL UB37
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       9339
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SIM-X

FUNC

... SUBACUTIVE COMPUTES COMPONENT AEPRESENT THE DYNAMICS OF THE SEPARATELY, THE ARTIFICIAL STATES XG ARE INTRODUCED TO AND RIGID BORY FILTERS. THACKER AND THE MODIL (BOOM, R.B., SPUTTLE) N SUBRCUTINE FUNCKX, XD ST. 0. N) 

INTEGER 0 DATA((AMAT(1,1),1=1,4),1=1,4)/0.,1.,2\*C., -16.,-3.,5.0.,1.,2.0.,-16.,-3./ DATA ((CG(1,1),1=1,4),1=1,3)/2.08,2.02,4\* 0M40N/PASSI/ ETHET(3,3),F6(8,3),F7(8,3), 8(8,3),F9(12,12),F1C(3,3),F11(3,3),ANEC OMMON/P1SSZ/ A(3,3),6(8,3),8C(8,3),9R(6, ),AR(5,6),ASH(12,12) W6(8,3),W7(12,3),W3(5,1),W5(12,9),W10(12, 1),W11(9,8),W12(9,1),W14(8,1),W15(6,1), W16(6,1),W2O(12,1),J(6),V(2),S1GMA1(12, OMMON /P 4553 / UDDOT(2,1), RK(3,8), RC (3,1) COMMON/PASS4/ SAMPLE(12,1),UDIST(3,1),IS COMMCN/PASS6/GR(12,1),XRDOT(6,1) DIMENSION XC DOT(8,1), XSHDOT(12,1), X & DOT( IMENSION ###1(4,4), CG(3,4), XSENS3(3), 2,3), AEY(12,3), ANET(3,12), AEYT(3,12) SIGM (8, 12), PSH (12,3), W4 (8,3), W5 (12,3) DIMENSION W1(8,12),W2(8,12),W3(8,12), IMENSION XR (6,1), XSH(12,1), XG(4,1) COMMCW/PASS7/A4(3,1),88(3,1) DIMENSION X (O.N), XDCT (O.N)

--- COFY X INTC XCOMMON

IF(I.GT.3.AND.I.LT.15)THEN

--- [ ... COMPUTE THE SIGMA MATRIX ---[ ... UPDATE THE ETHET MATRIX CALL ETHERA : : CALL MXMLT(F3,ETHET, #4,9,3,3,8,3) x C (I, 1) = x (I, 1) : : CALL MXMLT (W4, \*NET, W2, 8, 3, 12, 3, 3) T. CALL MXNLT (F7, ETHET, W. 4, 8, 8, 8, 8, 8, 8) : : CALL MXMLT(W4, ANET, W3,8,7,12,8,3) : : CALL MXNLT (F6) ETHET, W4,8,3,5,8,3) : : CALL MAML! (W4, MENT, W2, 8, 3, 12, 8, 3) : : CALL MXSUR(SIGMA,WZ,SIGMA,3,12,3) : : CALL 'AMPLIGUE'F17, bo, 8, 3, 5, 3, 5) ELSE 1F(1.GT.26.\*ND.I.LT.38)THEN xG(1-26,1)=x(1,1) 6

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	(S1GMA, S1GMAT,			:3:	(47, F11		CALL SENSE (XSENSS)	•	AA(1,1)=4((1,1) AA(2,1)=R((2,1) AA(3,1)=R((3,1)	:	• -	2,1)=xGb@T( 4,1)=xGb@T(	•
	4.2 ·.		• •	:::::::::::::::::::::::::::::::::::::::	ALL MAPLE (A		: : :			. :		:22	:
	CALL MXTRE		(ALL	CALL MXPLT					* II II II	<b>:</b>	× .	:	:
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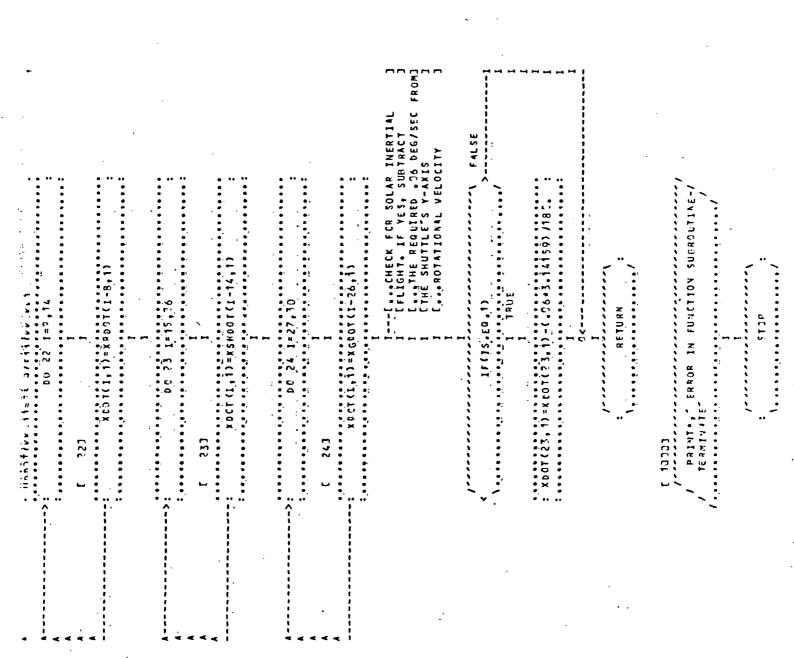
: CALL MXAED (WZ,SIGM#,SIGM#,3,12,8)

: CALL MXMLT (W5, ANET, W7, 3, 2, 12, 3, 3)

	: :	
	BE(1,1) = BE(1,1) + XGDCT(2,1)  BE(2,1) = BB(2,1) + XGDCT(4,1)	
	I TTC ZERO ROW IN CG 3	
	: BB(',1) = BB(',1) + 2, * AA(3,1) :	
	ICOMPUTE THE MODAL CONTROL  I I I I I I I I I I I I I I I I I I	
	TOUR JUNE 2	
·.	I —— [ TO THRUSTER FIRINGS.	
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	1["COETERMINE THE NOISE 1	
	(SOWX) SOM 1114 O	•
	I EREQUIRED  1 EREQUIRED	
	1	
	: UDD37(KK,1)=LDD37(KK,1)+98(KK,1)+X465(KK):	
	I[CHECK FCR TORQUER LIMITS ( ] I [SITURATION) I	

OMPUTE THE RI
CALL MXACD (W15, W16, 6, 3, 1, 6, 3)  CALL MXACD (W15, W16, XRDOT, 6, 1, 6)  I

•	r 2221	
	X COCT (1,1)=K8(1,1)	
		`
	I C COMPUTE THE SHUTTLE TERMS . 3	
	• •	
	CALL MANET (BSH, UDDCT, WIO, IV, 1, 1, 1, 1, 2, 3)	
	CALL 3xaro (210) Sample 221,121	
	<b></b>	
	TO CALL MARLE (ASH AND NATIONAL TO THE STATE OF THE STATE	
	ACT TO COLUMN TO	
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	CXSH SAMPLE 4GR	
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# . # # # # # # # # # # # # # # # # # #	00 21 1=1+8	
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303021.

SUBROUTINE GE

503032.

C...SURRCUTINE DEFINES THE GRAVITY GRADIENTS ACTING

503034.

C...ARE BASED ON EXPERIMENTAL DATA.

503034.

COMMON/CLOCK/T

5030305.

FIRSTALSS 6/6RGR(12,1)

FIRSTALSS 6/6RGR(12,1)

FIRSTALSS 6/6RGR(12,1)

FIRSTALSS 6/6RGR(12,1)

FIRSTALSS 6/6RGR(12,1)

FIRSTALSS 6/6RGR(12,1)

GRGR(1,1)=0.

GRGR(1,1)=0.

GRGR(1,1)=0.

GRGR(1,1)=0.

GRGR(11,1)=0.

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GRGR(11,1)=0.

GRGR(11,1)=0.

GRGR(11,1)=0.

GRGR(11,1)=0.

GRGR(11,1)=0.

GRGR(11,1)=0.
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.104

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COMMON/THRUST/XT IME(500,2), YTIME(200,2), 271ME(200,2), 1XT, 1YT, 1ZT
                                                                                                                                                                                                                                                                                                                                            COMMON/PRNT/ YX(15 CD. 3), YY(15 CC. 3), YZ (1530,3), YSH(15 DD. 3), INUM
                                                                                                     C...USES SUBROUTINES SAMPLE, GE, AND UDOT. COUPLING IN THROUGH
C...THE EQUATIONS FOR THE SHUTTLE TERMS.
                                                                                                                                                         DIMENSION X(40,1), X001(40,1), CC(3,8), CR(3,6), XSH(12,1)
                         ***CALLS SUBROUTINE R COMM 10 DETERMINE ACCELERATION INPUTS
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        COMMON/PASS&/ SAMPL(12,1),UDIST(3,1),IS,DB
COMMON/PASS3/UEDCT(3,1),NK(3,8),RCOM(3,1),XC(43,1)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  COMMON/PASS1/ETHET (3,3), F6 (8,3), F7 (8,3), F8 (8,3)
8, F9 (12,12), F12(3,3), F11(3,3), ANE (12,3), JEN (12,3)
                                                                                                                                                                                                               DIMENSION P1(3,1), P2(3,1), Y(7,1), XR(6,1),T(3,1)
DIMENSION OUT(15,00,2)
... MAIN FROCHAM TO INTEGRATE SYSTEM OF EQUATIONS
                                                   ... READS IN CC AND CUIPUTS THE TIP RESPONSE AS
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         "ENTER THE AC MATRIX ROW-WISE"
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                COMMON/PASS2/A(8,8),8(8,3),8C(8,3)
                                                                                                                                                                                                                                                                                                                                                                                                         CHABACTER+1 C(3)
CHABACTER+6 XN1M,YNAM(3),YSHNAM(3)
                                                                                                                                                                                                                                                                                               COMMON/TIMES/TXI,TYI,TZI,NX,NY,NZ
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                COMMON /PASS6/64(12,1), xRbot (6,1)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               TITLE(1)= DATE FOR THE Z-AXIS
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         SIXT-A BHE COL FLEG
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            COMMON/KEEP/TX,TY, TZ, 1X, IY, 12
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         TITES(4)= SHUTTLE ROTATIONS
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      COMMON/ANGLES/THEX, THEY, THEZ
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    COMMON IP ASST / AA (3,1), BB (3,1)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        DATA A, B, INUM / 64+0'., 24+0., 0/
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            R, BR (6, 1), AR(6, 6), ASH(12, 12)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      DATA AP, 4SH/7640., 16640.
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           TITLE(1)= DATA FOR THE X
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            DATA 1XT, 1YT, 12T /0,0,C/
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            6, ANET (3, 12), AENT (3, 12)
                                                                                                                                                                                                                                                                                                                                                                                                                                                            CHARACTER+20 TITLE (4)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              COMPON/CLOCK/TIME, DT
                                                                             Y = CC+XC + CB+XR
                                                                                                                                                                                                                                                                     THE THOUNDRINGHOOM
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          DATA NX, NY, NZ/3+E/
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             YSHNAM (1)="THETAX
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   YSHNAM(2)="THETAY
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               Y S H N A M (3) = " T F E I A Z
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             YNAM(1)= TORGUE
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   YNAM(2)= BASE
YNAM(3)= TIF
                                                                                                                                                                                     EXTERNAL FUNC
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                C1=1,14,35E-6
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     LUELL SECON
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       71118(3)=
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       PRINTAL
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               C(2)= 1
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        C(1)="
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           (i)=_B,
                                                                                                                                                                                                                                                                                                                                                                                 B, IPRINT
                                                                                                                                                                                     80000
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ENTER THE FIG MATRIX ROW-WISE
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   CENTER THE F11 MATRIX ROW-WISE
                                                                                                                                                                                                                                                                                                                                                                                                           PRINT. ENTER THE F7 MATRIX RCW-WISE"
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    " ENTER THE FO MATRIX ROW-WISE"
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      ENTER THE F8 MATRIX ROW-WISE
                                                                                               PRINT+, ENTER THE BC MATRIX ROW-WISE PRINT131
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         WRITE(6,190) (F11 (I,1), J=1,3)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             #RITE (6, 100) (FS(I, J), J=1,12)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            HAITE (6, 100) (F10 (I, J), J=1,3)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  #RITE(6,133) (F7(1,3), J=1,3)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               JR17E(6, 103) (FE(1, J), J=1,3)
                                                                                                                                                                                      WRITE(6, 100) (BC(1, J), J=1,3)
                                                                                                                                                                                                                                                                                                                                                                                   JAITE(6, 100) (F (1, 1), J=1, 3)
                   HRITE (6, 100) (4 (1,1), J=1,8)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           READ+, (F 3(I, J), ,J=1,12)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        DO 12 I=1,?
PEAD*,(F11(I,J),J=1,?)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               EAD*, (F3(I, J), J=1,3)
                                                                                                                                                                        READ*, (BC(1, J), J=1,3)
                                                        ORP4T (3(2X, 1PE11.4))
READ+, (A (I, J) , J= 1, 2)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          00 11 1=1,3
                                                                                                                                                     00 3 I=1,8
                                                                            FORMAT (/)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      0000
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          7 60 00
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ENTER THE DEADBAND FOR THE SHUITLE IN DEGREES"
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                C TG 2**35 FCR THE NOISE GENERATORS"
                                                                                                                                                          ENTER THE INITIAL TIME, THE FINAL TIME, THE STEP SIZE FOR THE INTEGRATION ROUTINE, AND THE PRINT FREQUENCY FOR OUTPUT.
                                                                                     C. . . COPY THE INITIAL SHUTTLE ANGLES INTO COMMON/ANGLES/
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             ENTER THE INITAL RANDOM NUMBER FROM THE
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          CUTPUT ONLY) OR ENTER & ZERO
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              ENTER A 1 IF THE SIMULATION IS SOLAR INERTIAL, OTHERWISE ENTER A 0"
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           O SUPRESS DATA PRINTING"
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           DATA PRINTED WITH PLOTS"
PRINTA," ENTER THE INITIAL STATE VECTOR
                                                                                                                                                                                                                                                                                                                                                                                                                                         ENTER THE CC MATRIX (CC(3,8))
                                                                                                                                                                                                                                                                                                                                 PRINTA," ENTER THE FEEDBACK MATRIX AK"
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     DATA CR/1,543,1,543,1,543,1,340,7
                                                                                                                                                                                                                                                                                                                                                                                      READ4, (RK(I; J), J=1,8)
WRITE(6, 100) (RK(I; J), J=1,8)
                                                    URITE (6, 13) (X(I, 1), I=1,13)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           WRITE(6, 100) (CCC 1, J), J=1,8)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     IF (I.GE. 9. AND . I. LE. 12) THEN
                                                                                                                                                                                                                                               PRINT**TI,TF,DT, NPRINI
PRINT101
                  PRINTIC1
READ+, (X (I+1), I=1,30)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                          READ+, (CC(1, 1), 1 = 1,8)
                                                                                                                                                                                                           READ+, TI, TF, DI, NFRINT
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              INTERVAL
                                                                                                                                                                                                                                                                                 NUM = (TF-TI)/01 +1
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                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          ENTER
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          TO SEE
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             PRINTA,IPRINT
PRINTALI
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           READ+, IPRIVT
                                                                                                    THE X =X (21,1)
                                                                                                                     THE Y=X (23, 1)
                                                                                                                                           THE 2 = X (25,1)
                                                                                                                                                                                                                                                                                                                                                                   50 15 1=1,7
                                                                                                                                                                                                                                                                                                                                                                                                                                                     00 17 I=1,3
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  PRINT+,JIY
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  PRINT+,1S
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    PRINT . DB
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          PRINT102
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     READ+, DB
PRINT101
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  7 E 4 D * , 3 4 Y
                                                                                                                                                                                                                                                                                                C...INITIALIZE
                                                                                                                                                                                                                                                                                                                                                     PRINTICA
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                READ+, IS
                                                                       PRINTICE
                                                                                                                                                                                                                             PRINT101
                                                                                                                                                                                                                                                                                                                   PRINT132
                                                                                                                                                          PRINT.
                                                                                                                                                                                                                                                                                                                                                                                                                           PR1NT102
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             PRINTIC2
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      PRINT 132
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            PRINTICA
                                                                                                                                                                                            PRINT.
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              PRINT*,
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 PRINT*,
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                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 PRINTIG
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                                                                                                                                                                                                                                                                                                                                                                                                                                           PRIKT
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    PRINTIC
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CALL PLOTS(OUT, XNAM, YNAM (2), TITLE (1), TX 1, NFRINT+DT, C (2), NX, 2, 1)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   CALL PLOTS (OUT, XAAM, YNAM (2), TITLE (2), TY 1, WFRINT+ DT, C(2), NY, 2, 1)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          CALL PLOTSCOUT, X NAM, YNAM (2), TITLE (3), TZ I, NFRINT +D T, C (2), NZ, 2, 1)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          CALL PLOTS(YSH,XNAM,YSHNAM,TITLE(4),TI,NPRINT+DT,C,INUM,3,1)
                                                                                                                                                                                                                                                                                                                                                                  CALL PLOTS COUT, XNAM, YNAM, TITLE (1), TXI, NFRINT+DT, C, NX, 1, 1)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                         CALL PLOTS COUT, XNAM, YNAM, TITLE (2), TYI, NP9INT+DT, C,NY,1,1)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               CALL PLOTSCOUT, X HAM, Y NAM, TITLE (3), TZI, NP4INT+DT, C, NZ, 1, 1)
                                                                                                                                                                                                                                                                                          CALL PRINTCTIME, RCCM, UDDGT, F11, X, CC, CR)
                                                                                                                                     CALL PRINTCTIME, PCCN, UDDCT, F11, X, CC, CR)
                                                                                                                                                                                                                            ALL RKSUB1(FUNC,X,XDOT, 10,1,DT)
IME=TIME+DT
                                                                                                                                                                                                                                                                           IF (ICOUNT .LT .NFR INT) 501020
                                                                                                                                                  C. . . BEGIN THE INTEGRATIONS
                                                                                                                                                                                                                                                                                                                                                                                               00T (II,1)=YX (II, 2)
                                                                                                                                                                                                                                                                                                                                                                                                                                            00 192 II=1,NY
0U7(II,1)=YY(II,1)
                                                                                                                                                                                                                                                                                                                                                                                                                 0UT (II,2)=YX (II,2)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      OUT (II,1)=YY (II, 2)
OUT (II,2)=YY (II, 3)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 (11,11)=Y2 (11,1)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               00 195 II=1,NZ
0UT(II,1)=YZ(II,2)
                                                                                                                                                                                                                                                                                                                                                    OUT (II, 1) = YX (II, 1)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            0U7 (11,2)=Y2 (11,7)
                                                                                                                                                                                                                                                              L+LKADD T= LKADD
                                                                                                                                                                                                                                                                                                                                                                                  KY41=11 1ct 00
                                                                                                                                                                                                                                                                                                                                     XN4.1=11 061 00
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         DO 173 11=1,NY
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 DO 174 II=1,NZ
                                                                                                                                                                    80 20 I=1, NUM
                ELSE IF(1.GT
                                                                                                                                                                                                  ALL SAMPLE
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          CALL SUMMRY
STOP
                                                                                                                       FORFAT ('1')
                                                                                                                                                                                     CALL RICOMM
                                                            CONTINUE
                                                                                         C=LNOO
                                                                                                                                                                                                                                                                                                           CCUNTED
                                                                                                                                                                                                                                                                                                                        CONTINUE
                                                                                                         PRINTIL
                                                                             TIME=TI
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303193.
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000279
                              07169,
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... THE EQUATIONS FOR THE SHUTTLED
                                                                                                               ... USES SUBROUTINES SAMPLE, 66,
                                                                                                                                              AND UDOT, COUFLING IN THROUGH
DETERMINE ACCELERATION INPUTS
                                                                                     Y = CC+XC + CR+XR
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 COMMON /P ASS3 /UDD 01(3,1), RK (3,8); RCOP(3,1)
                                                                                                                                                                                                                                                                                                                                                                                  EXTERNAL FUNC
DIMENSION F1(3,1), P2(3,1), Y(3,1), XR(6,1)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             COMMON/THAUST/XTIME(500,2),YTIME(200,2),
ZTIME(200,?),LXT,LYT,LZT
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         COMMON/P#SS6/GR(12,1),NRBOT(6,1)
COMMON/P#SS4/ SAMPL(12,1),UDIST(3,1),IS,
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            COMMON/PASS2/A(8,8),8(8,3),8C(8,3),8R(6,
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      COMMON/PRNT/ 3x(15C0,3),yy(15C0,3),yZ(15C0,3),yZ(15C0,3),ySH(15C0,3),INUM,IPRINT
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              COMMON/TIMES/TXI.TYI.TZI.NX.NY.NZ
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    COMMON/CLOCK/IIME, DI, TRX, TRY, TRZ
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            CHARACTER+6 XNAM, YNAM(3), YSHNAM(3)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     COMMON/ANGLES/THEX, THEY, THEZ
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             CHARACTER+2C TITLE(4)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    CHARACTER+1 C(3)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      JYN NES
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PRINT ( ) = SHUTLE ROTATE RHE AC MATR PRINT 101	••
PRINT, ENTER THE AC HATE  PRINT 191  PRINT 191  I I I I I I I I I I I I I I I I I I I	
PRINT 101  PRINT 101  PRINT 102  BRINT 102  PRINT 103	
PRINT 101  PRINT 101  PRINT 101  PRINT 102  PRINT 102  PRINT 102  PRINT 103	
PRINT 101  READ, (A(1, J), J=1  READ, (A(1, J), J=1  READ, (A(1, J), J=1  READ, (A(1, J), J=1  READ, (B(1, J), J=1  READ, (B(1, J), J=1  READ, (B(1, J), J=1	
PRINT 101  READS, (A(1, J), J=1  READS, (B(1, J), J=1  READS, (B(1	٠
PRINT ENTER THE BC MATE  PRINT ENTER THE BC MATER  PRIN	
READ * (A(1, J) * J= 1  READ * (B(1, J) * J= 1  READ *	
READ (A(1, J), 1J=1  URITE(6, 1CO)(A(1, J), 1J=1  URITE(1, 1J), 1	
READ (A(1, J), JET (A(1, J), J	• ••
READ (A(1, J), J=1	••
13	
PRINTIGE 11.3).  PRINTIGE 11.2  I	
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PRINTIG2  1	-
PRINT102	
PRINTS, ENTER THE BC MATR  FRINTS:  FRI	~_
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PRINTS, ENTER THE BC MATRIX RON-HISE / I I I I I I I I I I I I I I I I I I	PE11.42)
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1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	
8 END** (HC(I,J),J=1,7)	
I 1 7 (E. (B. (B. (B. (B. 1) ), J. = 1, 7) /	
qeno*, (ec(1,J),J=1,3)	•
/ 0 - 0 - 0 - 0 - 0 - 0 - 0 - 0 - 0 - 0	

2CLINIBE			⊷ ⊷				(	1	 : 14.647.41.			PRINTAL ENTER THE F6 MATRIX ROW-WI		FRINTIST	• • • • • • • • • • • • • • • • • • •	I Z 00		1	READ*, (F6(1, J)			/ MM II E(O) 1 O() ( 10 ( 10 ) ) 6 1 1 1 3 )	• • • • • • • • • • • • • • • • • • •	PAINT 192	/ *************************************	 . FUTER THE F7		
	1 1 1 1 1 1 1 1 1	: <b>&lt;</b> '	< ⋖	A B	, H :	D 33 ,	A B			•	٠.					A	< <	≺ ∢	< -	· < <	<b>«</b>							

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NI B d		Ted /	Y

READ*, (F9(I, J), J=1 I I I I I I I I I I I I I I I I I I I	PRINTIGE THE FIG WATRIX ROW-WISE/		### TEC6,100) (F10(1,J),J=1,3)  ###################################	PRINT 6 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1

---[...COPY THE INITIAL SHUTTLE [ANGLES INTO COMON/ANGLES/ \* 9 4 4 1 5 3 9 4 4 4 1 1 2 3 7 2 3 4 0 2 9 1 2 9 DATA ((AEN(1, J), J=1,3), I=1, 12) /3+0., 1., 6+ NATTE(6, 100) (F11(1,1), 3×1,7) WRITE(6,100)(X(I,1),I=1,30) PRINT+, ENTER THE INITIAL STATE READ+, (X(1,1),1=1,30) PRINT 101 FRINT 102 PRINT 102 THEY=X (27,1) THE2=x(25,1) THE X=X (21,1 3.,1.,6.0.,1.,18.0./ VECTOR"

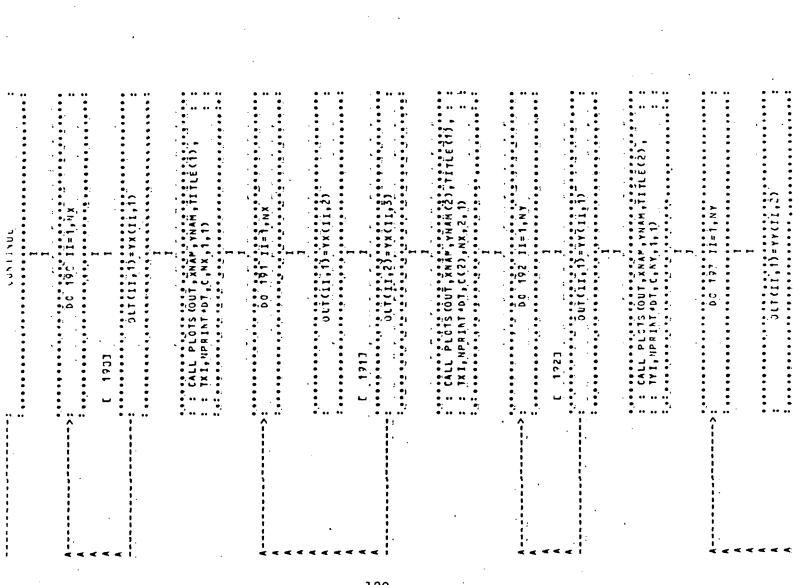
EP SIZE FOR THE	•	1	EAD to II. TF. DI, NPRINI	B: 4	PRINTIGO CONTRACTOR CO	PRINT OF TLATE OF TANKRINT	FRINTIG1	1	ENTE	PRINTIO1	DO 15 T=1,3	1
 Palut	PHINT*,		8	•	7	PRINTE	I	0; 0; 0; 0; 0; 0; 0; 0; 0; 0; 0; 0; 0; 0	 , , , , , , , , , , , , , , , , , , ,			· · · · · · · · · · · · · · · · · · ·

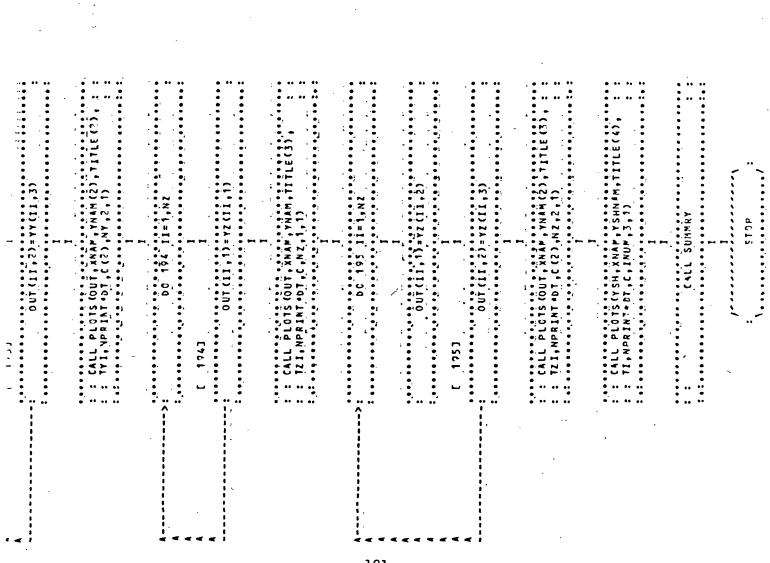
PRINT . INERTIAL, OTHERWISE ENTER A 0/ PRINTAS ENTER THE CC MATRIX (CC (13 E)) / READ = (CC(1+1) + 1=1+8) PRINT ", ENTER # 1 IF THE SIMULATION IS SOLAR WRITE(6,100) (CC(1, J), J=1,8) HAITE(6, 10C) (RK(I, J), J=1, 8) PRINT 102 READ+, IS PRINT+ , IS FRINT 172 PRINT131 FRINT 132

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		· · · · · · · · · · · · · · · · · · ·						1111		PRINT	\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \	· · · · · ·
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Ì	\	A Q	•3			UPRE.	2 0	1 4	•	)  ,	INIR	2
	E DEADBAND FOR THE	E P D + D D B	PRINTIO1		PRINT102	10 5	UTFU			1 4 4 1	IPRI	INT 132
	# # # # # # # # # # # # # # # # # # #	ELD.	PRINTIG	PRINT DB	PRINTIGE.	PRINTING FOR THE PRINTING PRIN	A ZERO	PRINTAL TO SEE ALL DATA PRINTED WITH PLOTS	PRINTIGI	RE LO CO	ANIMATOR AND ANTALANTALANTALANTALANTALANTALANTALANTA	
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	, E5.					N I I I	N. H.	PRINT				
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	24.35 FOR THE /	1	/ · · · · · · · · · · · · · · · · · · ·	/*************************************	78.4.6.6.6.6.6.6.6.7			.12) THEN >	0=1. 12)THEN:		
NUMBER FROM THE	PRINT, INTERVAL 0 TO NOISE GENERATORS	FR141101	READE, JAY	PRINTS	PRINTIGO	DATA CA/1000000000000000000000000000000000000	b 0 16 1=8,24.	IF (7 . GE . 3. A A D . I . L E	ARCI-7,1-6)= ELSE IF (1.GT-12 6SHCI-13,1-12 END IF	1 163 1 CONTINUE	

					·		34		
PRINTITI  PRINTITI  I[111 FORMAT (*17)	: CALL PAINT (TIME, RCCM, UDDOT, F11, X, CC, : : : CR)	1	THOUSE THE STATE OF S	CALL SAMPLE : :	: CALL RKSUB1(FUNC, X, XDOT, 30,1, DT) : :	1	TRUE    IF (ICCUNT, LT_ANPRINT) GOTO 2C     IF ALSE  IF ALSE	: CALL PRINT (TIME, RCCM, UDDOT, F11, X, CC, : : CR)	I CCUNT= 3





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15H' IS A PLCT OF , A6,8H VERSUS , A6/1)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                 1002 FORMAT (///T13,13HMINIMUM VALUE, 169,13HPAXIMUM VALUE/
SUBROUTINE PLOTS (Y, XLBL, YLBL, TITLE, XST, XD, C, N, NP, SS)
                                                                                                                                    SS#SCALE SHIFT: SS EQUAL TO O'INDIVIDUAL SCALING SS NOT EQUAL TO O'UNIFORM SCALING
                                                                                                                                                                                                              TITLE, (C(I), YLOL(I), XLBL, 1=1,NP)
                                                                                                                                                                                                                                                                                                                                                                                                                   1 IF(Y(1,1), LT,YSS) YSS=Y(1,1)
WRITE(6,1002) YSS,YLL,XLBL,(YLBL(1),1=1,4P)
                         DIMENSION Y(15;0,44), YL(5), YS(5), YO(5)
CHARACTER LINEA1(70), CA1(1), BLK+1
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           YO(1)=(YL(1)-YS(1))/70.
WRITE(6,1034) XLBL,(YLBL(I),1=1,NP)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              F(Y(1,1),LT.YS(1)) YS(1)=Y(1,1)
F(Y(I,1),GT.YL(1)) YL(1)=Y(I,1)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      1713,E11,4,T67,E11,4/
273,A6,713,1H1,68%,1H1,5(4%,A6))
YDD=(YLL-YS)/70,
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     $T3, A6, T13, THI, 68 X, THI, 5(4X, A6))
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         Y#1F1X((Y(1,1)-YSS)/YDD+1.)
                                                                                          CHARACTERAS XLEL, YLBL(1)
                                                                                                                                                                                                                                  FORMAT (1H1, / / T41, A20//
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             IF($5.60.0) 60 TC 10
                                                                                                                                                                                                                                                                                  IF(SS, Eq.0) 60 TC 7
                                                                                                                  CHARACTER+20 TITLE
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 1 F ( 1 Y + GT + 77) 1 Y = 7
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    IF(IY, GT.73) IY=
                                                                    INTEGER SS, IY
                                                                                                                                                                                                            WATTE(6, 1031)
                                                                                                                                                                                                                                                       CT10,7HCURVE
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      S(1)=Y(1,1)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              ÝL(J)=Y(1,J)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    0 9 J=1,NP
                                                                                                                                                                                                                                                                                                                             YSS=Y(1,1)
DO 1 I=1,N
                                                                                                                                                                                        DATA BLK/"
                                                                                                                                                                                                                                                                                                        11 = 1 (1, 1)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              I)+LSX=X
                                                                                                                                                                                                                                  1901
                                                                                                                900000
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$\langle \text{LINE(IY) = C(J)}$

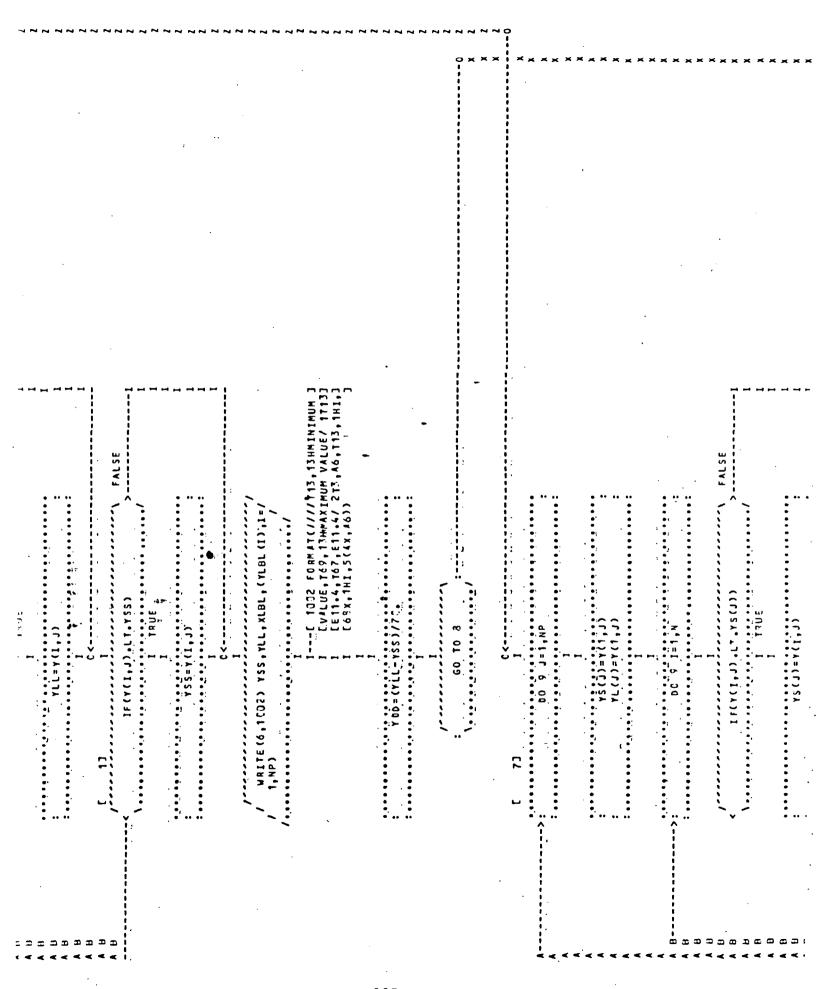
4 \text{MRITE(6, 1003)} \text{x, (LINE(K), K=1,72), (Y(I,J),J=1,NP)}$

50 \text{10 \te
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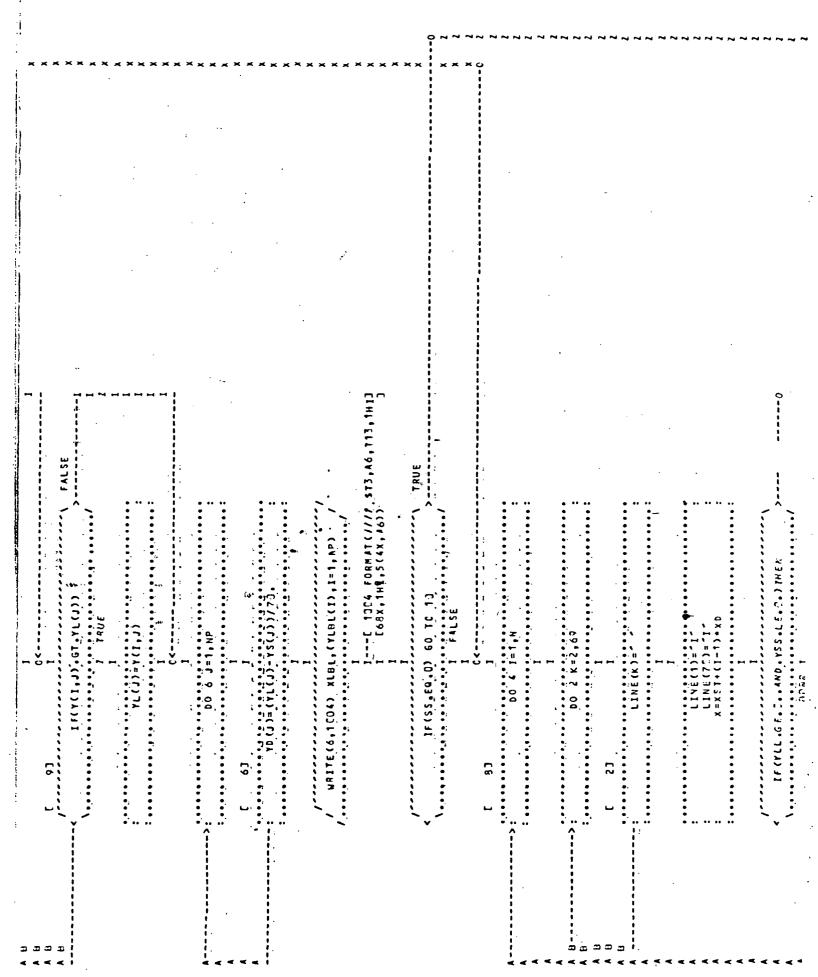
000055. 000055. 000056.

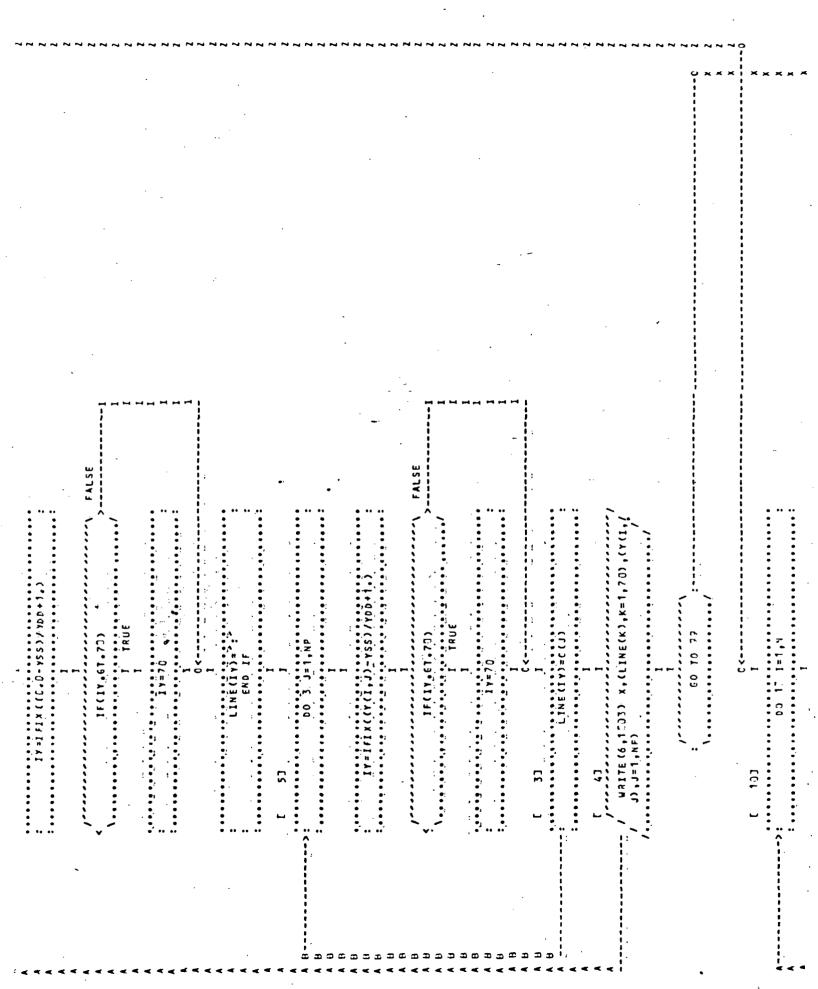
000065. 000065. 000065. 000067.

PLOTS



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	1 [E13.4)) I [E13.4)
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DIM ENSIGN RCCM (3,1), UDDGT(3,1), F11(3,3), X (40,1), CC(3,8), CR(3,8) DIMENSION T(3,7), P1(3,1), P2(T,1), Y (3,1), XR (6,1), XSH (12,1) COMMON/PRNT/ YX (1501,3), YY (1500,3), YZ (1500,3), YSH (1500,3), 1, IP COMMON/TIMES/TXI,TYI,TZI,NX,NY,NZ
                                                                                                                                                                                                                                                                                                                                                      ARC-SECONDS/SEC+27)
ARC-SECONDS/SEC+27)
SUBROUTINE PRINT (TIME, RCCM, UDDOT, F11, X, CC, CR)
                                                                                                                                                              ORMAT(" assassassassas TIMES", F6.2, 'SEC
                                                                                                                                                                                                                                                                                                                                                                                                                   x(26)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         SHUTTLE DISPLACEMENTS - NETERS
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       TIP RESFONSE Y - ARC SECONDS
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  CALL MXSCA(XR,6,1,6,C1)
IF(IP,Eq.1)GQ TO 33
PRINT*, BASE ROTATIONS - ARC SECONDS
                                                                                                                                                                                                                                                                                                                                                                                                               · •:
                                                                                                                                                                                                                                                           CALL MXMLT(F11,UDDOT, T, 3,3,1,3,3)
                                                                                                                                                                                                                                                                                                                                      PRINT96, (T(J, 1), J=1,3)
FORMAT( TRGE = ',3(1x,1PE11,4),"
FORMAT( RCOM = ',3(1x,1PE11,4),"
FORMAT( UDOT = ',3(1x,1PE11,4),"
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           CALL MXMLT(CR, XR, P2, 3, 6, 1, 3, 6)
CALL MXADD (P1, P2, Y, 3, 3, 3)
CALL MXSCA(Y, 3, 1, 3, C1)
                                                                                                                                                                                                                                                                                                                                                                                                                                                             CALL MXMLT(CC, X, F1, 3, 8, 1, 3, 40)
                                                                                                                                                                                                                                                                                                                                                                                                                 x(1) x(2) x(3)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             WRITE(6, 133) (XR(J, 1), J=1,5,2)
                                                                                                                                                                                                                                                                                                                                                                                                                             WRITE(6,100)(x(J,1),J=1,30)
PRINT161
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    HRITE(6, 103) (Y(J, 1), J=1,3)
                                                                                                                                                                                                                                                                           CALL MXSCA(UDDCT,3,1,3,C1)
IF(IP.EQ.1)GC TO 31
                                                                                                                                                                                                                                                                                                       PRINT98, (UDDOOT (J. 1), J#1, 3)
                                                                                                                                                                                                               CALL MXSCA(RCOM, 3, 1, 3, C1)
PRINT97, (RCOM (1, 1), J=1,3)
                                                                                                    IF(IP.EG.1)GC 10 3C
ORMAT(3(2x, 1PE11,4))
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          XSH(1,1)=XSH(1,1)+C1
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         IF(1P.Eu.1)GC 10 34
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         F(1P.Eq.1)GC 10 32
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           DO 19 J=1,12
XSH(J,1)=X(14+J,1)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              KR(J,1)=X(3+J,1)
                                                                                        1=1./4,85E-6
                                                                                                                                                                           PRINT99, TIME
                                                                                                                                                                                                                                                                                                                                                                                                                                                                             00 13 J=1,6
                                                                                                                                                   : ORMAT (/ /)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          `_=f 57 00
                                                                                                                                     ORMAT (/)
                                                                                                                                                                                                                                                                                                                                                                                                 PRINTIC!
                                                                                                                                                                                                                                                                                                                         PRINT 131
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   PRINT 121
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               PRINT131
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       PRINT.,
                                                                                                                                                                                              PRINT.
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F(NZ.GT.d)GCTC52 F(UDDOT(3,1),Eq.O..AND,XR(5,1),EQ.O..AND,Y(3,1).Eq.O.)GOTO37 IF CUDDOTCI,1), EQ .J .. 4ND. XR(1,1), EQ .D . . AND .Y(1,1).EQ . D. ) GOTO35 f(ubbct(2,1), Eq.O., AND, XR(3,1), Eq.Q., AND, Y(2, 1), EQ.Q., 1601036 PRINTICS
PRINT+, SHUTTLE ROTATIONS - AGC SECONDS WRITE(6,100) (XSH(J,1),J=7,11,2)
PRINTICS WRITE(4,133) (XSH (3,1), 3=1,5,2) C...COPY VALUES INTO YX , YY IF(NX.GT.0)GC 70 50 F(NY, EQ.1)TY1=TIME Y(NY, 1)=T(2,1) F(NX.EQ.1)TXI=TIME F(NZ, EQ, 1) T2 I=T IME 2(NZ, 1) = T(3, 1) F(NY.GT.0)GC 10 51 /SH(I, 2) = XSH(9,1) Y(hY, 2) = XR(3, 1) Z (NZ, 2) = XR(5, 1) X(NX,2)=XR(1,1) Y(NY, ?) =Y(2,1) X(NX,1)=I(1,1) X(NX,3)=Y(1,1) 2 (NZ, 3) #Y(3,1) SH(I . 1) = X SH (7 T + X N E X T Y = NY + 1 RETURA 707069. 707061. 707062. 907063. 300057 300058 300059 000064. 790000 000063 93066 63073 000071 00073 25000 25000 25000

PRINT

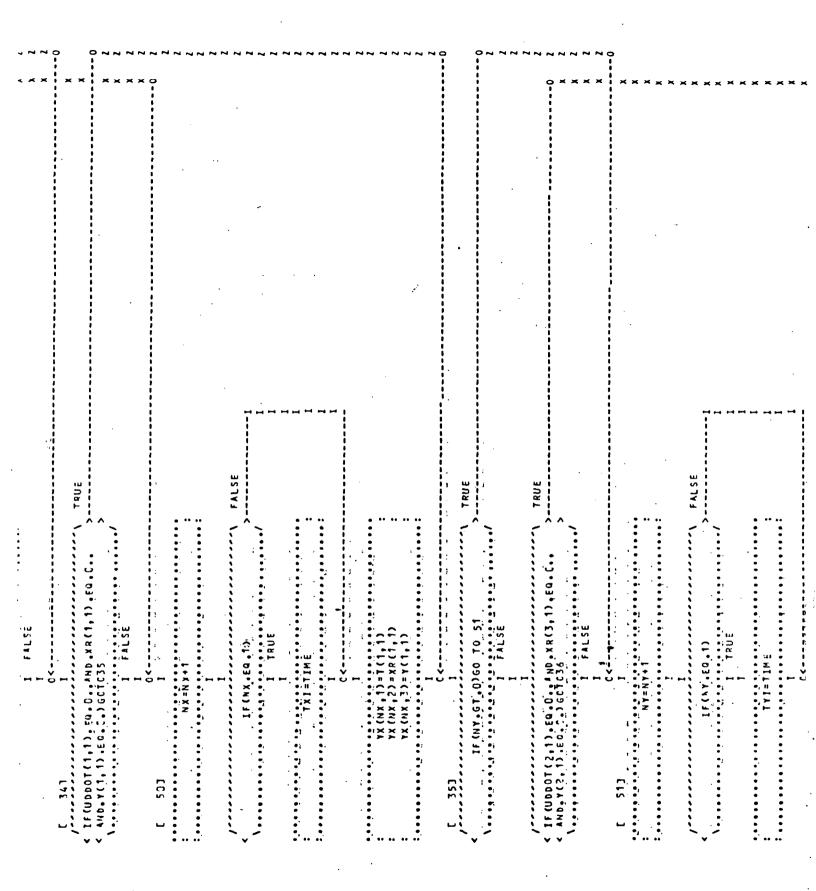
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	FALSE TENENT TO THE TENENT TO	<b>1</b>		PRINT96 (T(J, 1) , J=1, 3)  I	PRINTIDI PRINTIDI	PRINT., x(1) x(2) x(3) x(26) /	•	FRINTISI	313 I CALL MXPLT(CC, X, P1, T, F, 1, T, 4, C) : :	

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### ### ##############################	######################################	E 453  E 453  IF (1P, EQ, 1) GO TO 34  PRINT, SHUTTLE DISPLACEMENTS  HETERS  WAITE (6, 100) (XSH (1, 1), J=1,5, 2)	
### ### ##############################	### ##################################	X SH(J, 1) = X(14+J, 1)	
		E & S = 2	
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E 453			
## ## ## ## ## ## ## ## ## ## ## ## ##	E PRINT . SHUTTLE DISPLACEMENTS - AGE SECONDS SHOUTLE PRINT 101 - AGE SECONDS SHUTTLE PRINT 10		
FRINT:  PRINT:  PRINT:	E PRINT:    SHUTTLE DISPLACEMENTS - PRINT:   PRINT:   SHUTTLE DISPLACEMENTS - PRINT:   SHUTTLE PRINT:   SHUT		
IF (IP.EQ.1) GO TO 34  IF (IP.EQ.1) GO TO 34  IF ALSE  IF	######################################		
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PRINT., SHUTTLE DISPLACEMENTS - 1 FALSE	PRINT, SHUTTLE DISPLACEMENTS - FALSE	TF (IP, EQ, 1) GO TO 34 >-  I FALSE  I FALSE  PRINT,  PRINT,  PRINT,  I I FALSE  PRINT,  PRINT	
PRINT, SHUTTLE DISPL WRITE (6,100) (XSH(J) PRINT, SHUTTLE ROTAT SECONDS WRITE (6,100) (XSH(J)	PRINT, SHUTTLE DISPLACEMENTS  WRITE(6,100)(XSH(J,1),J=1,5,2)  PRINT  PRINT  I  I  WRITE(6,100)(XSH(J,1),J=7,11,2)  WRITE(6,100)(XSH(J,1),J=7,11,2)  I  I  I  I  I  I  I  I  I  I  I  I  I	PRINT SHUTLE DISPL PETERS	
PRINT, SHUTTLE DISPL WRITE (5, 100) (XSH (J I I I PRINT 10 SECONDS SHUTTLE ROTAT SECONDS SHUTTLE ROTAT SECONDS SHUTTLE ROTAT SECONDS SHUTTLE ROTAT	PRINT, SHUTTLE DISPLACEMENTS - WRITE (6, 100) (XSH (J, 1), J= 1,5,2)  PRINT   SHUTTLE ROTATIONS - A AC SECONDS SECONDS I WRITE (6, 100) (XSH (J, 1), J= 7,11,2)  HRINTINI I I I I I I I I I I I I I I I I I	PRINT, SHUTTLE DISPL WETERS'	
PRINT, SHUTTLE DISPLURITERS  WRITE (5, 100) (XSH (1)  PRINT, SHUTTLE ROTAT  SECONDS  WRITE (6, 100) (XSH (1)  I  WRITE (6, 100) (XSH (1)  I  PRINT (1)  PR	PRINT , SHUTTLE DISPLACEMENTS - WAITE (5, 100) (XSH (J, 1), J=1,5,2)  PRINT , SHUTTLE ROTATIONS - ARC SECONDS   1   1   1   1   1   1   1   1   1	PRINT, SHUTTLE DISPL FETERS I	
PRINT, SHUTTLE DISPLUETERS  WRITE (5, 100) (XSH(J)  PRINT, SHUTTLE ROTAT  SECONDS  WRITE (6, 100) (XSH(J)  IIII	PRINTS, SHUTTLE DISPLACEMENTS - MRITE (5, 100) (XSH (J, 1), J=1,5,2)  PRINTS SECONDS  BRINTING	PRINTS, SHUTTLE DISPL PETERS' 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	
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	1), Ja 1, 5, 2)  10NS - ABC  1), Ja 7, 11, 2)	WRITE (6,100) (XSH (J,1), J=1,5,2)	
	10NS - AG 10NS - AG 10, J=7, 11, 2)	WRITE(6,100)(xSH(J,1),J=1,5,2)	
	10NS - A HC 10NS - A HC 10NS - A HC 10NS - A HC		
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	10NS - AAC 10NS - AAC 17, JB7, 11, 23	•	
	10NS - AAC 10NS - AAC 17, J=7, 11, 2)		
	10NS - ABC 10, J=7, 11, 20	/ •••••••••••••••••••••••••••••••••••••	
	10NS - A BC 11,2=7,11,2) 11,4=7,11,2) 11,4=7,11,2) 11,4=7,11,2)		
SECONDS	1), J=7, 11, 2)	/ PRINT . SHUITLE ROTAT	
##ITEC6,100)(xSH(J,1),J=7,11,2) / 1	1), J=7,11,2)	/	
## ## ## ## ## ## ## ## ## ## ## ## ##	WAITE(6,100)(XSH(J,1),J=7,11,2)  1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1		
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	•,	1001			
YY (NY , 2) = Y (2, YY (NY , YY (	I FAL I FAL I	IF (UDDOT (3,1), EQ. Q. & ND & XRAND, Y(3,1), EQ. C. Q. & CTC37	1		P) • • • • • • • • • • • • • • • • • • •
Y (NY 1) = T (Z; 1) Y (NY 2) = X (NY 2) Y (NY 2)			1 NZ=NZ+1  NZ=NZ+1  1	TZI=TIME  TZI=TIME  CC  I  CC  YZ (NZ, 1) = T(3,1)  YZ (NZ, 5) = XR (5,1)  YZ (NZ, 5) = XR (5,1)  YZ (NZ, 5) = Y (3,1)	CC====================================
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COMMON/THRUST/XTIME(500,2),YTIME(200,2),ZTIME(200,2),IXT,IYT,IZT
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                - THRUST)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 C...INITIAL CONDITION AGAINST THE DEADBAND IN COMMON ULOCK
                   C...ON THE SHUTTLE DUE TO THAUSTER FIRINGS. THE ROUTINE
                                           C...IS DYNAMIC IN THE SENSE THAT IT MONITORS THE SHUTTLE C...ROTATIONS AND INITIATES THE PROPER AXIS SEQUENCE IF C...ANY CR ALL OF THE SHUTTLE ROTATIONS EXCEED THE DEAD-C...BAND LIMIT WHICH IS IN THE COMMON BLOCK.
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 C...ARRIVE HERE IF NO X-THRUSTER IS IN PROGRESS TO TEST
C...THE DEVIATION OF THE SHUTTLE'S X-ANGLE FRC4 ITS
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              C...IF TIME CYCLE FOR X-THRUSTER IS EXCEEDED, SET TX=0.
                                                                                                                                                                                C...IS=1 FOR SOLAR INERTIAL, =C OTHERWISE COMMON/PASS3/ UDEDT(3,1),RK(3,8),RC(3,1),X(40,1)
THE FORCES AND TORQUES ACTING
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           1 SAMPL(1,1)=0.
C...CHECK TO SEE IF X-THRUSTER FIRING IS IN PROGRESS
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         OF IX (=1 FOR + THRUST, = 2 FCR
                                                                                                                                                      COMMON/P4SS4/ S4MPL(12,1),UDIST(3,1),IS,DB
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            Ċ
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        +.052176
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    SAMPL(4,1)=SAMPL(4,1) -.0C2176
SAMPL(6,1)=SAMPL(6,1) +.0T2313
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     C... DETERMINE DIRECTION OF DEVIATION (-,
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  C...CHECK IF DEADUAND LIMIT IS EXCEEDED
                                                                                                                                                                                                                                                                                               COMMON/KEEP/ TX, TY, TZ, TX, TY, IZ, COMMON/ANGLES/ THEX, THEY, THEZ
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         C... SET 1X=1 FOR +VE TPRUSTER FIRING
                                                                                                                                                                                                                                                                                                                                                                                                                                                         C...INITIALLY SET THE SAMPLE TO ZERO
                                                                                                                                                                                                                                                                                                                                                                                                         C. CONVERT THE DEADEAND TO RADIANS
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   XTIME(1X1,2)=TIME
                                                                                                                                                                                                                                      COMMON/PASS2/ 4(8,9),8(8,3)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              SAMPL(4,1)=SAMPL(4,1)
SAMPL(6,1)=SAMPL(6,1)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   SAMPL(3,1)=-6.2E-4
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        AMPL(8,1)=6,2E-4
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        IF(TX.GE,.2)THEN
                                                                                                                                                                                                                                                                  COMMON/CLOCK/ TIME, DT
                                                                                                                                                                                                                                                                                                                                                                               DTCR=3.14159/190.
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    [F(AMGX) 11,12,17
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           ING X=X (21,1) - THE X
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        F(TX.GT.O.) THEN
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             THE VALUE
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   TX=TX+DT
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        60 TO (1
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           GO TO 30
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          00 1 1=1,12
                                                                                                                                                                                                                                                                                                                                                                                                                                      VAL = DB .D TOR
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        1 x = 1
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         C... CHECK
                                                                                                                                                                                                              00000
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C...ARRIVE HERE TO CHECK THE Y-AXIS. FIRST CHECK TO SEE C...IF A THRUSTER FIPING IS IN PROGRESS.

TO IF(TY.GI.D.) THEN
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               C... ARRIVE HERE IF NO Y-THRUSTER IS FIRING TO TEST THE
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   C...ANGY TO ALLOW FOR REQUIRED RATE OF ROTATION.
IF (IS.EQ.1) ANGY-ROSTRED RATE OF ROTATION.
IF (IS.EQ.1) ANGY-ROSTRED FOR TIME
 SAMPL (4,1)= SAMPL (4,1)-. 302176
                SAMP_(6,1)= SAMP_(6,1)+,002318
                                                                                                                                                                                                                          SAMPL (4, 1)= SAMPL (4, 1)+, 002176
SAMPL (6, 1)= SAMPL (6, 1)-, 002318
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            SAMPLIG, 1)= SAMPLIG, 1) + 000263
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  54MPL(6,1)=54MPL(6,1)-200263
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  C. . Y-ANGLE AGAINST THE DEADBAND LIMIT.
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   SAMPL(6,1)=54MPL(6,1)+,33263
SAMPL(10,1)=-2,9E-4
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  SAMPL(8,1)=SAMPL(6,1)-,30263
                                                                                                                                                                 C... SET IX=2 IF -VE THFUSTER FIRING
                                                                                                                                                                                                                                                                                                                                                                                                                                                     YTIME(IYT,2)=TIME
GO TO 12
                                                                                                                                C. . . IF ANGX IS ZERO GO TO Y_AXIS
12 GO TO 30
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 SAMPL(10,1)=-2,96-4
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    SAMPL(10,1)=-2,9E-4
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         SAMPL(10,1)=2,9E-4
                                                                                                                                                                                                                                                                                                                      XTIME CIXT, 1) =- TIME
                                                                                                                                                                                                                                                              SAMPL(8,1)=-6.2E-4
                                                                                        XTINE(IXT,1)=TIME
                                                                                                                                                                                                                                                                                                                                                                                                                   IF(TY .GE . . S 2) THEN
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          YTIME (IYT,1)=TIME
                                     SAMPL (8,1)=6.2E-4
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                F ( ANGY . LT . _ VAL) THEN
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             60 TO (6,7), IY
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    IF (ANGY GT - VIL) THEN
                                                                                                                                                                                                        . IF ( ANGX . GT . V . L) THEN
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               IF (ANGY) 15, 16,17
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 ANGY=X (23, 1) - THEY
                                                                          IXT=IXT+1
                                                                                                                                                                                                                                                                                                     IXI=IXI+1
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          YY=IYT+1
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              [ Y = T Y + D T
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            60 10 32
                                                                                                                                                                                                                                                                                     10 = X
                                                          X=DT
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                60 10 32
                                                                                                             END IF
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                X= 2
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                IY=1
                                                                                                                                                                                     1 X = 2
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                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     03337
0000052
                                                                                                                                                                                   00062
                                                                                                                                                                                                       00063
                                                                                                                                                                                                                                                                                                     02068
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          00000
                                                                                                                                                                                                                                                                                  03067
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```
C...ARRIVE HERE IF NO 2-THRUSTER IS FIRING TO CHECK ANGLE ANGZ=X(25,1)-THE2

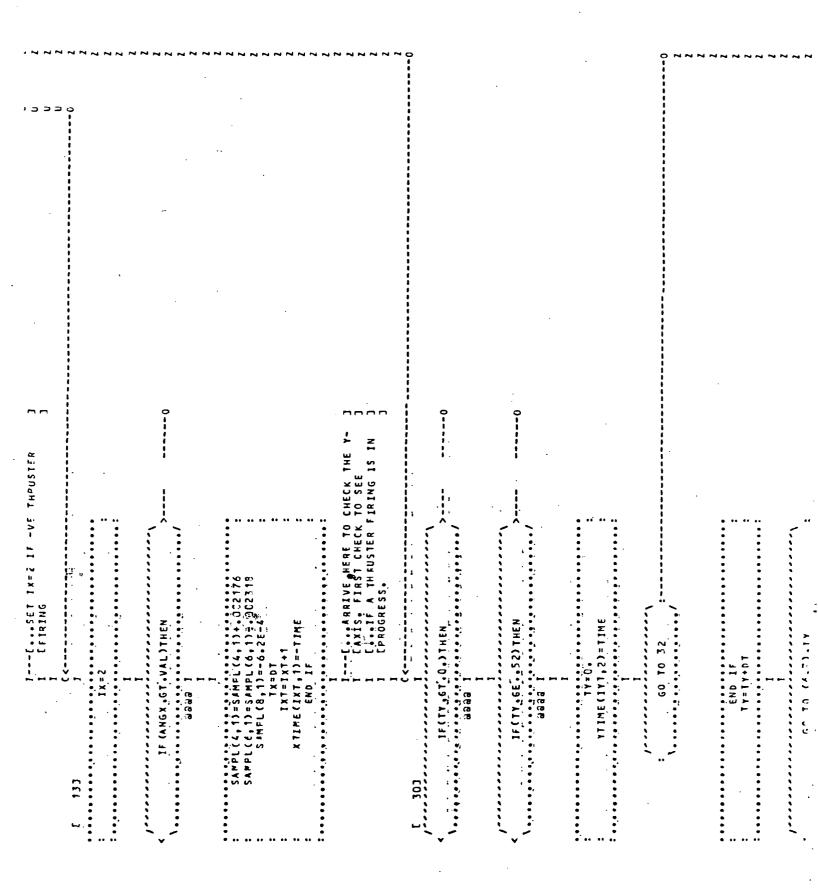
18 IF (ANGZ) 19,20,21
                                                                                                                                                                                                SAMPL(4,1)=SAMPL(4,1)-,000452
SAMPL(6,1)=SAMPL(6,1)-,001004
SAMPL(12,1)=-2,9E-4
G0 TO 33
                                                                                                                                                SAMPL (4, 1) = SAMPL (4, 1) + 000452
SAMPL (6, 1) = SAMPL (6, 1) + 00 0040
SAMPL (12, 1) = 2,9E_4
                                                                                                                                                                                                                                                                                                                          SAMPL(4,1)=SAMPL(4,1)+,000452
SIMPL(6,1)=SAMPL(6,1)+,001034
SAMPL(8,1)=2,9E-4
                                                                                                                                                                                                                                                                                                                                                                                                                                                   SAMPL(4,1)= SAMPL(4,1)-,00C452
Sampl(6,1)= Sampl(6,1)-,0010P4
                                  C...ARRIVE HERE TO CHECK THE Z-AXIS 32 IF(1Z,GT,Q,)14EN
                                                                                   ZTIME(12T,2)=TIME
GO 1C 33
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   ZTIME(12T+1) =-TIME
END IF
RETURN
END
           YTIME (IYT,1)=-TIME
                                               IF(12,6T,0,)THEN
IF(T2,6E,,48)THEN
                                                                                                                                                                                                                                                                                                                                                                                       ZTIME(12T,1)=TIME
                                                                                                                                                                                                                                                                                                                                                                                                                                                                            SIMPL(8,1)=-2,9E-
                                                                                                                                                                                                                                                                                                            F CANGZ.LT.-VAL) THEN
                                                                                                                                      GO TO (9,10), 12
                                                                                                                                                                                                                                                                                                                                                                                                                                        I F ( ANGZ • GT • V ª L ) T HEN
I + I * I * I * I
                                                                                                                                                                                                                                                                                                                                                                            121=121+1
                                                                                                                         12=12+01
                                                                                                                                                                                     60 70 3
                                                                                                                                                                                                                                                                                                                                                               10=Z
                                                                                                                                                                                                                                                                                                                                                                                                              50 TO 33
                                                                                                                                                                                                                                                                                                                                                                                                    END IF
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       ņ
                                                                                                                                                                                                 2
                                                                                                                                                                                                                                                                                       4 4
        000110:
000111.
000112.
                                                                                   001116.
                                                                                                                                               00121.
                                                           000114.
                                                                                                         000118.
                                             93113.
                                                                                                                                                                                                          03126
                                                                                                                                                                                                                                                           .07173.
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    200152
                                                                                                                                                                                                                                                                                                                                                                                                                                                                         100147
                                                                                                                                                                                                                                                                                                                                                                                                              00142
                                                                                                                                                                                                                                                                                                                                                                                                                                     303144
303145
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       000148
                                                                                                                                                                                                                                                                                                             100134
                                                                                                                                                                                                                                                                                                                                                             0317.8
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 100153
                                                                                                                                                                                                33125
                                                                                                                                                                                                                                                                                                                                                                          03139
                                                                                                                                                                                                                                                                                                                                                                                                  30141
                                                                                                                                                                                                                                                                                                                                                                                                                                                               97100
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              000150
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          101151
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	00	60	P.O.
I FORCES AND TORQUES ACTING I FOR THE SHUTLE BUE TO I THRUSTER FIRINGS. THE ROUTINE I THRUSTER FIRINGS. THE SHUTLE I THRUSTER AXIS SEQUENCE IF I T	COMMON/PASSZ/ ACB, B), B(B, B) COMMON/REEP/ TX, TY, TZ, IX, IX, IZ	COMMON/INGLES/ THEX, THEY, THEZ  COMMON/THRUST/XIIME(500,2), YTIME(20C,2), ZTIME(20C,2), IXTY, IXT, DTOR=3,14159/18C,  INC. CONVERT THE DE.  INC. CONVERT	1
•			; ;

· ·		0.		7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7	7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7	1 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2	7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7	7 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2	
	99 99 99 99 99 99 99 99 99 99 99 99 99	A D D D D D D D D D D D D D D D D D D D	TX=0. FERMINE (IXT, 2)=TIME		END IN TAKET OF STREET OF		SAMFL(4,1) = SAMPL(4,1) = 002176 SAMFL(6,1) = SAMPL(4,1) = 002176 SAMFL(8,1) = SAMPL(4,1) = 002176	:	

1	• •• •	IF NO X-THRUSTER 3 TO TEST N OF THE SHUTTLE'3 ITS ITION AGAINST THE3 MON BLOCK		RECTION OF 3	 +VE THRUSTER J	• • •	EADBAND LIMIT IS 3	0	• • • • • •		אַט קט ץ •• אַזוֹא J	# \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$
	ENDIF	-EARRIVE HERE CIS IN PROGRESS CTHE DEVIATIO IS X-ANGLE FROM CINITIAL COND CDFADBAND IN COM	A NGX = X (2 1) 1) = T H E X	COEVIATION (- 0	J[ SET lx=1 FCR 1 CFIRING	I 113 I I I I I I I I I I I I I I I I I	I CENCEEDED  I	IF (ANGX-LT-VAL)THEN  OBSE 1	AMAPPI SAMPI SAMPI	IXT=IXT+1  XTIME(IXT+1)=TIME END IF		[21]

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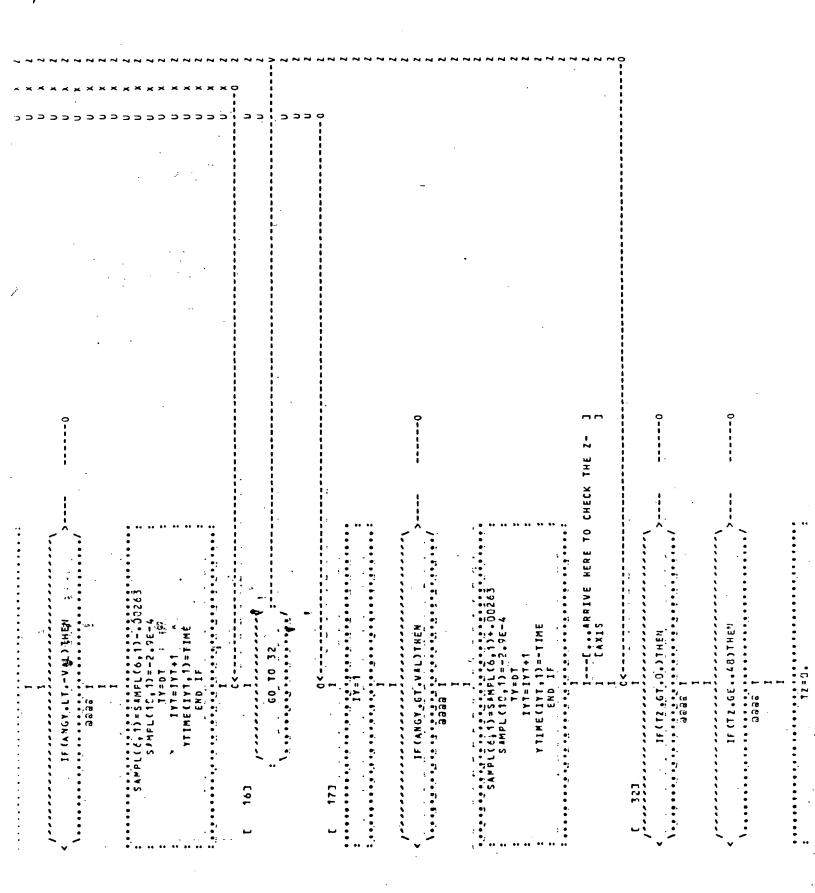


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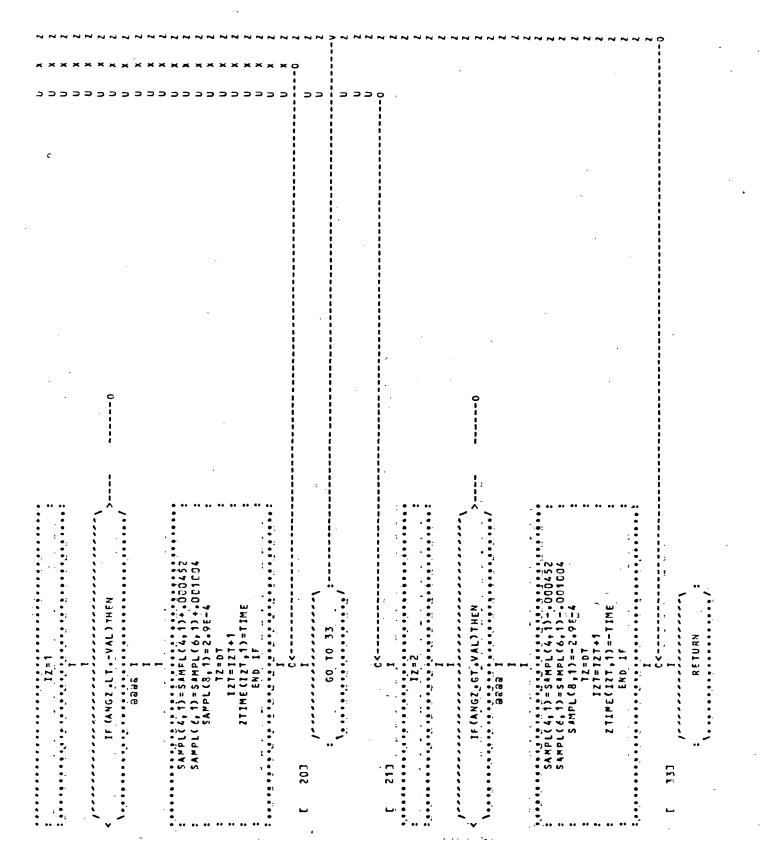


	27 IME (127,2)=TIME  1  1  1  1  1  1  1  1  1  1  1  1  1	END IF TZ=TZ+DT	GO TO (9,10), 12, 5  CO TO (9,10), 12, 5  SAMPL(4,1) = SAMPL(4,1) + 3C0452  SAMPL(4,1) = SAMPL(4,1) + 0C1004  SAMPL(4,1) = SAMPL(4,1) + 0C1004  SAMPL(4,1) = SAMPL(4,1) + 0C1004			END IF  I LIS FIRING TO CHECK ANGLE  ANGZEX (25 1) - THEE  I I I I I I I I I I I I I I I I I I	1 1 3 1
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DODDET.

SUBROUTINE SENSETCKNOISE)

ODDDEZ.

C...SUBROUTINE DEFINES A GAUSSIAN NOISE SIGNAL FCR THE DODDES.

COMMON/RANDOW/ J 4Y

DODDDES.

COMMON/RANDOW/ J 4Y

DODDDES.

KNOISE(1)=NR (ND ISE(3)

CALL RANDN(KNOISE, 3, 0, 1, 2125E-7)

RETURN

ODDDER.

END

SIM

SENSORT

: c

ARAY.FORFLO,S EE.SENSORB/SIM FLOWCH\*RTED BY FORFLO /x833/ ON 13 AUG 81 AT 38:05:24

Ç,

SUBROUTINE SENSE CKNOISE)

JOJUNS.

C...SUBROUTINE DEFINES A GAUSSIAN NOISE SIGNAL FOR THE JOSUNS.

JOJUNS.

COMMON/RANDOM J MY

DODUNS.

TORNON/RANDOM J MY

DODUNS.

TORNON/RANDOM J MY

DODUNS.

TORNON/RANDOM J MY

TORNOM RANDOM J MY

TORNOM RANDOM J MY

TORNOM RANDOM J MY

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DODUNG.

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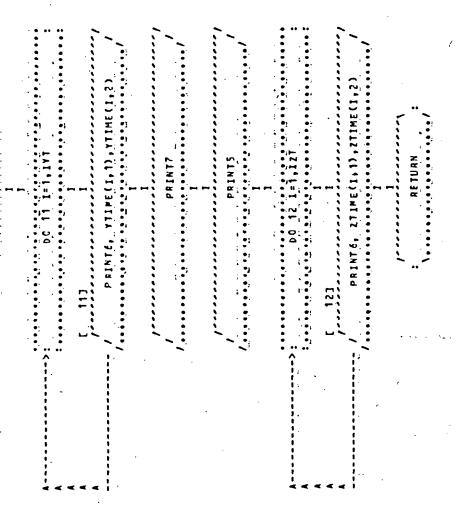
TORNOM RANDOM J MY

TORNOM RANDOM J MANDOM J

SIM

SENSORR

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C... PROGRAM 10 QUTFUT THE TIMES OF THE THRUSTER FIRINGS C... ACCUMULATED IN SAMPLE AND SAVED IN COMMON/THRUST/
                                                                                                                                                                                                                           DO 11 I=1,IYT
PRINTS, YTIME(1,1),YTIME(1,2)
PRINT7
                                                                                                                                                                              DO 13 1=1,1XT
PRINT6+ XTIME(1,1),XTIME(1,2)
                                                                                                                                                                                                                                                                          DO 12 1=1,127
PRINT6, 2TIME(1,1),2TIME(1,2)
SUBROUTINE SUMMRY
                                                                                                                 FORMAT (" ",
                                                                                          FORMATIC
                                                                                                        FORMAT(" -
                                                                                                                                                                   FORMAT (//)
                                                                                                                                           PRINT2
                                                                                                                                                      PRINTS
                                                                                                                                                                                                     PRINT7
                                                                                                                                                                                                                 PRINTA
                                                                                                                                                                                                                                                                PAINTS
                                                                                                                                                                                                                                                                                                 003026.
                                                         300000
3000000
                                                                                                                                                                                                                            050000
                                                                                                                                                                                                     000013
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C...WHICH IS IN THE COPMON BLOCK
C...ROUTINE CALLS SUPRCUTINE SENSEB TO DETERMINE MEASUREMENT NOISE
COMMON/PASS3/ UDDOT(3,1),RK(3,2),RCOM(3,1),X(40,1)
DIMENSION W1(3,1),RJ(3,3),XNJISE(8),XC(8,1)
                 C... ROUTING COMPUTES THE VALUE OF U-BOUBLE-BOT,
                                                                                                                                   XC(II, 1) = X(II, 1) + XNOISE(II)
CALL MYMLT (RK'XC, M'), 3, 8, 1, 3, 8)
CALL MXSUB(RO, L1, UDDO1, 3, 1, 3)
RETURN
                                                                                                         CALL SENSEBCXNCISE)
DO 1 11=1,9
```

# IX.E. Shuttle Drift/Deadband

465+001-.8143+000 .1991+0u1-.7140+0uc +309-.1426+301-.4163+001 +3u0 -8913+030-1484+0u1 131+001--1469+000 01 .1562+001 .5165+000 00 -1593+001-.5105-00 .1398+001-.1378+00 .8040+000-.2C44+0u1 +000 -2085+000--2710+00 :-JC1-,3883+DUO-,3378+DU +JUO-,4866+OUC-,4C48+DU +000-.1586+001-.4719+00 00--2009+001--4859+00 100-18440+000-13504+00 30-, 2538+300-,2928+00° -.1216+AUG .3146+366-.2155+00° +001-,8364+000 ..3382+000 .1706+001 +000-,2638+000 01 .3579+000 000+7874,000 000+0296 000+ .9925+000 .1076+001 +000--1451+001 100-11510+001 MEXIMUN VALUE .5050+001 11M1.1UM V4.UE .=.5:164+101

Various TING VERSIES TIME PERSUS TIME A PLUT OF FIVE 0 0 CONVERTIBLE OF PLUT OF CAR 3F 143 1.1. : 1 71 CURVE 35 30×00

+000 .1456+001 .6094+000 |+100 .2366+000-.7046+000 9366+000-.900+906 --8293+000-1644+001-1352+000 ;+000′-1350+001-.1431+001 |+000-.7471+000-;2086+001 |+000-.1495+000-;2747+001 -.1494+061-.9630+006 .8477+000--4665-001 -001 .2470+000-.2645+000 .5055+000 2170+000-.1957+001-.7806+000 3+000-,377+000-,1366+00 2+000-,9952+000-,2031+00 +000--1616+001--2700+00 +000--1981+001--3371+00 +000-.7713+000-.4725+00 +000-.1717+000-.4857+00 +000 .4243+000-.4189+00 017+001-.3526+00 034-001 ;1605+001-,2866+00° 546+000 ,2004+001-,2210+00 1422+001-.1557+00 .2399+00 -001 .4430+000-.3412+00 030+001--4682+00 .1613+001-.4758+00 .1989+001-.4825+00 .2834+000 .1422+001-.4158+00 .8976+300 .8492+000-.3497+0u .6996+300 .2714+000-.2940+00 .9286-301-,3116+800-,2169+80 •1202+0Ü +000--1374+001--4046+ -.5193+300-.900C+000-.1543+ .9215+000 .6799+700 .1533+001 .6494+000-.3466+000 1557+000-4149+000 7678+000--1027+001 .7952+000 4517+000 .1925+000 675+000-.9442+000 00--2046+001 749+000--1441+001 00--8212+000 +000 -1614+001 -.1167 -

.2010+001-.3528-001 -.3401-001 .3627+000-.8799+000 6520+000=-4522+000+99893+000 .7012+000 ,2591+000 .1168+001 .5697+000 .4223+300 .1446+001-.6468+000 .8754+000-.1265+0u1 -.4115-001-.2857+000-.2521+001 152+601 .5803+000-.2096+000-.2655+000 .9290+000-.1500+001 .4109+000-.4694+001 --2486;001;1754+000-,4887+001 .2981+000-11990+00 .1489+001-.2127+001 2033,4001-.2759+00 .6649+000-.7679+000-.4221+00 345+63 761+000-3159+00 +001--3863+00 00+7667 1565+001-.3398+00 293+300-.1631+001-.2263+00 00+5664 07--000+6066 9457+000-,1038+001-,16 -.9224+000-.1367+001-.35 ,1268+001 .1608+001 010+001-.7880+000 000+0959\* 000+6676\* -.4831+000 .4539+000-.1048+000 .1044+001 .1217+301 .261+000-.1372+001 .6391+000 -.1451+000 :4728+000 .8939-301 --8387+200--1061+0u′ -.7608+300-.1646+001 244+300--1963+00 .1781+00 .1213+00 -.6660+000-.1722+001 .1042+001-.6890+00( -.9293+000-.1122+00 01-,1877+00 -.3358+000-.5286+0 -.7607+909 -.8294+000 .5664+000 000+24599 8319+000 .3635-301 3595+000 2513+000 .1031+001 -.6553+000 -.9423+NOO \_ ر. با د ... 120+03 (Pr+) 00.0 + 0.0 1220+07 370+07 ...+0 20 O+ ). 550+05 34.74.5

.8134+000 .1443+001 .2566+001 -.1057-7001 .1507-801-.1771-001 -.4943-800 .2048-8011-.1115-801 .1649-808 .1495-801-.4655-800 .4494+001 .6562+000 .4518-001 .9222+000 .9383-032-;5782+000 .2988+000 -,6444+000-,1208+001-,3310+000 -,9453+000-,1844+001-,9670+000 -,2823+000-,1747+001-,1609+001 .9159+630-.2433+001 .37.96+000 .1772+000 -.8446+000-.2048+001-.1216+00C -.1957+000-.1418+001 .5C35+00C .6271+000 .7796+006-.4632+006 .3182+000-.3162+601 .2663+001 .1539+001 .3745+000-.1114+001-.2258+001 .1023+001-.4875+000-.2913+00 .5714+000 .1331+000-.3574+001 .7475+000-.4241+0U1 .1642+001-.3998+00 .1021+001-.3337+001 \*1037+001 | 3948+000-\*2682+001 1143+001 243+00 944+001 .5754+00 .2150+00 1356+001-,4914+00 .1958+001-,4665+00 .5410+000-.2378+000-.253+00 -.9759-001-.8765+000-.1390+00 -.1521+001-.7526+00( 1736+00 .5344+00 00+575 .3541+00 .4132+0u .4716+00 . 00 + 688 7 .4323+0u .3751+00 00+870 2.59+00 .3352+00 .3174+00 --1037+001--1646+001 .1051+001-.1384+000 .5080+000 .4928+000 -. 5288+JQD-. 1905+001 -.3667+000 -1877+001 .9799+000 .3627-001 .2610+000-.1312+001 .9056+000-.6913 4733+000 -.7422+000 <u>.</u> ... •

596+001-.2264+001 \$43+000 .3774+000-.3530+0U1 467+003-.8616+000-.4816+001 278+000-.1489+001-.4779+001 -.9071+003-.2052+001-.4153+001 -.6691+000-.1474+001-.3532+001 •1829-001-.8580+000-.2916+001 •7009+009-.2466+900-.23C4+001 .8828+000 .3601+000-.1698+001 .9621+000-.1096+0u1 .1559+001-.4584+000 .00-8576 .6826+000 98956+000 .3026+000 .8048-001-.6792+000-.2941+000 ..6147+030-.1327+001-.8943+000 --2451+000--1615+001--2105+001 .3857+000 .3169+000-.3547+001 \*9181+000 \*7960+000-3678+001 \*6507+000 \*4346-001-.2432+001 -.7491;+007-.1955+001-.5117+000 **-781-11529+881 .1231+888** .7553+500 .1785+001 .00+76a2\*-00C+1686\* +001--2396+000--4170+00 .2071+00. --9669+000--1978+001--1498+00, .4733+000-.9675+000-.2716+03 .9542+000-.4568+001 -.6193+307--1267+501--1149+501 .2012+003 .1266+00 1945+00 .2420+00 .2591+0n 3557+00 4 1 19 + 00 00+0767 00+7227 8 04 + 00 .2652+00 1-.3237+000-.3330+00 588+001-.5028+00. 010+001--4379+00. .1781+000 .1357+001-.3727+00 --3290-001--6219+000-1189+00 .2035+001 +000 +1447+001 7721+000-.3503-001 .8438+000 6394+000-,3755+000 364+000 .4796-001-.9917+000 -.1673+000-.1356+001 .5049+000-.7317+000 .1056+001-.1110+030 000+9 .1118+001 .1727+001 --7397+000--1612+001 .8437+000-.1985+001 -.1065+001 .2032+000 17:24:374 40.4 100+004 554+17 5 ro • 43.045 .+(97 613+ 563 79 6.

.4282+700 .1840+001 .5054+900 -.1337+881 .8189+388-.5527+688 .1074+NU1 .1752+NU1-.1253+9U0 -.5235+900 -1381+000 -8227-CU1 .1432+001-.1189+001 -.1743+001-.1435+000-.2021+001 .5040+001--1827+CO. .1549+901-.2466+00 .9309+200-,3107+00 .3127+333-33749+60 .5297+300-.1548+001-.4558+00 .1028+001-.2034+c01-.3922+00 .2643+700-.1410+0U1-.3287+DU -.5022+000-.7765+0u0-.2654+0u --3228+000 .4889+000-.1368+00. -.318m+n00 .1189+701 .1135+00 -.1027+001-.3065+000-.4392+00 -.2492+000-.9269+000-.5030+00 .1121+901-.7565+ 711+701--1255+001 2380+000-1905+001 .5742+300-.1599+001 1024+301--1062+001 000+2924-000+4 -.1952+001 .5369+000 233+600--0048+600 -.5057+000-.1150+000 .2424+000-.7672+000 .2117+788 .3059-881 -.2576+000 000+7857\* -.5308+00G .4038+000 .5285+330 .1033+001 0

THOMETER	Sharrida Ego	4" Defede of	18.7 × 7. 6			
-16.JT		193.00	•		: (	+577.5
-15.27	-03.37 -33.41	<del>-</del> 275.57	375.47 375.40	-445.3I	560,79 562.79	717.7
-16.43	120.60	-225.83	375.47	-447.33 -447.23	565.19	710.91
-16.07	120.27	-226.53	335,63	-447.43	563.39	711.1
-16.87	120.40	-226.20	335.31	-447.63	563.39	711.35
-17.00	120.60	-226.49	306.00	-447.83	-597.79	711.51
° -17.30	123.83	-226.60	376.20	-447.03	-597.99	711.75
-170	121.00	-226.33	306.47	-443.20	-599.19	711.0
-17.00	121.20	-227.30	375.62	-445%.40	-393.39	712.11
-17.87	151.47	-227.20	326.30	-448,67	-598 59	712.3
<u>-</u> 1∂.∂0	121.63	-227,45	37.00	-448.83	-593.79	712.51
-15,27	121.30	-227.63	337.20	434.42	-598,99	712.71
-18.47	122,00	-217,00	337.47	484.53	-599.19	712.91
-13.95	122.20	-238.07	337+60	484.60	<del>-</del> 599.•59	715.1
-10.87	102.40	-225.20	337.60	435,00	-579.57	713,31
-19.33	102,50	-228,49	335.10	455.20	-599,79	713+51
-19.23	122.30	-228.30	37 <i>8</i> [• 20	485.47	-529.99	713.7
-19.40 -19.60	123, 13	-223.80	<b>-</b> 371]•33	435.62	−50 j <b>. 1</b> 9	713.09
56.23	123, 20	-229.33	<u>-</u> 371,20	485.80	<b>-</b> 500 <u>/</u> .39	714.1
50.47	123,47	262.20	-371.40	486,•9 <b>0</b>	-600,59	-747.7
50.60	123.650	262,40	-371.60	486.2 <u>2</u>	-500,79	-747.3
50.82	-154.50	262,60	-371,80	406.41	-610.99	-743 <b>.1</b>
51.00	-154-87	262°•30	-372.00		5∑ <b>ó</b> . 17	<b>-748.3</b>
51.25	-155,00	263,33	-372,20	435, 37	575.39	
513	-155.20	263,20 263,40	+372,40	437,00	676,57 675,79	-743.7 -745.9
51.57	-155,40 -175,67	263.49 263.69	-372 +60	487.20	5. 5. 5. 5. 5. 5. 5.	-749.9 -749.1
51.37	-155.3°	263.37	-372,430 -373,400	487°.40	577.19	-749.3
52.00	-156.33	264.33	-373,20	487,60 -523,00	527.39	-749.5
50.27 50.47	-156.23	264.20	-373.43	-523, 20	537.59	749.7
52.47	-156.40	264,40	-373.6°	-523.43	637.73	-749.9
52,50	-150.03	264.67	-373.37	-523.60	617.99	-750+1
52,37	-156.37	264.37	-374.77	-573.80	578.19	-750.3
53,97	-157.33	265.00	-374.30	-524.90	558.39	-750.5
53.47 55,47	-157,23	265.20	405,40	-524.20	57.8[•59	-75).7
33,43	-157.43	265,40	408,60	-534.43	638,77	-770.9 703.7
33.67	-157.67	265.63	478,80	-524,53	638,99	773.7
E3.37 54.00	-157.87	-298,.30	479.00	-524,80	639 <b>,</b> 19	733.9
34.632	-158.07 -158.27	-299,23 -299,23	409.20	<del>-</del> 525.00	67.9°±3.9	704.1
-84.80 -85.00	-158,20	-299,27	400,40	-515.20	679.59	7-4.3
700+07	139.40	-299,40	40.9°•60	-535,40	-673, 79	784.5
-05.27 -85.47	189.60	-299,50	409.30 410.00	-525,60	-574,19	734.7 734.9
-85.67	139.37	-299,30	410.00	-525-80	-674.39 -074.59	
-35.37	190.07	-300.00	410.27	-536,00	-074.79	735 <b>.</b> 1 705 <b>.</b> 3
-(6.37	190.20	-3001.23 -3101.40	4107	-506.20	-674.99	7.5.5
-86.23	190.43	-3.0,40 -300.00	417.53	560.3?	-575.19	785.5 785.7
- * 5 · - I	193.33	-300.30	410.33	550.59	-675.39	705.9
-86.35	190.30	•		550,79	-075.59	735.1
+ā5.5Ω	191.03 191.23	-301.20	411.20 411.40	569.99 561.19	-373.79	77.6.
-67.00	191.43	-371.40	411.63	561•1∼ 561•39	-675.99	77.6.3 705.5
-27.27	191.63	-301.60	-445,50 -445,50	561•39 561•59	-575.19	776.7
-87,40	191,33	-301.30	-445.33	561.79	-576.39	785.9
-37.50	192.00	-302.00	-445.37	561.99	<del>-</del> o76.59	757.1
<del>_</del> 07.80	192.27	-302.20	-446.23	552 <b>.</b> 17	-575.79	727.3
_83.00	192.40	334.63	-445.43	562.37	-373.99	-370.1
	192.60	354.80	-445.60	562.59	-677.19	±600.0•0

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THRUSTER SUMMERY FOR I. DEGREE DERIGHND
  -T2.33
-T2.37
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              238.20
                                          659.79
                                                      -350,50
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              278.40
                                          570,90
  -72.47
-72.60
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                           -452.00
              273,63
                                                      -369.79
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                                          657.99
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  -33.60
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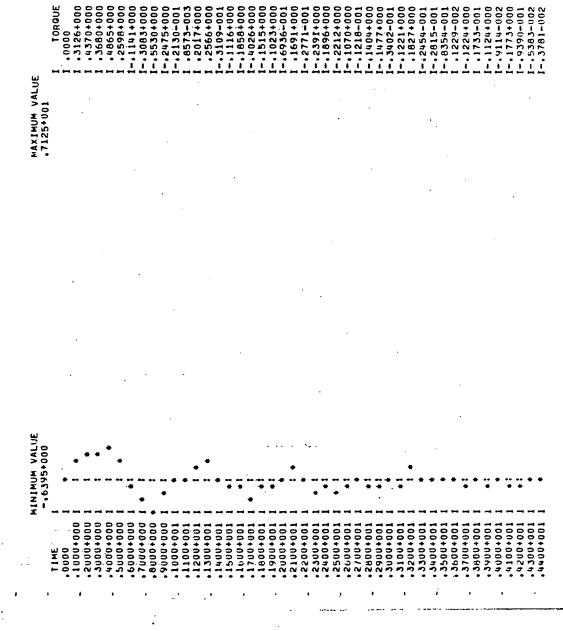
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                 254,40
                                   547.79
-80,60
                 234.60
                                  -704.39
_00.80
                 234.80
                                  -784,59
-81.00
                 235.00
                                  -76.4.79
-91%23
                 235, 20
                                  -784,99
-81.47
                 23.5%+3
                                  -755.19
<u>-01,60</u>
                235.60
                                   765.39
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                                  -705%59
-82,00
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                                  -705.79
-82.80
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                 545.79
                 545-99
                 546.19
                 546.39
                 546.59
                 546.79
                 546.99
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547,19

## IX.F. <u>Simulation Results</u>

IX.F.1. Boom Deployment Sequence
 Figures F1 - F43

DATA FOR THE X-AXIS CURVE '. IS A PLOT OF TORQUE VERSUS TIME



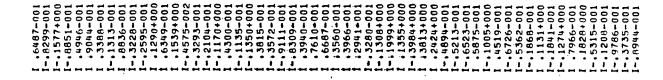
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10020+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 | 1000+002 |

| -1689+000 | -1689+000 | -1686+000 | -1686+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1688+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000 | -1678+000

1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 | 1650+002 |

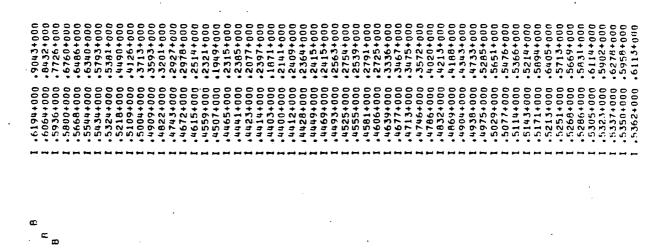


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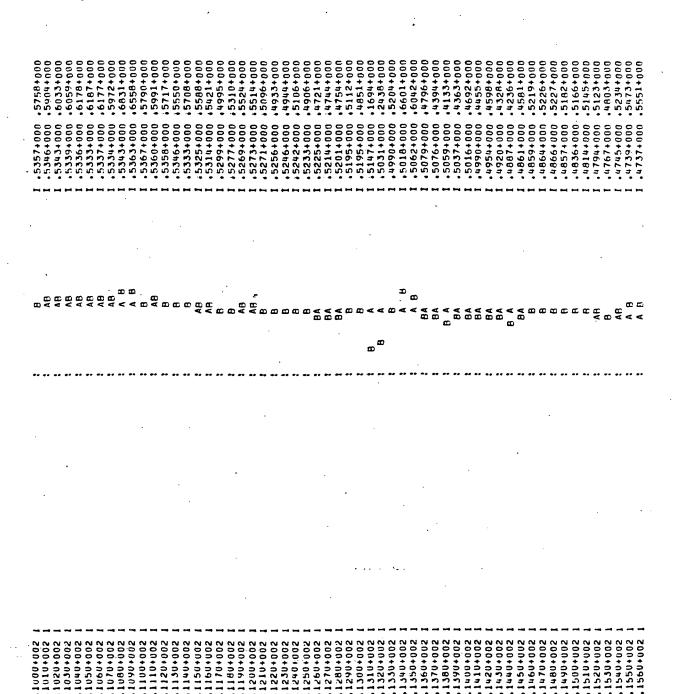
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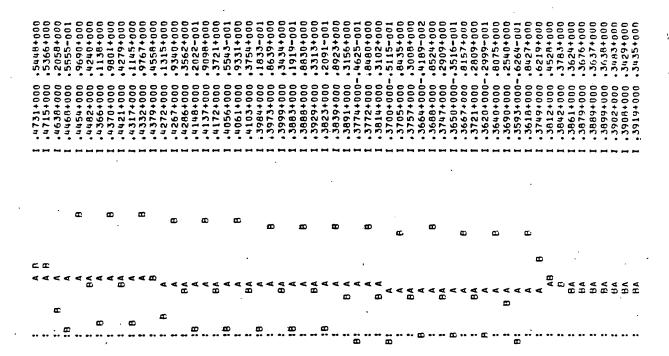
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CURVE '8' IS A PLOT OF BASE VERSUS TIME
CURVE '8' IS A PLOT OF TIP VERSUS TIME



4500+001 | 4500+001 | 4500+001 | 4500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001 | 44500+001



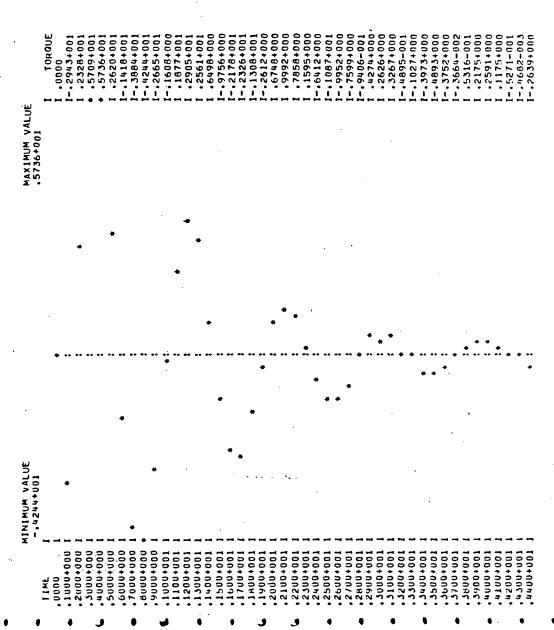


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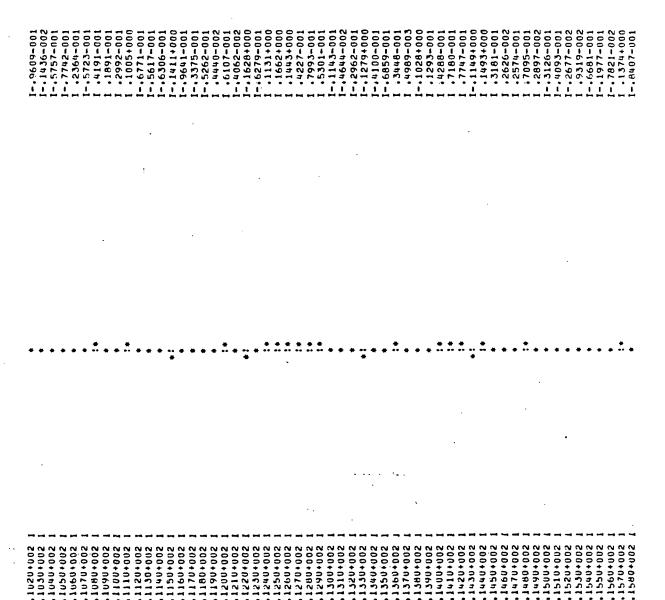
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DATA FOR THE Y-AXIS

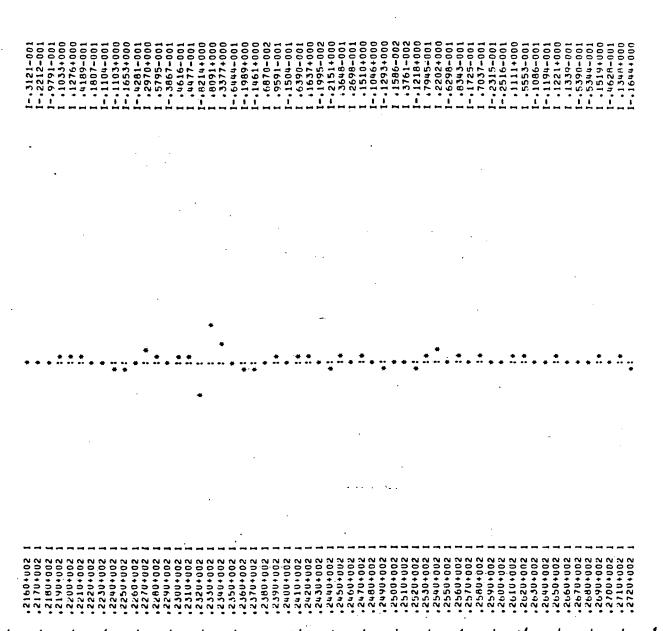
CUMVE '+' IS A PLOT OF TORQUE VERSUS TIME



| . 1894+000 | . 3887+000 | . 3887+000 | . 1894+000 | . 1894+000 | . 1895-001 | . 1595-001 | . 1595-001 | . 1595-001 | . 1595-001 | . 1998+000 | . 1995-001 | . 1995-001 | . 1995-001 | . 1995-001 | . 1995-001 | . 1995-001 | . 1995-001 | . 1995-001 | . 1995-001 | . 1995-001 | . 1995-001 | . 1995-001 | . 1995-001 | . 1995-001 | . 1995-001 | . 1995-001 | . 1995-001 | . 1995-001 | . 1995-001 | . 1995-001 | . 1995-001 | . 1995-001 | . 1995-001 | . 1995-001 | . 1996-001 | . 1996-001 | . 1996-001 | . 1996-001 | . 1996-001 | . 1996-001 | . 1996-001 | . 1996-001 | . 1996-001

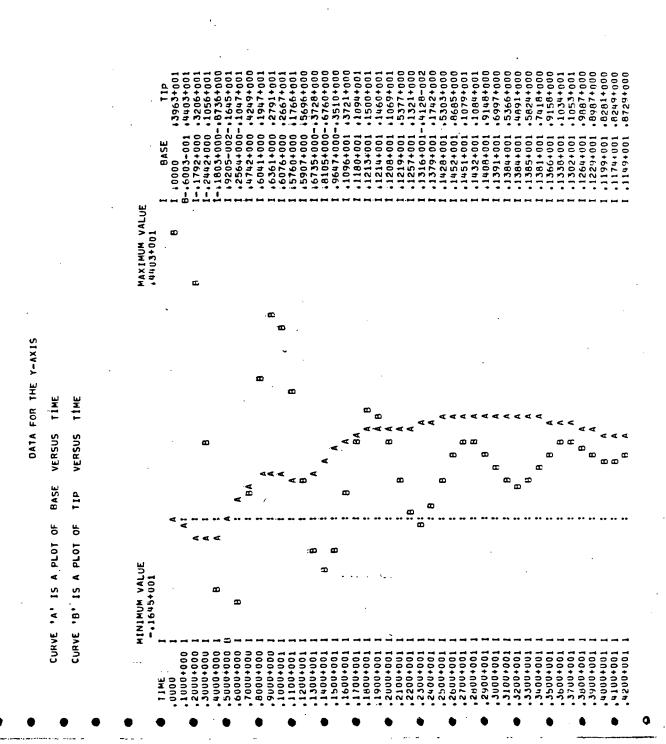


11594+002 11610+002 11610+002 11620+002 11620+002 11620+002 11700+002 

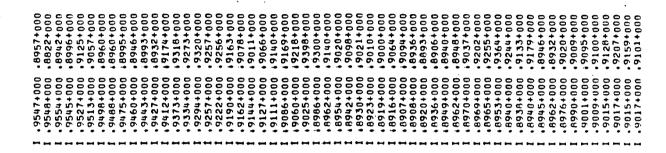


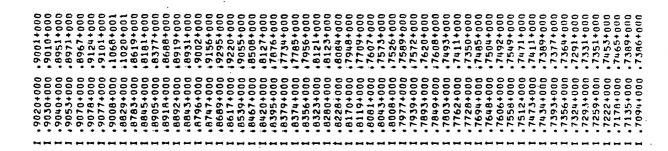
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- 1501-001
- 1501-001
- 1501-001
- 6837-001
- 6830-001
- 6830-001
- 6840-001
- 6840-001
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2750+002 2750+002 2750+002 277

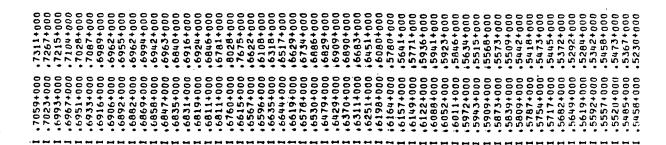


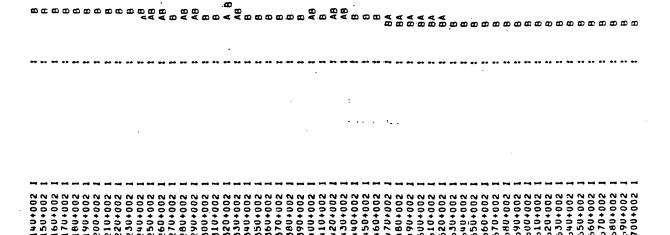
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1.1026+001 .1013+001
1.1025+001 .1055+001
1.1029+000 .1022+001
1.9960+000 .1022+001
1.9952+000 .9933+000
1.9152+000 .9945+000
1.9152+000 .9945+000
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DATA FOR THE Z-AXIS CURVE \*\*\* IS A PLOT OF TORQUE VERSUS TIME

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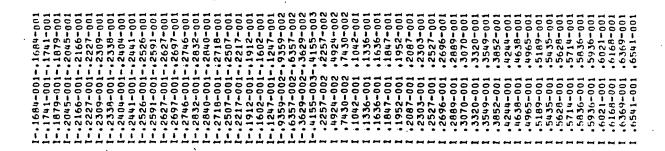
1940+002 1940+002 1950+002 1950+002 1950+002 1990+002 2000+002 2010+002 2010+002 2010+002 2010+002 2010+002 2010+002 2010+002 2100+002 2100+002 2100+002 2100+002 2100+002 2100+002 2100+003 2100+003 2100+003 1840+002 1850+002 1860+002 1870+002 1880+002 1890+002 1900+002 1910+002

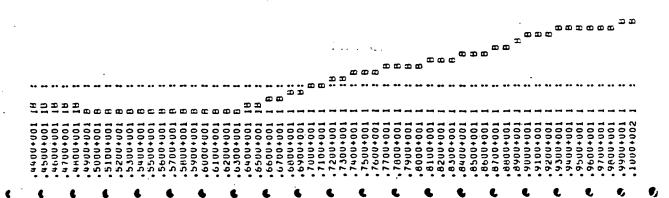
2390+002 2400+002 2410+002 2420+002 2270+002 2280+002 2630+002 2250+002 2260+002

-.3106-002 -.1377-002 -.13608-002 -.1859-004 -.1859-002 -.1864-002 -.1844-002 -.18412-002 -.18412-002 -.2891-002 -.2891-003 -.2498-003 -.2498-003 -.2414-003 -.3287-002 -.3287-002 -.3284-003 -.3287-002 -.3284-003 -.3287-002 -.3284-003

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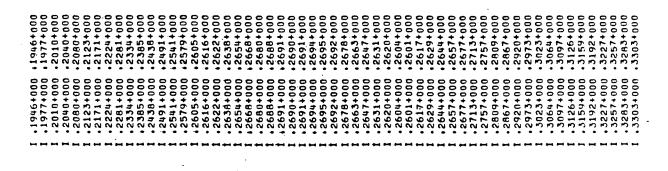
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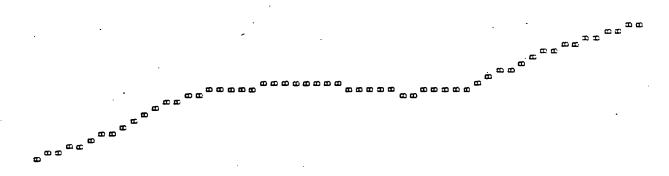




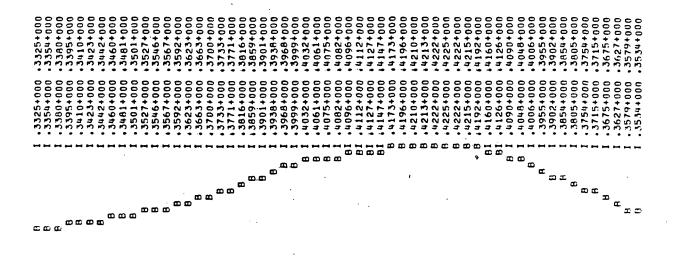
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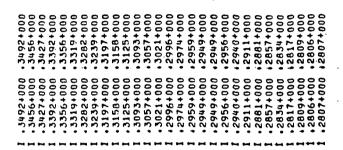




1580+002 1550+002 1550+002 1550+002 1550+002 1750+0



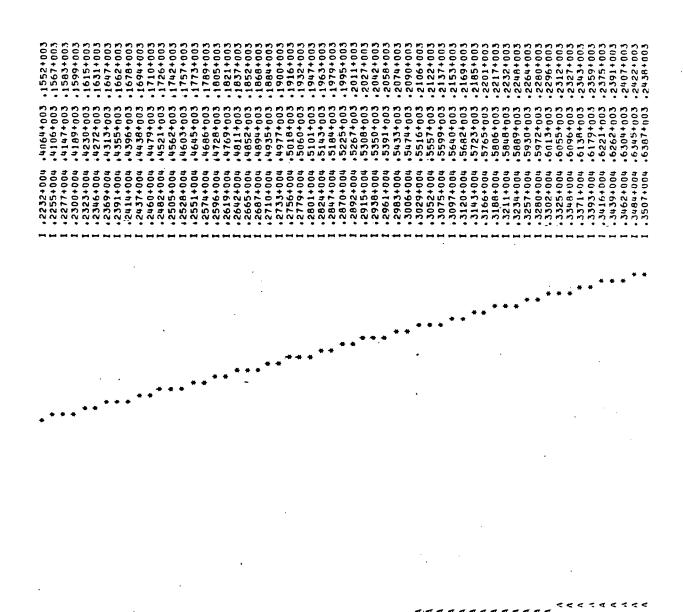
22160+002 22140+002 22140+002 22240+002 2230+002 2230+002 2230+002 2230+002 2230+002 2240+002 2250+002 22



SHUTTLE ROTATIONS

CURVE '+' IS A PLOT OF THETAX VERSUS TIME
CURVE 'A' IS A PLOT OF THETAY VERSUS TIME
CURVE,'B' IS A PLOT OF THETAZ VERSUS TIME

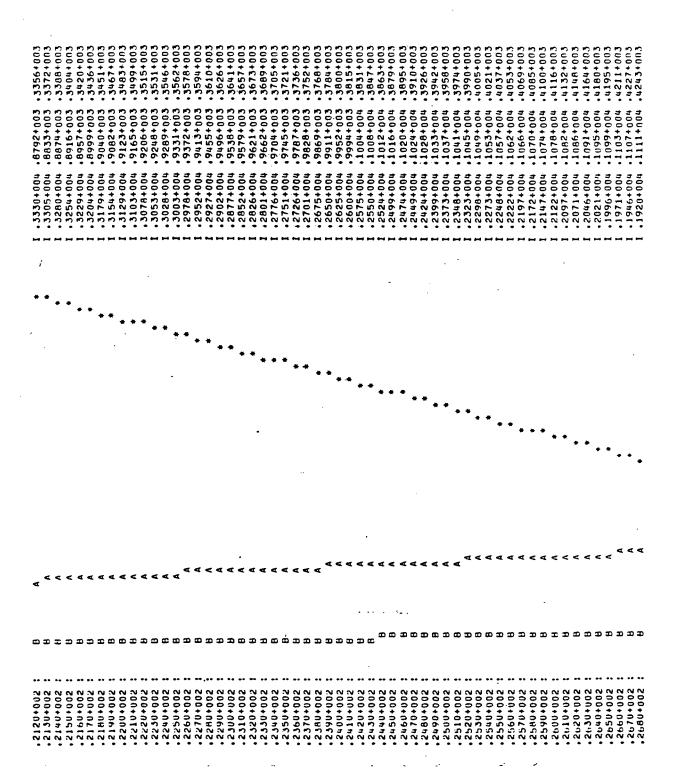
.3193+003 .3235+003 .3069+003 .3318+003 3359+003 4023+003 2986+003 .3152+003 3401+003 .3442+003 .3484+003 .3525+003 .3567+003 .3608+003 .3650+003 .3691+003 .2027+004 .2050+004 940+004 959+004 9814004



13290+002 1310+002 1310+002 1350+002 1350+002 1350+002 1350+002 1350+002 1410+002 1410+002 1450+002 1450+002 1450+002 1450+002 1450+002 1450+002 1450+002

| .3530+004 .6428+003 .2454+003 | .3553+004 .64776+003 .2470+003 | .3553+004 .6511+003 .2470+003 | .3553+004 .6511+003 .2470+003 | .3562+004 .6511+003 .2502+003 | .3562+004 .6511+003 .2502+003 | .3562+004 .6511+003 .2502+003 | .3562+004 .6511+003 .2502+003 | .3562+004 .6511+003 .2502+003 | .3562+004 .6511+003 .2502+003 | .3562+004 .6511+003 .2502+003 | .3562+004 .6511+003 .2502+003 | .3702+004 .6502+003 .2502+003 | .3702+004 .6502+003 .2502+003 | .3702+004 .6502+003 .2502+003 | .3702+004 .7702+003 .2502+003 | .3702+004 .7702+003 .2702+003 | .3802+004 .7202+003 .2702+003 | .3802+004 .7202+003 .2902+003 | .3802+004 .7202+003 .2902+003 | .3802+004 .7202+003 .2902+003 | .3802+004 .7202+003 .2902+003 | .3802+004 .7202+003 .2902+003 | .3802+004 .7202+003 .2902+003 | .3802+004 .7702+003 .2902+003 | .3802+004 .7702+003 .3902+003 | .3802+004 .7702+003 .3902+003 | .3802+004 .7702+003 .3902+003 | .3702+003 .3902+003 | .3702+004 .7702+003 .3902+003 | .3702+004 .7702+003 .3902+003 | .3702+003 .3002+003 | .3702+004 .7702+003 .3002+003 | .3702+004 .8002+003 .3102+003 | .3502+004 .8002+003 .3102+003 | .3502+004 .8002+003 .3102+003 | .3502+004 .8002+003 .3102+003 | .3502+004 .8002+003 .3102+003 | .3502+004 .8002+003 .3102+003 | .3502+004 .8002+003 .3102+003 | .3502+004 .8002+003 .3102+003 | .3502+004 .8002+003 .3102+003 | .3502+004 .8002+003 .3102+003 | .3502+004 .8002+003 .3102+003 | .3502+004 .8002+003 .3102+003 | .3502+004 .8002+003 .3102+003 | .3502+004 .8002+003 .3102+003 | .3502+004 .8002+003 .3202+003 | .3502+004 .8002+003 .3202+003 | .3502+003 .3202+003 | .3502+003 .3202+003 | .3502+003 .3202+003 | .3502+003 .3202+003 | .3502+003 .3202+003 | .3502+003 .3202+003 | .3502+003 .3202+003 | .3502+003 .3202+003 | .3502+003 .3202+003 | .3502+003 .3202+003 | .3502+003 .3202+003 | .3502+003 .3202+003 | .3502+003 .3202+003 | .3502+003 .3202+003 .3202+003 | .3502+003 .3202+003 .3202+003 .3202+003 | .3502+003 .3202+003 .3202+003 .3202+003 .3202+003 .3202+003 .3202+003 .3202+003 .3202+003 .3202+003 .3202+003 .3202+003 .3202+003 .3202

1155004002 | B | 155004002 | B



1895+004 1115+004 4259+003 11895+004 1289+003 1180+004 4289+003 1184+004 4289+003 11895+004 4289+003 11895+004 4289+003 11895+004 42895+003 11895+004 42895+003 11895+004 42895+003 11895+004 42895+003 11895+004 42895+003 11895+004 42895+003 11895+004 42895+003 11895+004 42895+003 11895+004 42895+003 11895+004 42895+003 11895+004 42895+003 11895+004 42895+003 11895+004 42895+003 1185+004 42895+003 11895+004 42895+003 11895+004 42895+003 11895+004 42895+003 11895+004 42895+003 11895+004 42895+003 11895+004 44895+003 11895+004 44895+003 1185+004 42895+003 1185+004 42895+003 1185+004 42895+003 1185+004 42895+003 1185+004 42895+003 1185+004 42895+003 1185+004 42895+003 1185+004 42895+003 1185+004 42895+003 1185+004 42895+003 1185+004 42895+003

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SUMMAPY OF THRUSTER FIRING TIMES

NEGATIVE ON TIME IDICATES -VE THRUST SEQUENCE

15.85 16.10

16.45 16.70

17.05 17.00

17.05 17.00

17.05 17.00

17.05 17.00

17.05 17.00

17.05 17.00

18.85 18.80

18.85 18.10

19.40

19.45 19.40

19.45 19.40

19.45 20.30

20.05 20.30

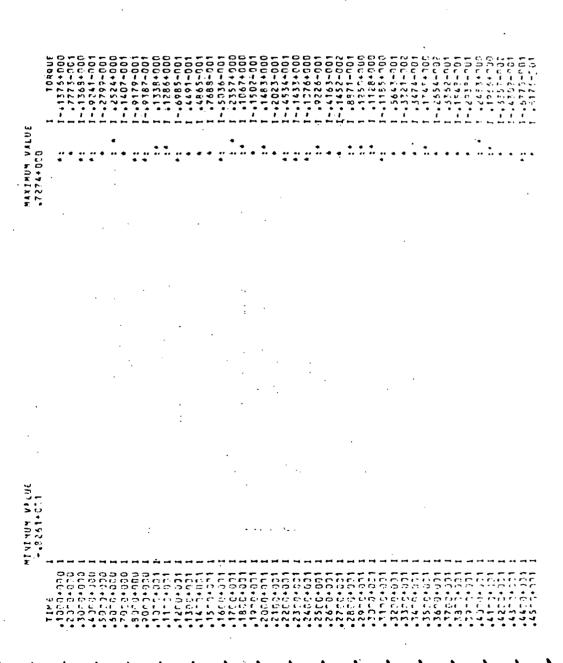
20.05 20.30

20.05 20.30

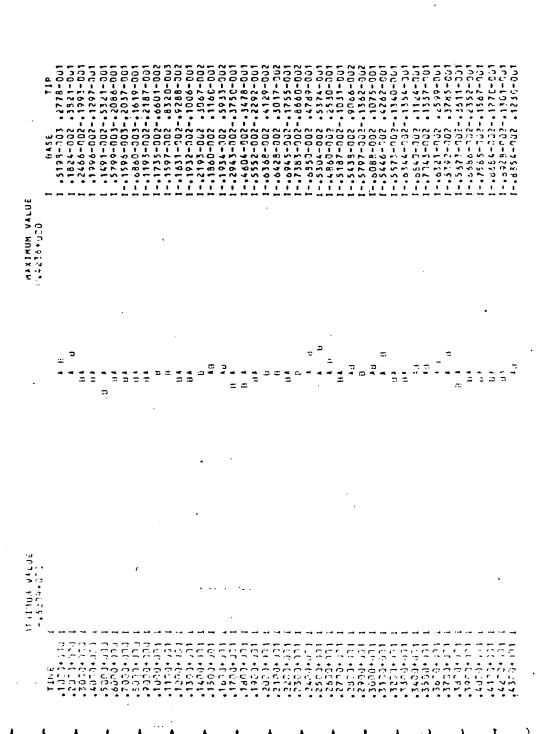
20.00 .00

# IX.F.2. Roll Axis VRCS Disturbance Responses

Figures F44 - F61



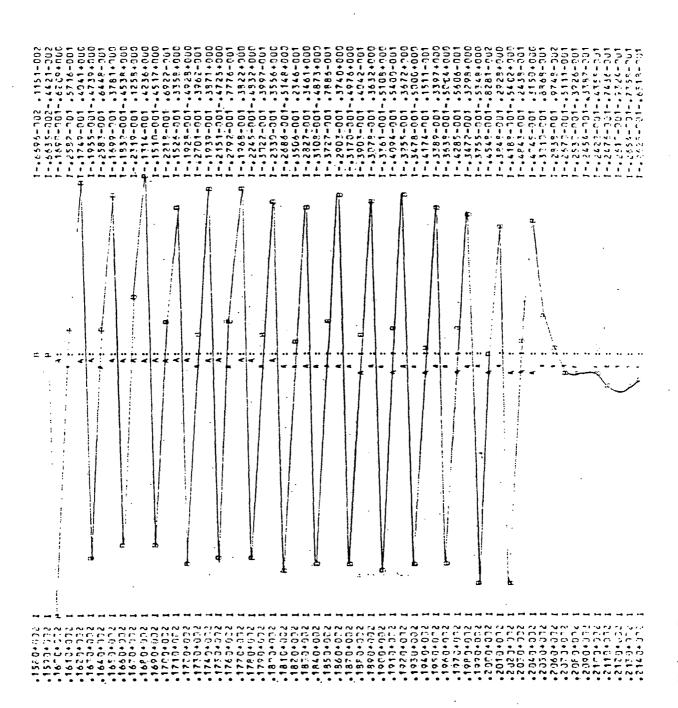
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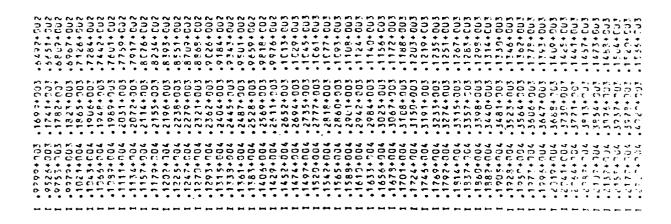
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FIGURE F58

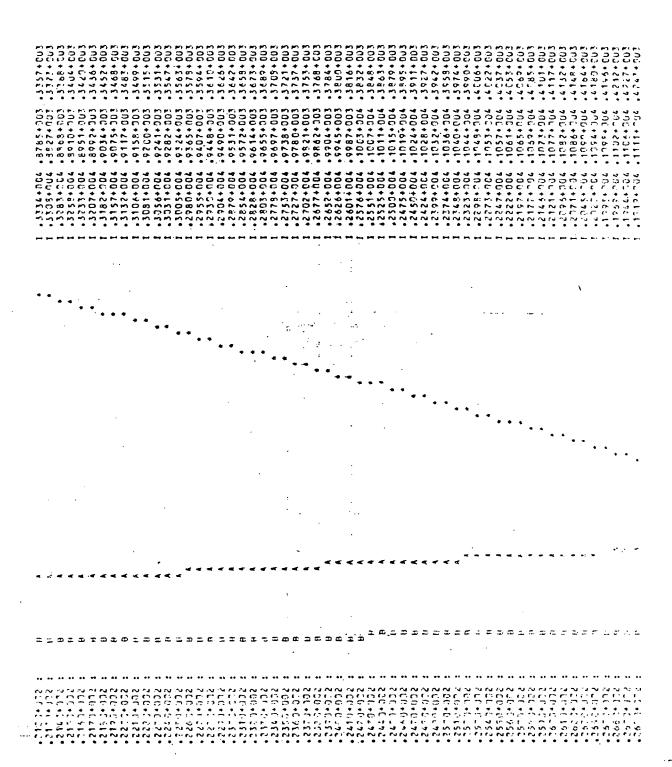
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1.2245-004 4414-003 1552-003
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#### FIGURE F59

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1864-004 1123-014 4275-013

1817-004 1123-014 4207-013

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1616-004 1157-004 4407-003

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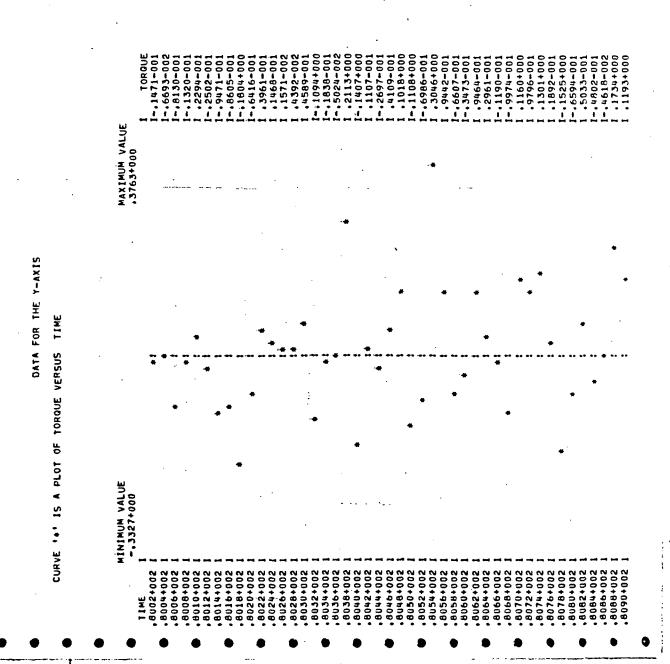
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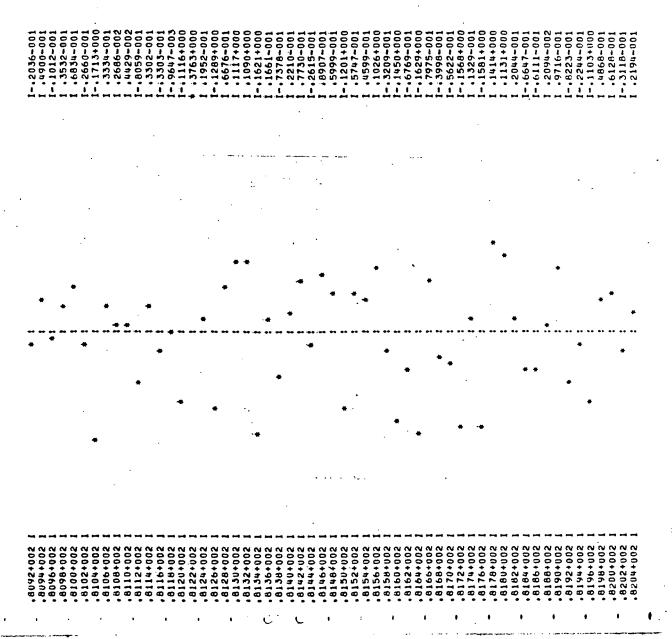
1186-004 11237-004 4607-003

# IX.F.3. Pitch Axis VRCS Disturbance Responses

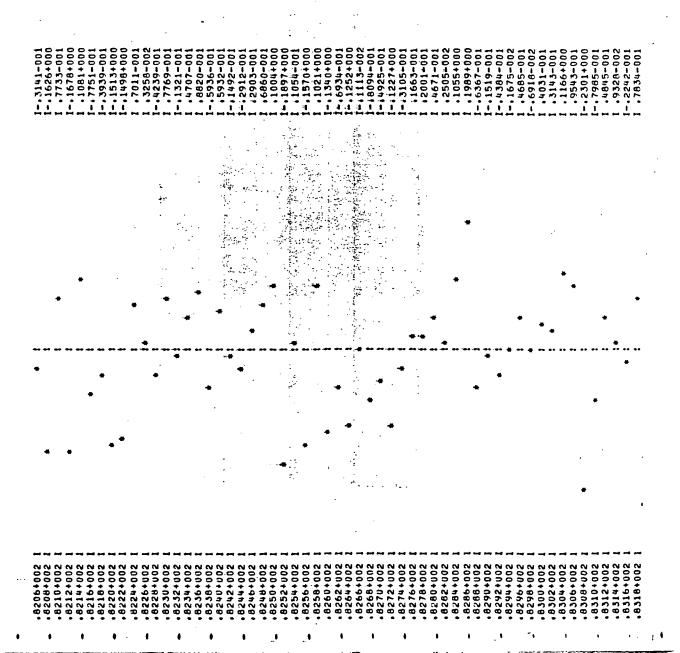
Figures F62 - F100

FIGURE F62

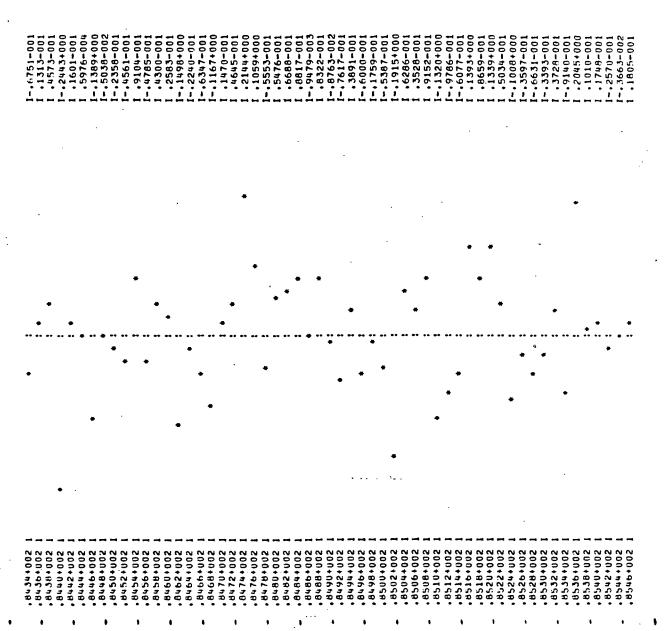




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## FIGURE F70 ·

.8918+002 .8918+002 .8922+002 .8922+002 .8924+002 .8928+002 .8928+002 .8928+002 8936+002 8938+002 8940+002 8986+002 8988+002 8990+002 8992+002 8902+002 8946+002 8910+002 8942+002 8914+002 8944+002 8950+002 8952+002 8954+002 8958+002 8964+002 8966+002 8996+002 8906+002 8908+002

.9094+002 .9096+002 .9098+002 .91002-002 .9104+002 .9106+002 90048906 9090+000 9092+002

9128+002 9130+002 9134+002 9134+002 9138+002 9142+002 9144+002 9144+002 .9152+002 .9154+002 .9156+002 .9158+002 .9162+002 .9164+002 .9166+002 .9192+002 .9194+002 .9196+002 9202+002 9204+002 9204+002 9212+002 9212+002 9214+002 9216+002 9218+002 .9148+002 .9188+002 .9198+002 9184+002 9186+002 9208+002 126+002

9396+002

9442+002

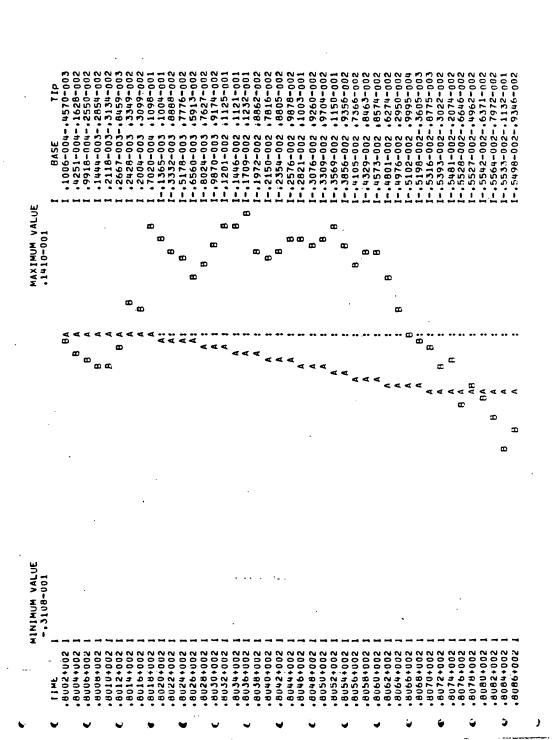
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368+002 370+002

362+002 364+002 366+002

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100 - 100 -

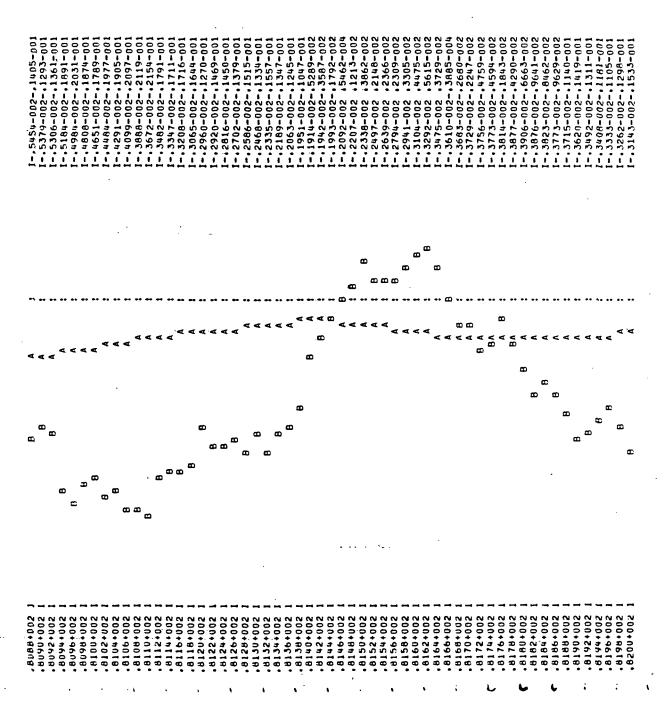


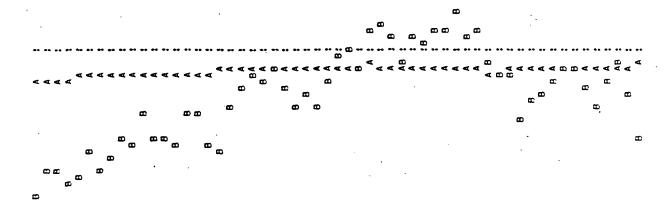
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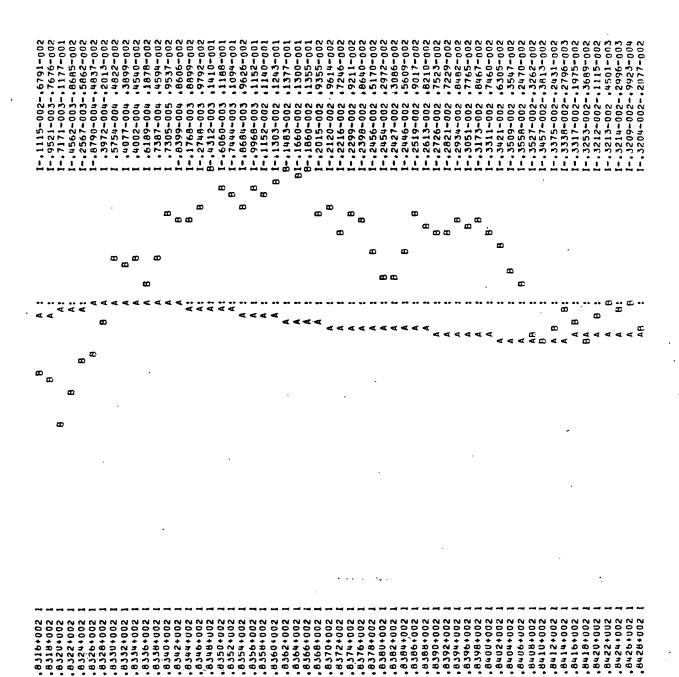
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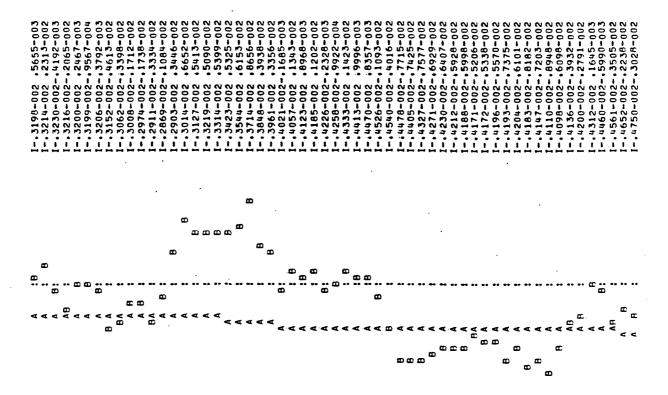
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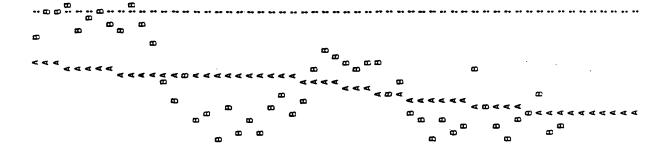


8214+002 8292+002 8306+002 8308+002 8310+002 .8312+002 .8314+002 8256+002 8258+002 8304+005 8222+002 8226+002 8228+002 3230+002 3232+002 8234+002 3236+002 3238+002 8240+002 3242+002 3244+002 246+002 200+057 8252+002 3288+002 3296+002 3298+002 8300+002 8302+002 8212+002 8218+002 248+002 8254+002 264+002 3286+002 566+005 1270+002 274+005 1278+00 1280+002



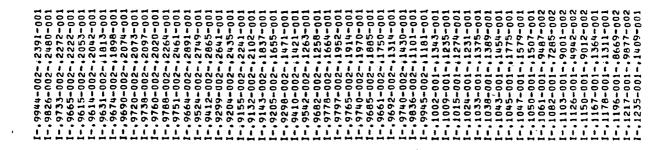


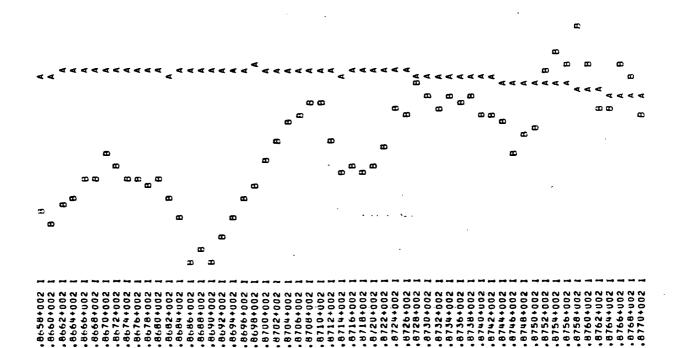
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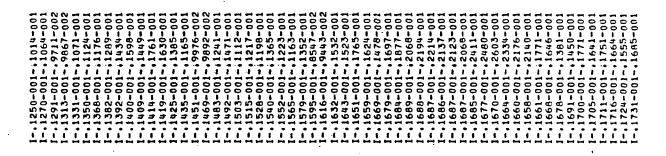


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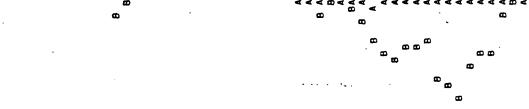
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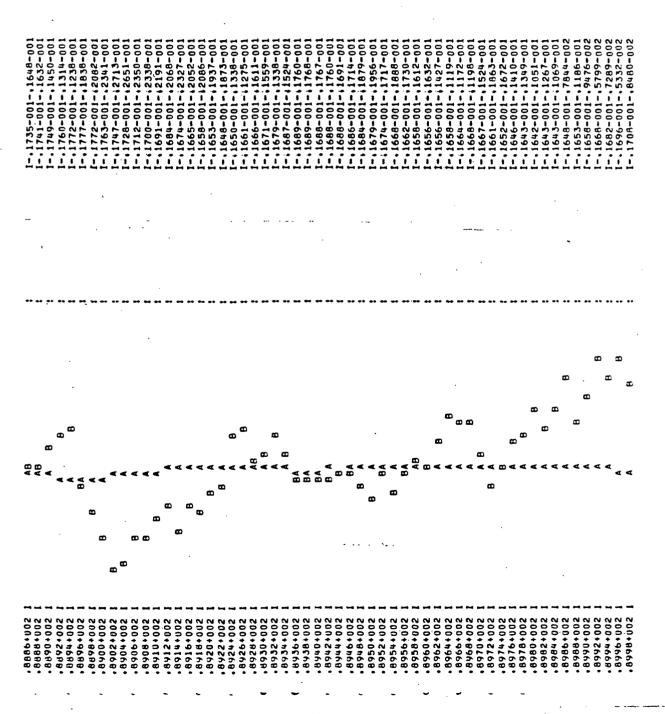




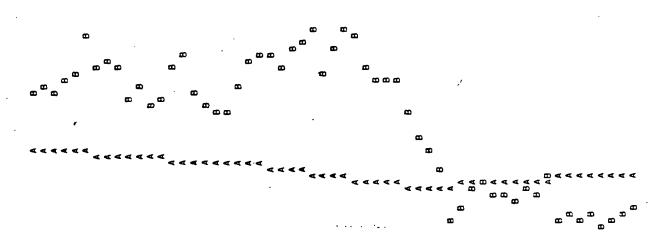


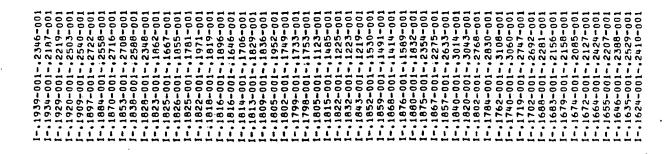


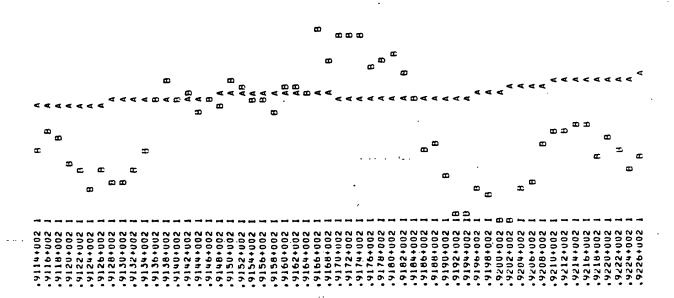




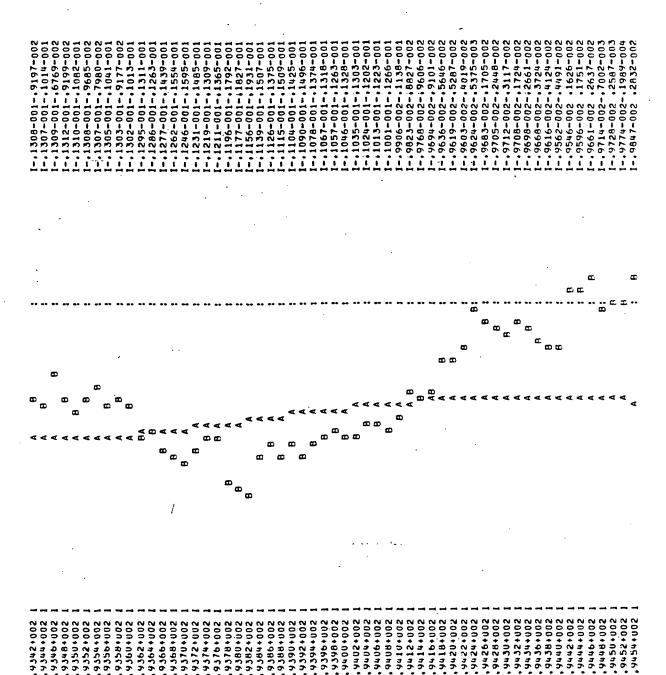




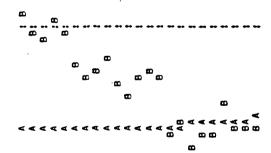




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94.58+002 94.68+002 94.68+002 94.68+002 94.68+002 94.68+002 94.78+002 94.78+002 94.78+002 94.78+002 94.78+002 94.78+002 94.88+002 94.88+002 94.88+002 94.88+002 94.88+002 94.88+002 94.88+002 94.88+002 94.98+002 94.98+002 94.98+002 94.98+002 94.98+002 94.98+002

TIME TIME CURVE \*\*\* IS A PLUT OF THETAX VERSUS OF THETAY VERSUS CURVE 'A' IS A PLOT

CURVE '8' IS A PLOT OF THETAZ VERSUS

000+69460 1893+00 ,3326+004 ,3329+004 43334004 4045+002 3596+002 5394+002 MAXIMUM VALUE MINIMUM VALUE

8022+002 8024+002 8026+002 8028+002 8030+002 8032+002 8034+005 8036+002 8038+002 8040+008 8044+008

8018+002 8020+005 8016+002

.0000+002 .002+002 .0004+002 .0006+002 .0008+002

8012+002

.8060+002 .8062+002 .8064+002

8048+002

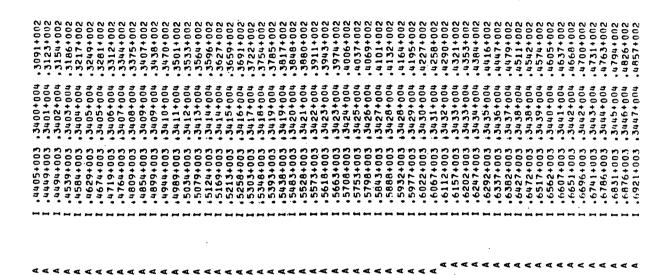
8042+002 8046+002 8054+002 8058+002

8052+002 8056+002 .8070+002 .8072+002

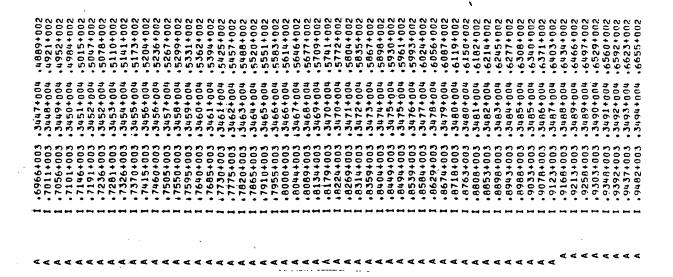
8068+002

.8076+002 .8078+002 .8080+002

| 1984+003 3355+004 1293+002 | 1938+003 | 1938+004 | 1938+002 | 1938+004 | 1938+002 | 1938+004 | 1938+002 | 1938+003 | 1938+004 | 1938+002 | 1938+003 | 1938+004 | 1938+002 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 1938+003 | 19



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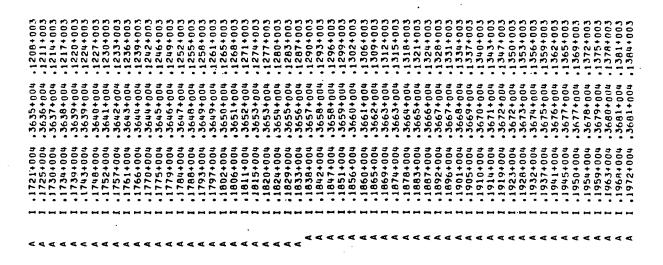
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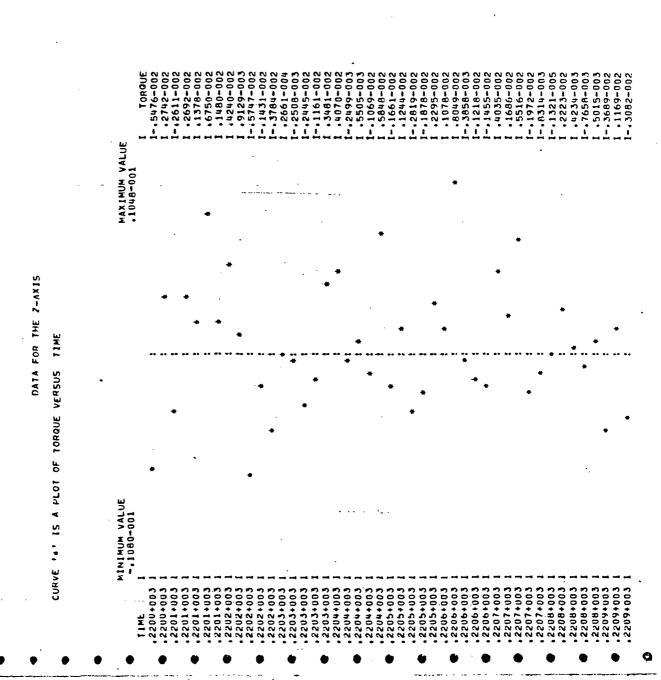
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# IX.F.4. Yaw Axis VRCS Disturbance Responses

Figures F101 - F139



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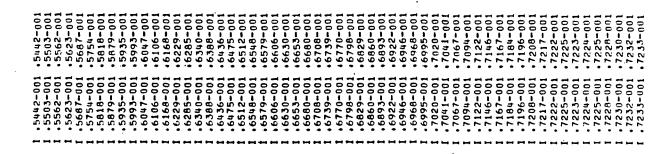
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DATA FOR THE Z-AXIS

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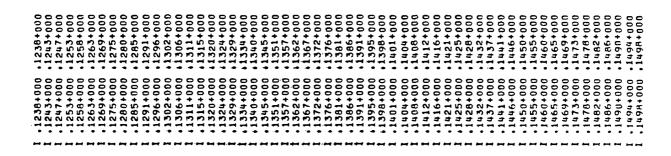
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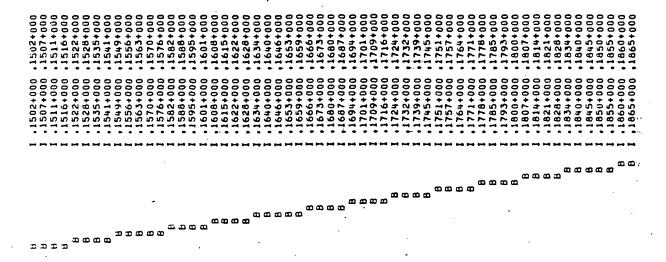
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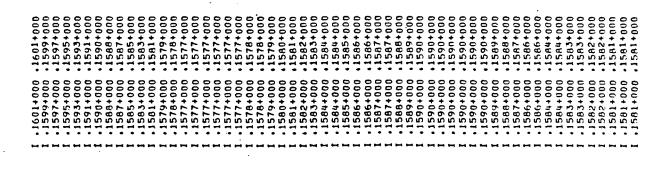


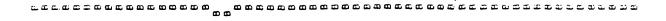
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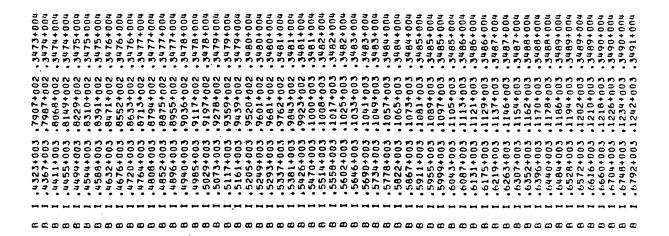
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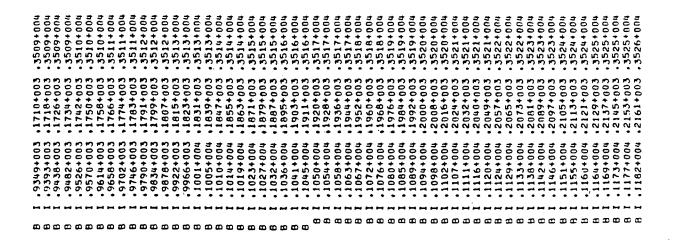
CUHVE ". IS A PLOT OF THETAX VERSUS TIME CURVE 'A' IS A PLOT OF THETAY VERSUS CURVE '8' IS A PLUT OF THETAZ VERSUS

MINIMUM VALUE

| 1,1809+003 ,3308+002 ,3456+004 | 1,1854+003 ,3358+002 ,3456+004 | 1,1854+003 ,3359+002 ,3456+004 | 1,1854+003 ,3478+002 ,3457+004 | 1,1987+003 ,3551+002 ,3457+004 | 1,2029+003 ,3712+002 ,3457+004 | 1,2029+003 ,3712+002 ,3457+004 | 1,2039+003 ,3712+002 ,3458+004 | 1,2039+003 ,3712+002 ,3458+004 | 1,2039+003 ,3712+002 ,3458+004 | 1,2039+003 ,4712+002 ,3458+004 | 1,2039+003 ,4712+002 ,3458+004 | 1,2039+003 ,4712+002 ,3458+004 | 1,2039+003 ,4712+002 ,3469+004 | 1,2039+003 ,4712+002 ,3469+004 | 1,2039+003 ,4712+002 ,3469+004 | 1,2039+003 ,4712+002 ,3469+004 | 1,2039+003 ,4712+002 ,3469+004 | 1,2039+003 ,4712+002 ,3469+004 | 1,2039+003 ,4712+002 ,3469+004 | 1,2039+003 ,5712+002 ,3469+004 | 1,2039+003 ,5712+002 ,3469+004 | 1,2039+003 ,5712+002 ,3469+004 | 1,2039+003 ,5712+002 ,3469+004 | 1,2039+003 ,5712+002 ,3469+004 | 1,2039+003 ,5712+002 ,3469+004 | 1,2039+003 ,5712+002 ,3469+004 | 1,2039+003 ,5712+002 ,3469+004 | 1,2039+003 ,5712+002 ,3469+004 | 1,2039+003 ,5712+002 ,3469+004 | 1,2039+003 ,5712+002 ,3469+004 | 1,2039+003 ,5712+002 ,3469+004 | 1,2039+003 ,5712+002 ,3469+004 | 1,2039+003 ,5712+002 ,3469+004 | 1,2039+003 ,5712+002 ,3469+004 | 1,2039+003 ,5712+002 ,3469+004 | 1,2039+003 ,5712+002 ,3469+004 | 1,2039+003 ,5712+002 ,3469+004 | 1,2039+003 ,5712+002 ,3469+004 | 1,2039+003 ,5712+002 ,3469+004 | 1,2039+003 ,5712+002 ,3469+004 | 1,2039+003 ,5712+002 ,3469+004 | 1,2039+003 ,5712+002 ,3469+004 | 1,2039+003 ,5712+002 ,3469+004 | 1,2039+003 ,5712+002 ,3469+004 | 1,2039+003 ,5712+002 ,3469+004 | 1,2039+003 ,5712+002 ,3469+004 | 1,2039+003 ,5712+002 ,3469+004 | 1,2039+003 ,5712+002 ,3469+004 | 1,2039+003 ,7712+003 ,2469+004 | 1,2039+003 ,7712+003 ,2469+004 | 1,2039+003 ,7712+003 ,2469+004 | 1,2039+003 ,2469+004 | 1,2039+003 ,7712+003 ,2469+004 | 1,2039+003 ,7712+003 ,2469+004 | 1,2039+003 ,7712+003 ,2469+004 | 1,2039+003 ,7712+003 ,2469+004 | 1,2039+003 ,7712+003 ,2469+004 | 1,2039+003 ,2469+004 | 1,2039+003 ,2469+004 | 1,2039+003 ,2469+004 | 1,2039+003 ,2469+004 | 1,2039+003 ,2469+004 | 1,2039+003 ,2469+004 | 1,

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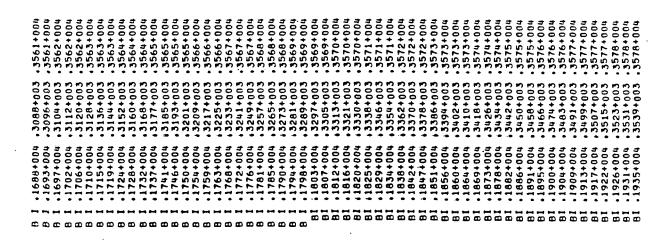




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\$ 000+6622 \$ 000+

ŧ.

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BI .2203+004 ,40030+003 .3597+004
BI .2203+004 ,40030+003 .3597+004
BI .2217+004 ,40030+003 .3597+004
BI .2217+004 ,40030+003 .3599+004
BI .2217+004 ,40070+003 .3599+004
BI .2234+004 ,4078+003 .3599+004
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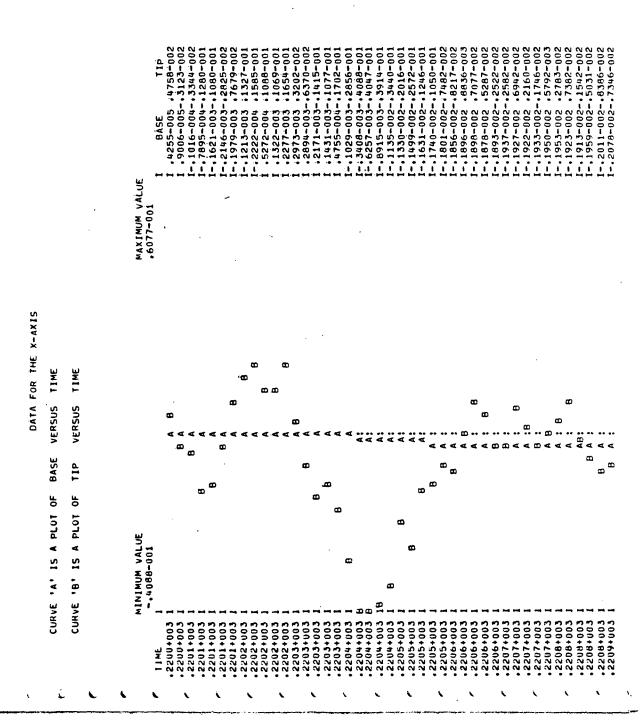
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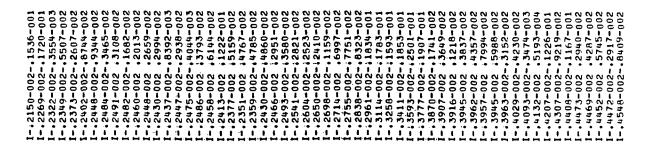
2319+003 2319+003 2319+003

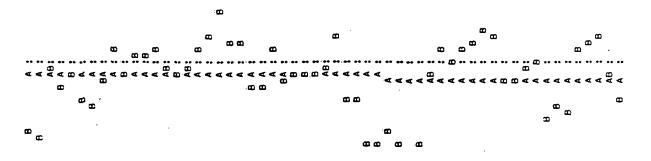
# IX.F.5. Noise Characteristics

Figures F140 - F153



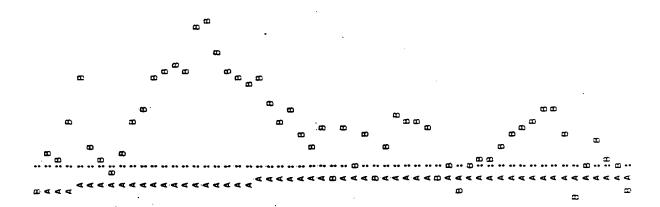
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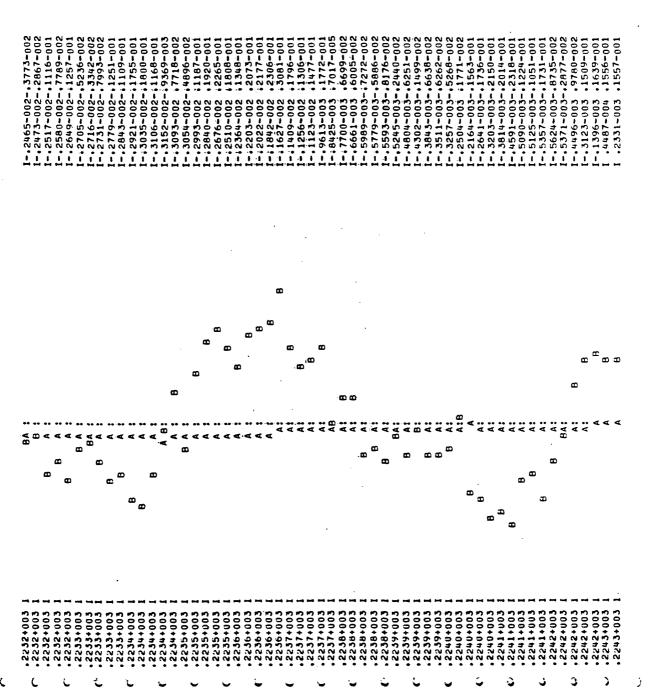


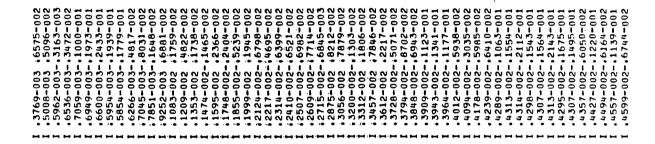
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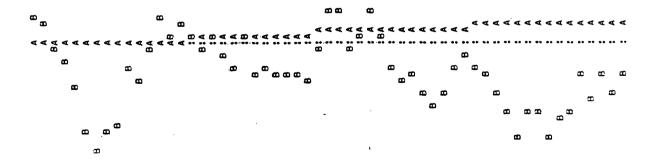
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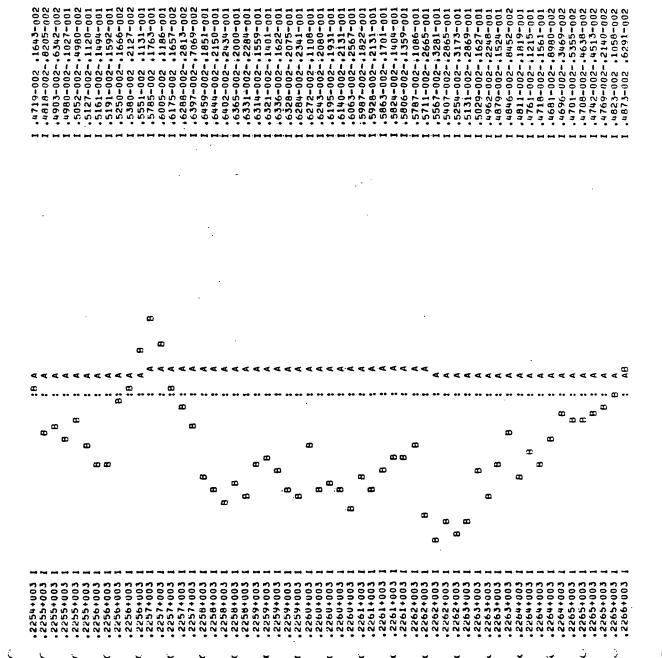


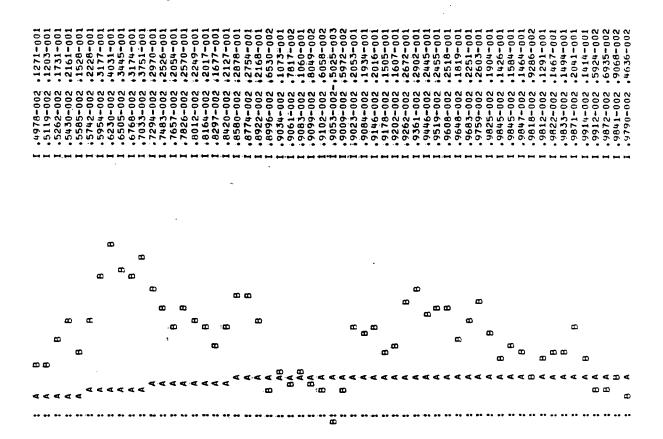
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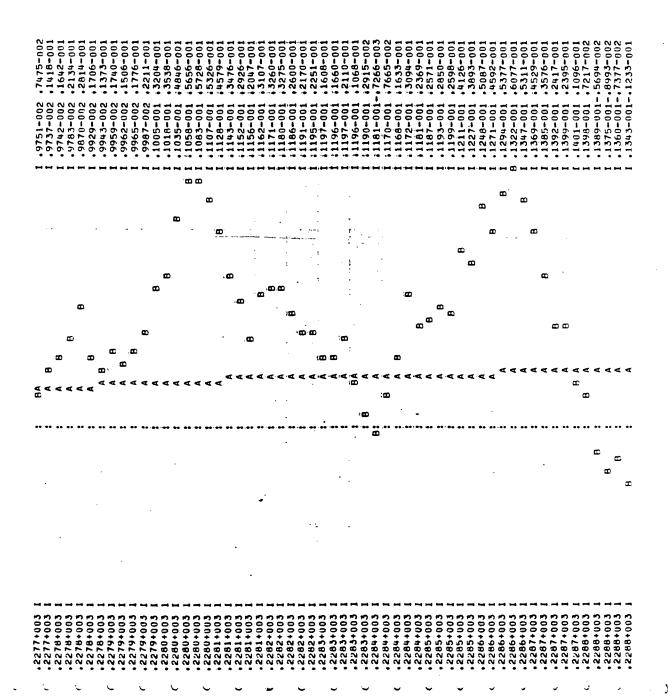


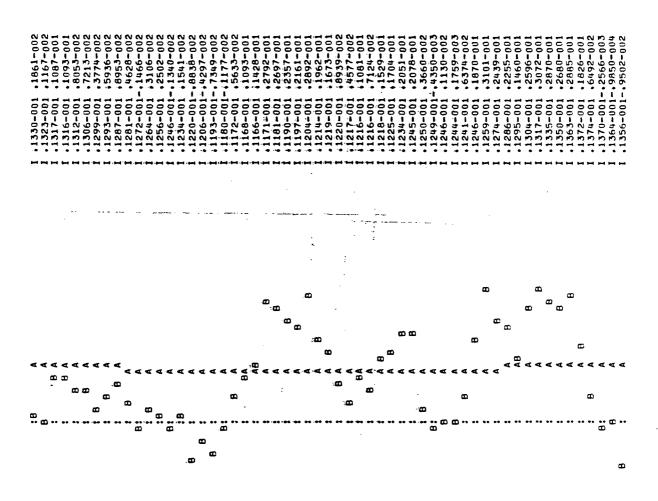


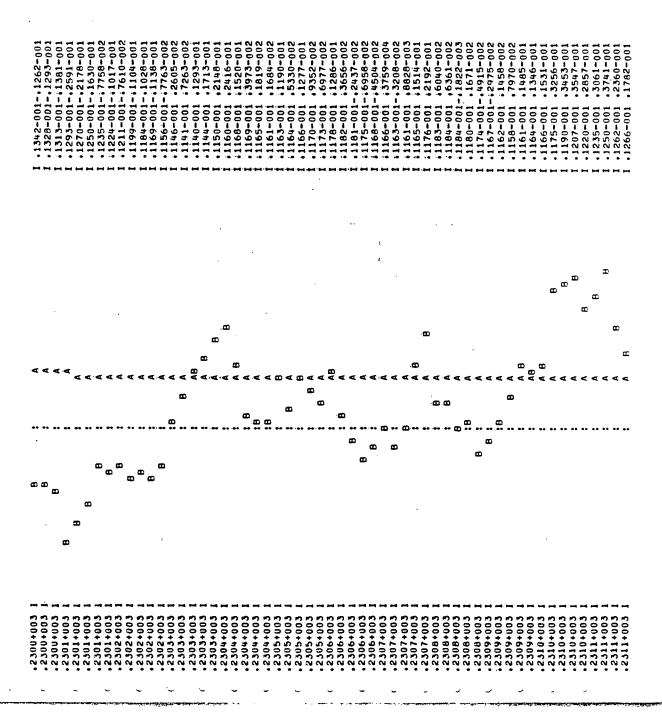




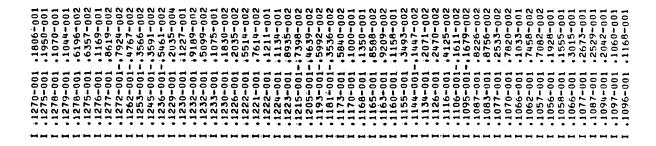
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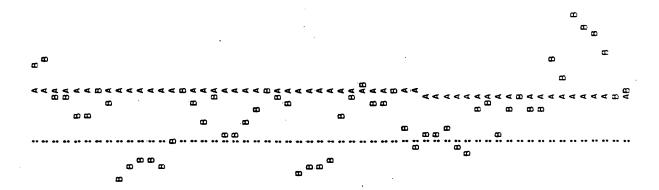






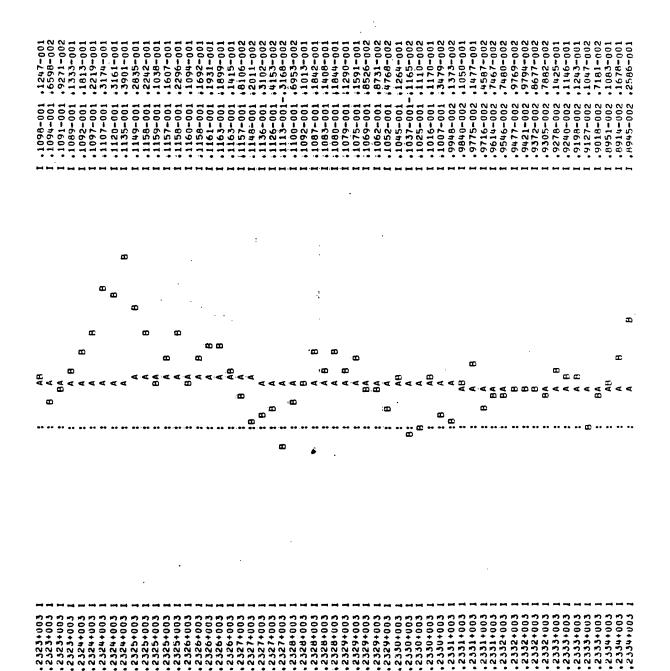
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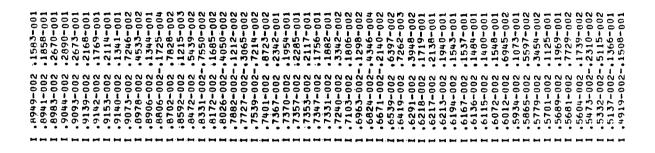


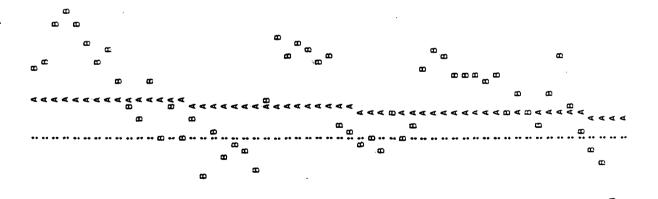


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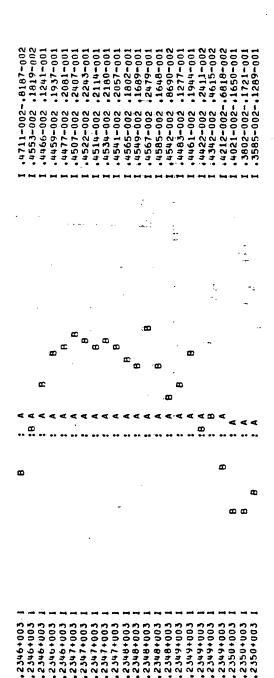
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# IX.G. LOS Sun Sensor Calculations

## Fine LOS Sun Sensor Calculation

- 1. Passband:  $\Delta \lambda = .05 \, \mu m$  8250 A° to 8750 A° Transmittance =  $.5 \times .5 = .25$
- 2. Assumption: sun is a 5770°k Black Body

$$8 \times 10^3 \text{ w/cm}^2/\mu\text{m}$$
 @  $\lambda$  peak

$$1.9 \times 10^3 \text{ w/cm}^2/\mu\text{m/sr} @ 8500 A^\circ$$

- 3.  $\Delta \Theta = 5$  arc min  $\Delta \phi = 15$  arc sec (FIELD STOP)
- 4. Silicon detector

.1sec integration,  $\lambda$  peak = 8500 A°

$$N.E.P. = 10^{-11} w$$

5. S/N = 1000

$$= \frac{1.9 \times 10^{3} \text{ w/cm}^{2}/\mu\text{m/sr} \times .25 \times (.05 \mu\text{m}) \times 10^{-7} \text{ sr} \times A \times (.1)}{10^{-11}\text{w}}$$

Therefore  $A = .042 \text{ cm}^2$ 

Required collecting area.